ST2024C

24K 8-bit Single Chip Microcontroller

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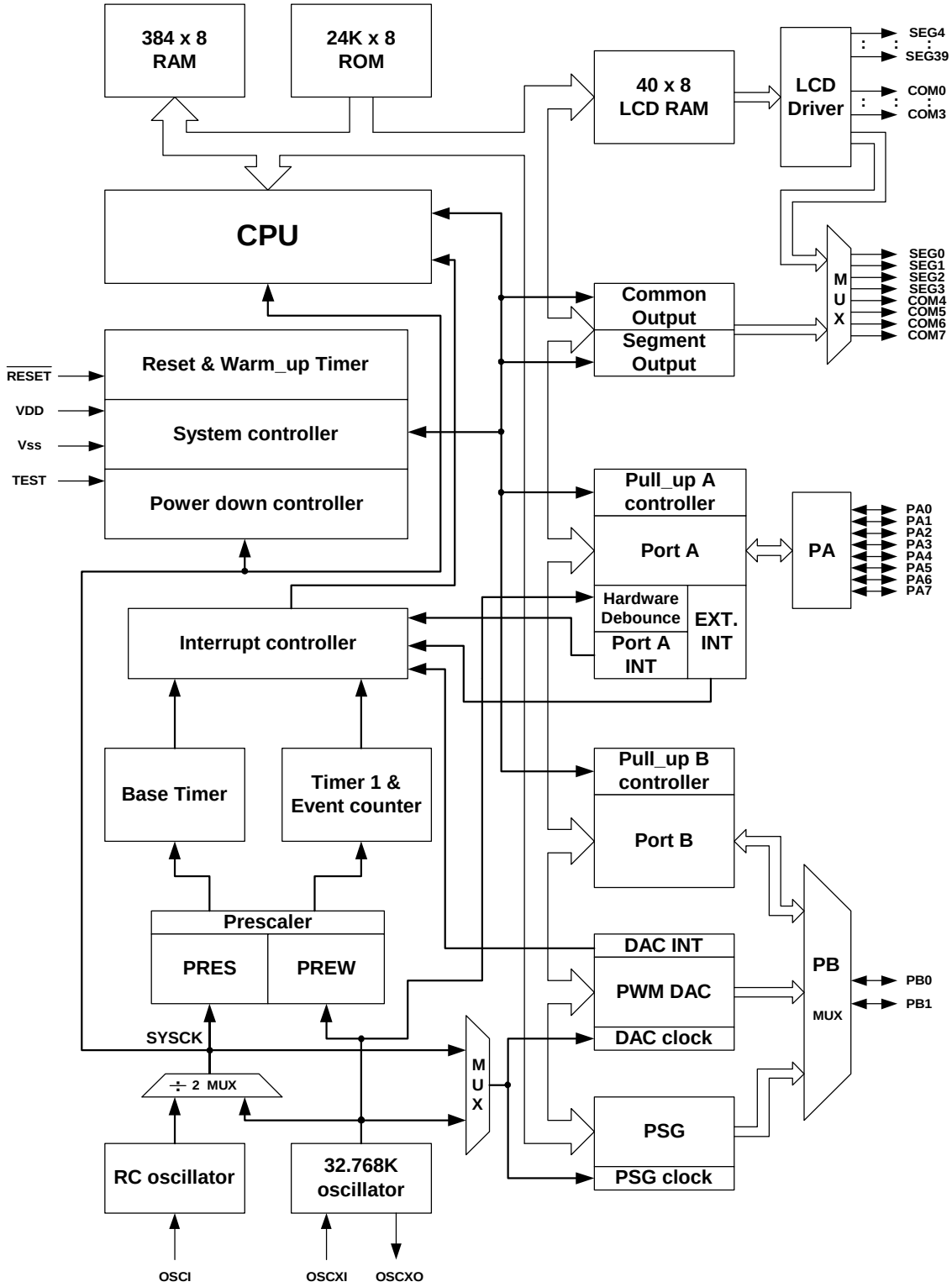
1. FEATURES

- 8-bit static pipeline CPU
- ROM: 24K x 8 bits
- RAM: 384 x 8 bits
- Operation voltage : 2.4V ~ 3.6V
- 10 CMOS Bi-directional bit programmable I/O pins
- 8 Output pins (Shared with LCD common/segment)
- Hardware debounce option for input port
- Bit programmable PULL-UP for input port
- Timer/Counter :
  - One 8-bit timer / 16-bit event counter
  - One 8-bit BASE timer
- Five powerful interrupt sources :
  - External interrupt (edge trigger)
  - TIMER1 interrupt
  - BASE timer interrupt
  - PORTA[7~0] interrupt (transition trigger)
  - DAC reload interrupt
- 128-level deep stack
- Dual clock source :
  - OSCX: Crystal oscillator: 32.768K Hz
  - OSC: RC oscillator 500K ~ 4M Hz
    CPU clock 250K ~ 2M Hz
- Build-in oscillator with warm-up timer
- LCD driver programmable duty :
  - 320 (8x40) dots (1/8 duty, 1/4 bias)
  - 160 (4x40) dots (1/4 duty, 1/3 bias)
  - Internal bias resistor(1/4 bias, 1/3 bias) with 32 level driving strength control.
- Programmable Sound Generator (PSG) includes :
  - Tone generator
  - Sound effect generator
  - 4 level volume control
  - Digital DAC for speech / tone
- Three power down modes :
  - WAI0 mode
  - WAI1 mode
  - STP mode

2. GENERAL DESCRIPTION

ST2024C is a low-cost, high-performance, fully static, 8-bit microcontroller designed with CMOS silicon gate technology. It comes with 8-bit pipeline CPU core, SRAM, timer, LCD driver, I/O port, PSG and mask program ROM. A build-in dual oscillator is specially integrated to enhance chip performance. For business equipment and consumer applications. Such as watch, calculator, and LCD game , ST2024C is definitely a perfect solution for implementation.

3. BLOCK DIAGRAM

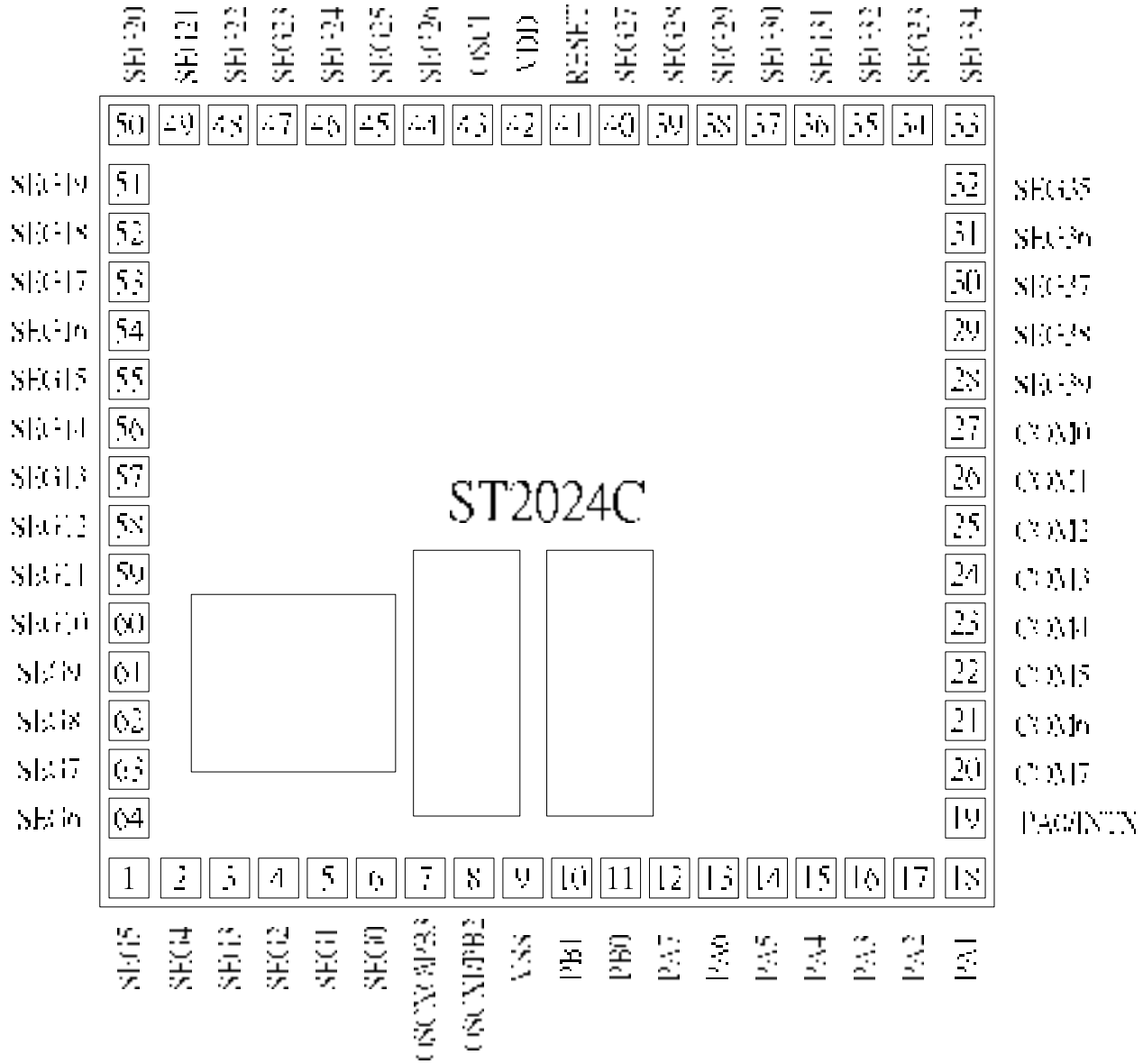


4. PAD DESCRIPTION

Designation	Pad #	Type	Description
SEG 0 - 3	3~6	O O	LCD Segment output Output port
SEG 4 - 31	1,2, 36~40, 46~66	O	LCD Segment output
SEG 32 - 39	28~35	O	LCD Segment output
COM 0 - 3	24~27	O	LCD Common output
COM 4 - 7	20~23	O O	LCD Common output Output port
RESET	41	I	Pad reset input (HIGH Active)
VSS	9	P	Ground Input and chip substrate
PA0/INTX	19	I/O I I I	Port-A bit programmable I/O Edge-trigger Interrupt. Transition-trigger Interrupt Programmable Timer1 clock source
PA 1-7	12~18	I/O I	Port-A bit programmable I/O Transition-trigger Interrupt
PB 0-1	10, 11	I/O O	Port-B bit programmable I/O PSG/DAC Output
V_{DD}	42	P	Power supply
OSCXI/PB2	8	I I	OSC input pin. For 32768Hz crystal Port-B input
OSCXO/PB3	7	O I	OSC output pin. For 32768Hz crystal Port-B input
OSCI	43	I	OSC input pin. toward to external resistor

Legend: I = input, O = output, I/O = input/output, P = power.

5. PAD DIAGRAM:



6. DEVICE INFORMATION：

Chip Size: 2003 x 1820 μm

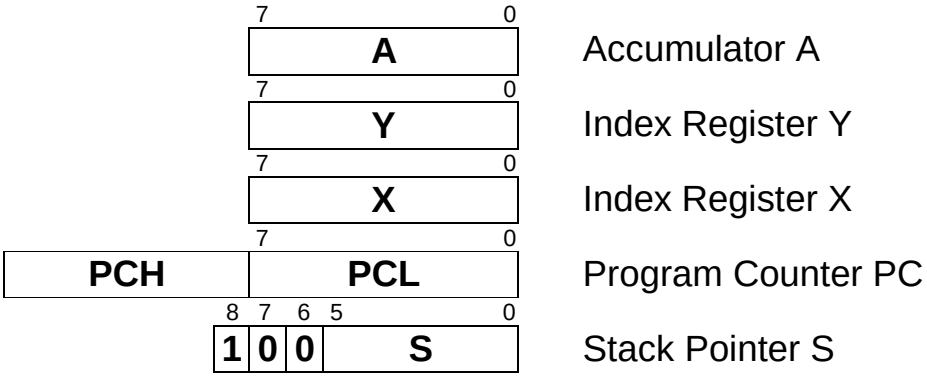
- The chip substrate should be connected with the VSS pin.

Unit: μm

PAD #	NAME	PAD CENTER	
		X	Y
1	SEG5	60	60
2	SEG4	176.600	60
3	SEG3	286.600	60
4	SEG2	396.600	60
5	SEG1	506.600	60
6	SEG0	616.600	60
7	OSCX0/PB3	726.600	60
8	OSCXI/PB2	836.600	60
9	VSS	946.600	60
10	PB1	1056.600	60
11	PB0	1166.600	60
12	PA7	1276.600	60
13	PA6	1386.600	60
14	PA5	1496.600	60
15	PA4	1606.600	60
16	PA3	1716.600	60
17	PA2	1826.600	60
18	PA1	1942.400	60
19	PA0/INTX	1942.4	195.500
20	COM7	1942.4	305.500
21	COM6	1942.4	415.500
22	COM5	1942.4	525.500
23	COM4	1942.4	635.500
24	COM3	1942.4	745.500
25	COM2	1942.4	855.500
26	COM1	1942.4	965.500
27	COM0	1942.4	1075.500
28	SEG39	1942.4	1185.500
29	SEG38	1942.4	1295.500
30	SEG37	1942.4	1405.500
31	SEG36	1942.4	1515.500
32	SEG35	1942.4	1625.500

PAD #	NAME	PAD CENTER	
		X	Y
33	SEG34	1942.4	1759.6
34	SEG33	1823.300	1759.6
35	SEG32	1713.300	1759.6
36	SEG31	1603.300	1759.6
37	SEG30	1493.300	1759.6
38	SEG29	1383.300	1759.6
39	SEG28	1273.300	1759.6
40	SEG27	1163.300	1759.6
41	RESET	1053.300	1759.6
42	VDD	943.300	1759.6
43	OSCI	833.300	1759.6
44	SEG26	723.300	1759.6
45	SEG25	613.300	1759.6
46	SEG24	503.300	1759.6
47	SEG23	393.300	1759.6
48	SEG22	283.300	1759.6
49	SEG21	173.300	1759.6
50	SEG20	60	1759.600
51	SEG19	60	1625.500
52	SEG18	60	1515.500
53	SEG17	60	1405.500
54	SEG16	60	1295.500
55	SEG15	60	1185.500
56	SEG14	60	1075.500
57	SEG13	60	965.500
58	SEG12	60	855.500
59	SEG11	60	745.500
60	SEG10	60	635.500
61	SEG9	60	525.500
62	SEG8	60	415.500
63	SEG7	60	305.500
64	SEG6	60	195.500

7. CPU



CPU REGISTER MODEL

7.1 Accumulator (A)

The accumulator is a general purpose 8-bit register which stores the results of most arithmetic and logic operations. In addition, the accumulator usually contains one of the two data words used in these operations.

7.2 Index Registers (X,Y)

There are two 8-bit Index Registers (X and Y) which may be used to count program steps or to provide and index value to be used in generating an effective address. When executing an instruction which specifies indexed addressing, the CPU fetches the OP code and the base address, and modifies the address by adding the index register to it prior to performing the desired operation. Pre or post-indexing of indirect addresses is possible.

7.3 Stack Pointer (S)

The stack Pointer is an 8-bit register which is used to control the addressing of the variable-length stack. It's range from 100H to 1FFH total for 256 bytes (128-level deep). The stack pointer is automatically incremented and decrement under control of the microprocessor to perform stack manipulations under direction of either the program or interrupts (IRQ). The stack allows simple implementation of nested subroutines and multiple level interrupts. The stack pointer is initialized by the user's software.

7.4 Program Counter (PC)

The 16-bit Program Counter register provides the address which step the microprocessor through sequential program instructions. Each time the microprocessor fetches and instruction from program memory, the lower byte of the program counter (PCL) is placed on the low-order bits of the address bus and the higher byte of the program counter (PCH) is placed on the high-order 8 bits. The counter is incremented each time an instruction or data is fetched from program memory.

7.5 Status Register (P)

The 8-bit Processor Status Register contains seven status flags. Some of the flags are controlled by the program, others may be controlled both by the program and the CPU. The instruction set contains a member of conditional branch instructions which are designed to allow testing of these flags.

TABLE 7-1: STATUS REGISTER (P)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
N	V	1	B	D	I	Z	C

Bit 7: **N :** Signed flag by arithmetic
1 = Negative
0 = Positive

Bit 6: **V :** Overflow of signed Arithmetic flag
1 = Negative
0 = Positive

Bit 4: **B : BRK** interrupt flag *****
1 = **BRK** interrupt occur
0 = Non **BRK** interrupt occur

Bit 3: **D :** Decimal mode flag
1 = Decimal mode
0 = Binary mode

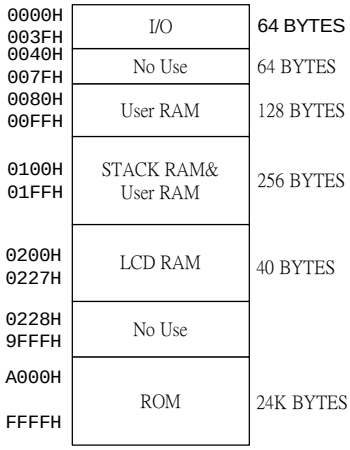
Bit 2: **I :** Interrupt disable flag
1 = Interrupt disable
0 = Interrupt enable

Bit 1: **Z :** Zero flag
1 = Zero
0 = Non zero

Bit 0: **C :** Carry flag
1 = Carry
0 = Non carry

*** Don't use "BRK" instruction.**

8. MEMORY CONFIGURATION



8.1 ROM ($A000~$FFFF)

The ST2024C has 24K bytes ROM used for program, data and vector address.

Vector address mapping :

$FFFE	Reserved.
$FFFC	RESET vector.
$FFFA	Reserved.
$FFF8	INTX (PA0) edge interrupter.
$FFF6	Reload DAC data interrupter.
$FFF4	Reserved.
$FFF2	Timer1 interrupter.
$FFF0	PORTA transition interrupter.
$FFEE	Base Timer interrupter.

8.2 RAM

The RAM mapping includes Control Registers, Data RAM, Stack RAM and LCD RAM.

TABLE 8-2: CONTROL REGISTERS ($0000~$003E)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$000	**PA**	R/W	PA[7]	PA[6]	PA[5]	PA[4]	PA[3]	PA[2]	PA[1]	PA[0]	1111 1111
$001	**PB**	R/W	-	-	-	-	PB[3]	PB[2]	PB[1]	PB[0]	- - - - - -11
$008	**PCA**	R/W	PCA[7]	PCA[6]	PCA[5]	PCA[4]	PCA[3]	PCA[2]	PCA[1]	PCA[0]	0000 0000
$009	**PCB**	R/W	-	-	-	-	-	-	PCB[1]	PCB[0]	- - - - - -00
$00F	**PMCR**	R/W	PULL	PDBN	INTEG	-	-	-	PSGO	PSGOB	100 - - -00
$010	**PSG0L**	R/W	PSG0[7]	PSG0[6]	PSG0[5]	PSG0[4]	PSG0[3]	PSG0[2]	PSG0[1]	PSG0[0]	0000 0000
$011	**PSG0H**	R/W	-	-	-	-	PSG0[11]	PSG0[10]	PSG0[9]	PSG0[8]	- - - - 0000
$012	**PSG1L**	R/W	PSG1[7]	PSG1[6]	PSG1[5]	PSG1[4]	PSG1[3]	PSG1[2]	PSG1[1]	PSG1[0]	0000 0000
$013	**PSG1H**	R/W	-	-	-	-	PSG1[11]	PSG1[10]	PSG1[9]	PSG1[8]	- - - - 0000
$014	**DAC**	R/W	DAC[7]	DAC[6]	DAC[5]	DAC[4]	DAC[3]	DAC[2]	DAC[1]	DAC[0]	0000 0000
$016	**PSGC**	R/W	-	PCK[2]	PCK[1]	PCK[0]	PRBS	C1EN	C0EN	DACE=0	-000 0000
		R/W	-	PCK[2]	PCK[1]	PCK[0]	DMD[1]	DMD[0]	INH	DACE=1	-000 0000
$017	**VOL**	R/W	VOL1[3]	VOL1[2]	VOL1[1]	VOL1[0]	VOL0[3]	VOL0[2]	VOL0[1]	VOL0[0]	0000 0000
$020	**LCK**	R/W	-	-	DRV[2]	DRV[1]	DRV[0]	LCK[2]	LCK[1]	LCK[0]	- -00 0100
$021	**BTM**	R/W	-	-	-	-	BTM[3]	BTM[2]	BTM[1]	BTM[0]	- - - - 0000
$023	**PRS**	R	PRS[7]	PRS[6]	PRS[5]	PRS[4]	PRS[3]	PRS[2]	PRS[1]	PRS[0]	0000 0000
		W	SRES	SENA	SENT	-	-	-	-	-	000 - - - - -
$026	**T1M**	R/W	-	-	-	T1M[4]	T1M[3]	T1M[2]	T1M[1]	T1M[0]	- - -0 0000
$027	**T1C**	R/W	T1C[7]	T1C[6]	T1C[5]	T1C[4]	T1C[3]	T1C[2]	T1C[1]	T1C[0]	0000 0000
$030	**SYS**	R/W	XSEL	OSTP	XSTP	TEST	WSKP	WAIT	-	-	0000 00- -
$038	**XLCD**	R/W	-	-	-	-	-	-	HEAV	-	- - - - - -0-
$03A	**LCTL**	W	LPWR	BLANK	COMO	LENH	SEGO	CTR[1]	CTR[0]	DUTY	0000 0000
$03B	**SCAN**	R/W	SCAN[7]	SCAN[6]	SCAN[5]	SCAN[4]	-	-	-	-	0000 - - - -
$03C	**IREQ**	R/W	-	-	IRBT	IRPT	IRT1	-	IRDAC	IRX	- - 11 1-11
$03E	**IENA**	R/W	-	-	IEBT	IEPT	IET1	-	IEDAC	IEX	- - 00 0-00

Note: 1. Some addresses of I/O area, $2~$7, $A~$E, $15, $18~$1F, $22, $24~$25, $28~$2F, $31~$37, $39, $3D,$3F, are no used.
2. User should never use undefined addresses and bits.
3. Do not use Bit instructions for write-only registers, such as RMBx, SMBx ….
4. E.V.B 's RAM Power On Initial Value are Same as Real Chip.

8.2.2 DATA RAM ($0080~$00FF)

DATA RAM are organized in 256 bytes.

8.2.3 STACK RAM ($0100~$01FF)

STACK RAM are organized in 256 bytes. It provides for a maximum of 128-level subroutine stacks And can be used as data memory.

8.2.4 LCD RAM ($0200~$0227)

Resident LCD-RAM, accessible through write and read instructions, are organized in 40 bytes for 40x8 LCD display. Note that this area can also be used as data memory.

9. INTERRUPTS

TABLE 9-3: PREDEFINED VECTORS FOR INTERRUPT

Name	Signal	Vector address	Priority	Comment
-	-	$FFFF,$FFFE	-	Reserved
RESET	External	$FFFD,$FFFC	1	RESET vector
-	-	$FFFB,$FFFA	-	Reserved
INTX	External	$FFF9,$FFF8	2	PA0 edge interrupt
DAC	Internal	$FFF7,$FFF6	3	Reload DAC data interrupt
-	-	$FFF5,$FFF4	-	Reserved
T1	INT/EXT	$FFF3,$FFF2	4	Timer1 interrupt
PT	External	$FFF1,$FFF0	5	Port-A transition interrupt
BT	Internal	$FFEF,$FFEE	6	Base Timer interrupt

9.2 Interrupt description

RESET
A positive transition of RESET pin will then cause an initialization sequence to begin. After the system has been operating, a high on this line of a least two clock cycles will cease ST2024C activity. When a positive edge is detected, there is an initialization sequence lasting six clock cycles. Then the interrupt mask flag is set, the decimal mode is cleared and the program counter will loaded with the restart vector from locations $FFFC (low byte) and $FFFD (high byte). This is the start location for program control. This input should be low in normal operation.

INTX interrupt
The IRX (INTX interrupt request) flag will be set while INTX edge signal occurs. The INTX interrupt will be active once IEX (INTX interrupt enable) is set, and interrupt mask flag is cleared. Hardware will push 'PC', 'P' Register to stack and set interrupt mask flag (I). Program counter will be loaded with the INTX vector from locations $FFF8 and $FFF9.

DAC interrupt
The IRDAC (DAC interrupt request) flag will be set while reload signal of DAC occurs. Then the DAC interrupt will be executed when IEDAC (DAC interrupt enable) is set, and interrupt mask flag is cleared. Hardware will push 'PC', 'P' Register to stack and set interrupt mask flag (I). Program counter will be loaded with the DAC vector from locations $FFF6 and $FFF7.

T1 interrupt
The IRT1 (TIMER1 interrupt request) flag will be set while T1 overflows. With IET1 (TIMER1 interrupt enable) being set, the T1 interrupt will executed, and interrupt mask flag will be cleared. Hardware will push 'PC', 'P' Register to stack and set interrupt mask flag (I). Program counter will be loaded with the T1 vector from locations $FFF2 and $FFF3.

PT interrupt
The IRPT (Port-A interrupt request) flag will be set while Port-A transition signal occurs. With IEPT (PT interrupt enable)being set, the PT interrupt will be execute, and interrupt mask flag will be cleared. Hardware will push 'PC', 'P' Register to stack and set interrupt mask flag (I). program counter will be loaded with the PT vector from locations $FFF0 and $FFF1.

BT interrupt
The IRBT (Base timer interrupt request) flag will be set when Base Timer overflows. The BT interrupt will be executed once the IEBT (BT interrupt enable) is set and the interrupt mask flag is cleared. Hardware will push 'PC', 'P' Register to stack and set interrupt mask flag (I). Program counter will be loaded with the BT vector from locations $FFEE and $FFEF.

9.3 Interrupt request clear

Interrupt request flag can be cleared by two methods. One is to write “0” to IENA, the other is to initiate the interrupt service routine when interrupt occurs. Hardware will automatically clear the Interrupt flag.

TABLE 9-4: INTERRUPT REQUEST REGISTER (IREQ)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$03C	**IREQ**	R/W	-	-	IRBT	IRPT	IRT1	-	IRDAC	IRX	- - 11 1-11

Bit 5: **IRBT:** Base Timer Interrupt Request bit
1 = Time base interrupt occurs
0 = Time base interrupt doesn’t occur

Bit 4: **IRPT:** Port-A Interrupt Request bit
1 = Port-A transition interrupt occurs
0 = Port-A transition interrupt doesn’t occur

Bit 3: **IRT1:** Timer1 Interrupt Request bit
1 = Timer1 overflow interrupt occurs
0 = Timer1 overflow interrupt doesn’t occur

Bit 1: **IRDAC:** DAC reload Interrupt Request bit
1 = DAC time out interrupt occurs
0 = DAC time out interrupt doesn’t occur

Bit 0: **IRX:** INTX Interrupt Request bit
1 = INTX edge interrupt occurs
0 = INTX edge interrupt doesn’t occur

TABLE 9-5: INTERRUPT ENABLE REGISTER (IENA)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$03E	**IENA**	R/W	-	-	IEBT	IEPT	IET1	-	IEDAC	IEX	- - 00 0-00

Bit 5: **IEBT:** Base Timer Interrupt Enable bit
1 = Time base interrupt enable
0 = Time base interrupt disable

Bit 4: **IEPT:** Port-A Interrupt Enable bit
1 = Port-A transition interrupt enable
0 = Port-A transition interrupt disable

Bit 3: **IET1:** Timer1 Interrupt Enable bit
1 = Timer1 overflow interrupt enable
0 = Timer1 overflow interrupt disable

Bit 1: **IEDAC:** DAC reload Interrupt Enable bit
1 = DAC time out interrupt enable
0 = DAC time out interrupt disable

Bit 0: **IEX:** INTX Interrupt Enable bit
1 = INTX edge interrupt enable
0 = INTX edge interrupt disable

10. I/O PORTS

ST2024C has four I/O ports, PORT-A, PORT-B, SEGMENT-PORT and COMMON-PORT. In total, ST2024C provides for a maximum of 18 I/O pins with both SEGMENT-PORT and COMMON-PORT being programmed as output ports. For detail pin assignment, please refer to Table 9-6 :

NOTE: all of unused input pins should be pulled up to minimize standby current

TABLE 10-6: I/O DESCRIPTION

PORT NAME	PAD NAME	PAD NUMBER	PIN TYPE	FEATURE
PORTA	PA0/INTX	18	I/O	Programmable input/output pin
	PA1	17	I/O	
	PA2	16	I/O	
	PA3	15	I/O	
	PA4	14	I/O	
	PA5	13	I/O	
	PA6	12	I/O	
	PA7	11	I/O	
PORTB	PB0	10	I/O	Programmable input/output pin
	PB1	9	I/O	
	PB2	43	I	Input pin(Mask Option)
	PB3	44	I	
SEGMENT PORT	SEG0	6	O	These 4 segment pins can be programmed as output ports.
	SEG1	5	O	
	SEG2	4	O	
	SEG3	3	O	
COMMON PORT	COM4	22	O	These 4 common pins can be programmed as output ports.
	COM5	21	O	
	COM6	20	O	
	COM7	19	O	

10.2 PORT-A

Port- A is a bit-programmable bi-direction I/O port, which is controlled by PCA register. It provides user with bit programmable pull-up MOS, interrupt debounce and interrupt edge selection(PA0 only).

TABLE 10-7: SUMMARY FOR PORT-A REGISTERS

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$000	**PA**	R/W	PA[7]	PA[6]	PA[5]	PA[4]	PA[3]	PA[2]	PA[1]	PA[0]	1111 1111
$008	**PCA**	R/W	PCA[7]	PCA[6]	PCA[5]	PCA[4]	PCA[3]	PCA[2]	PCA[1]	PCA[0]	0000 0000
$00F	**PMCR**	R/W	PULL	PDBN	INTEG	-	-	-	PSG0	PSGB	100 - - -00
$03C	**IREQ**	R/W	-	-	IRBT	IRPT	IRT1	-	IRDAC	IRX	- - 11 1-11
$03E	**IENA**	R/W	-	-	IEBT	IEPT	IET1	-	IEDAC	IEX	- - 00 0-00

10.2.2 PORT-A I/O control

Direction of Port-A is controlled by PCA. Every bit of PCA[7~0] is mapped to the I/O direction of PA[7~0] correspondingly, with “1” for output mode, and “0” for input mode.

TABLE 10-8: PORT-A CONTROL REGISTER (PCA)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$008	**PCA**	R/W	PCA[7]	PCA[6]	PCA[5]	PCA[4]	PCA[3]	PCA[2]	PCA[1]	PCA[0]	0000 0000

Bit 7~0: **PCA[7~0] :** Port-A directional bits
1 = Output mode
0 = Input mode

10.2.3 PORT-A PULL-UP OPTION

PORT-A contains pull-up MOS transistors controlled by software. When an I/O is used as an input. The ON/OFF of the pull-up MOS transistor will be controlled by port data register (PA) and the pull-up MOS will be enabled with "1" for data bit and disable with "0" for data bit. The PULL control bit of PMCR controls the ON/OFF of all the pull-up MOS simultaneously. Please refer to the Figure 9-1.

FIGURE 10-1: Port-A Configuration Function Block Diagram

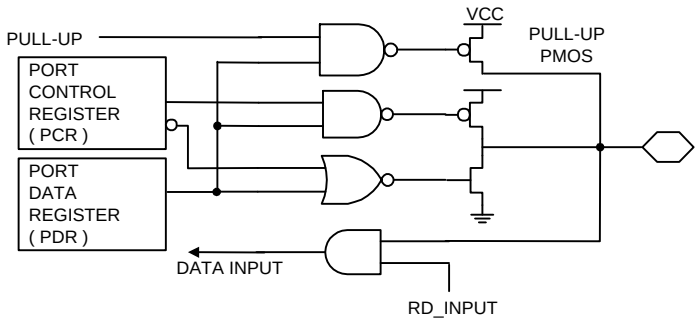


TABLE 10-9: PORT CONDITION CONTROL REGISTER (PMCR)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$00F	**PMCR**	R/W	PULL	PDBN	INTEG	-	-	-	PSG0	PSGB	100 - - -00

Bit 7: **PULL :** Enable all pull-up function bit
1 = Enable pull-up function
0 = Disable pull-up function

Bit 6: **PDBN :** Enable Port-A interrupt debounce bit
1 = Debounce for Port-A interrupt
0 = No debounce for Port-A interrupt

Bit 5: **INTEG :** INTX interrupt edge select bit
1 = Rising edge
0 = Falling edge

10.2.4 Port-A interrupt

Port-A, a programmable I/O, can be used as a port interrupt when it is in the input mode. Any edge transition of the Port-A input pin will generate an interrupt request. The last state of Port-A must be kept before I/O transition and this can be accomplished by reading Port-A.

When programmer enables INTX and PT interrupts, PA0 trigger occur. INTX and PT interrupts will therefore happen sequentially. Please refer to the Figure 9-2.

Operating Port-A interrupt step by step :

1. Set input mode.
2. Read Port-A.
3. Clear interrupt request flag (IRPT).
4. Set interrupt enable flag (IEPT).
5. Clear CPU interrupt disable flag (I).
6. Read Port-A before 'RTI' instruction in INT-Subroutine.

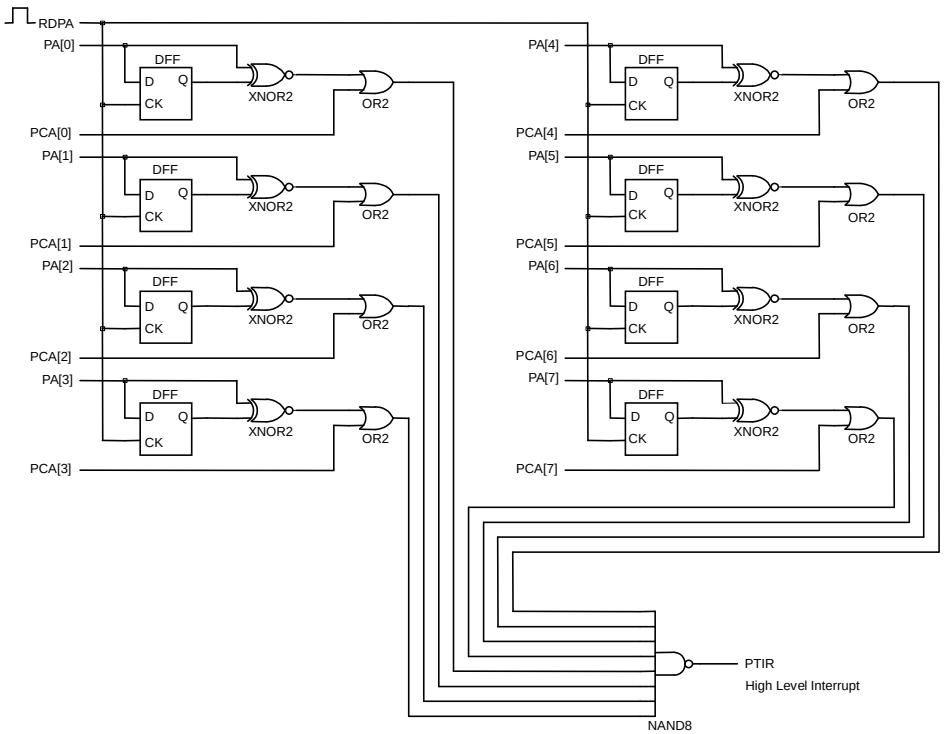
Example :

```
.
.
.
STZ     PCA         ;Set input mode.
LDA     #$FF
STA     PA          ;PA be PULL-UP.
LDA     PA          ;Keep last state.
RMB4    <IREQ       ;Clear IRQ flag.
SMB4    <IENA       ;Enable INT.
CLI
.
.
```

INT-SUBROUTINE

```
.
.
LDA     PA          ;Keep last state.
RTI
```

FIGURE 10-2: Port Interrupt Logic Diagram



10.2.4.2 Port-A interrupt debounce

ST2024C has hardware debounce option for Port-A interrupt. The debounce will be enabled with "1" and disable with "0" for PDBN. The debounce will active when Port-A transition occurs, PDBN enable and **OSCX enable**.

The debounce time is **OSCX x 512 cycles(about 16 ms).** Refer to the TABLE 9-10.

TABLE 10-10: PORT CONDITION CONTROL REGISTER (PMCR)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$00F	**PMCR**	R/W	PULL	PDBN	INTEG	-	-	-	PSG0	PSGB	100 - - -00

Bit 6: **PDBN :** Enable Port-A interrupt debounce bit
1 = Debounce for Port-A interrupt
0 = No debounce for Port-A interrupt

10.2.5 PA0/INTX

PA0 can be used as an external interrupt input(INTX). Falling or Rising edge is controlled by INTEG(PMCR[5]) and the external interrupt is set up with “0” for falling edge and “1” for rising edge. Please refer to the Figure 9-3.

When programmer enables INTX and PT interrupts, PA0 trigger will occur. Both INTX and PT interrupts will happen sequentially. Pelase refer to the operating steps.

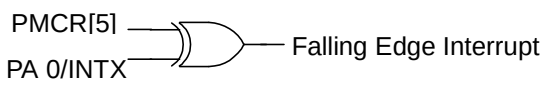
Operating INTX interrupt step by step :

1. Set PA0 pin into input mode. (PCA[0])
2. Select edge level. (INTEG)
3. Clear INTX interrupt request flag. (IRX)
4. Set INTX interrupt enable bits. (IEX)
5. Clear CPU interrupt mask flag (I).

Example :

```
.
.
.
RMB0    <PCA     ;Set input mode.
SMB5    <PMCR    ;Rising edge.
RMB0    <IREQ    ;Clear IRQ flag.
SMB0    <IENA    ;Enable INTX interrupt.
CLI
.
.
.
```

FIGURE 10-3: INTX Logic Diagram



10.3 PORT-B

Port -B is a bit programmable bi-direction I/O port, which is controlled by PCB register. It also provides user with bit-programmable pull-up MOS and sound output port separately.

TABLE 10-11: SUMMARY FOR PORT-B REGISTERS

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$001	**PB**	R/W	-	-	-	-	PB[3]*	PB[2]*	PB[1]	PB[0]	- - - - - -11
$009	**PCB**	R/W	-	-	-	-	-	-	PCB[1]	PCB[0]	- - - - - -00
$00F	**PMCR**	R/W	PULL	PDBN	INTEG	-	-	-	PSG0	PSGB	100 - - -00

Note:because PB2,PB3 is input pin,so PB[2],PB[3] only read status.

10.3.2 PORT-B I/O control

Direction of Port-B is controlled by PCB. Every bit of PCB[1~0] is mapped into the I/O direction of PB[1~0] correspondingly, with “1” for output mode, and “0” for input mode.

TABLE 10-12: PORT-B CONTROL REGISTER (PCB)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$009	**PCB**	R/W	-	-	-	-	-	-	PCB[1]	PCB[0]	- - - - - -00

Bit 1~0: **PCB[1~0] :** Port-B directional bits
1 = Output mode
0 = Input mode

10.3.3 PORT-B PULL-UP OPTION

This port contains pull-up MOS transistors which is controlled by software and can be enabled or disabled with "1" or with "0" accordingly in data bit of the port data register (PB) when an I/O is used as an input. The PULL control bit of PMCR also controls the ON/OFF of all pull-up MOS simultaneously. Please refer to the Figure 9-4.

FIGURE 10-4: Port-B Configuration Function Block Diagram

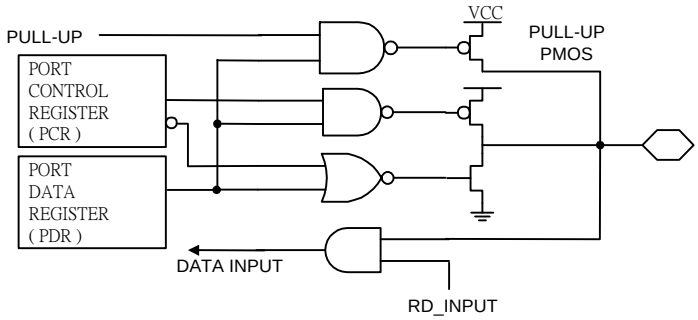


TABLE 10-13: PORT CONDITION CONTROL REGISTER (PMCR)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$00F	**PMCR**	R/W	PULL	PDBN	INTEG	-	-	-	PSGO	PSGOB	100 - - -00

Bit 7: **PULL :** Enable all pull-up functions bit
1 = Enable pull-up function
0 = Disable pull-up function

Bit 1: **PSGO :** PSG output enable bit
1 = PB1 is PSG data output pin if PB1 is set in output mode
0 = PB1 is normal I/O pin

Bit 0: **PSGOB :** PSG inverse signal output enable bit
1 = PB0 is PSG inverse data output pin if PB0 is set in output mode
0 = PB0 is normal I/O pin

10.4 SEGMENT-PORT

The SEG0~SEG3 can be used as LCD drivers or output ports. In output port mode, programmer must write $FF($00) into LCD RAM in order to output FLOAT(LOW).

The assignments of SEGO will be decided by Bit 3 of LCTL[3]. Please refer to TABLE 10-14.

TABLE 10-14: LCD CONTROL REGISTER (LCTL)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$03A	**LCTL**	W	LPWR	BLANK	COMO	LENH	SEGO	CTR[1]	CTR[0]	DUTY	0000 0000

Bit 3: **SEGO :** Segment output selection bit
1 = SEG0-SEG3 used as output pins
0 = SEG0-SEG3 used as LCD segment pins

TABLE 10-15: SEGMENT OUT REGISTER

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$200	**SEGMENT OUT 0**	W	SEGMENT-0 OUTPUT BIT								???? ????
$201	**SEGMENT OUT 1**	W	SEGMENT-1 OUTPUT BIT								???? ????
$202	**SEGMENT OUT 2**	W	SEGMENT-2 OUTPUT BIT								???? ????
$203	**SEGMENT OUT 3**	W	SEGMENT-3 OUTPUT BIT								???? ????

In the output port mode, programmer must write $FF($00) into LCD RAM to output FLOAT(LOW).

10.5 COMMON-PORT

The COM4~COM7 can be used as LCD drivers or output ports. In output port mode, SCAN[7~4] will be map to COM7~COM4 output ports, which pin assignment will be decided by Bit 5 of LCTL[5], Please refer to the following table.

TABLE 10-16: LCD CONTROL REGISTER (LCTL)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$03A	**LCTL**	W	LPWR	BLANK	COMO	LENH	SEGO	-	-	DUTY	0000 0- -0

Bit 5: **COMO :** Common output selection bit
1 = COM4~COM7 used as output pins
0 = COM4~COM7 used as LCD Common pins

TABLE 10-17: SCAN OUTPUT REGISTER (SCAN)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$03B	**SCAN**	R/W	SCAN[7]	SCAN[6]	SCAN[5]	SCAN[4]	-	-	-	-	0000 - - - -

Bit 4: **SCAN[4] :** COM4 scan output bit
1 = COM4 output =FLOAT
0 = COM4 output =LOW

Bit 5: **SCAN[5] :** COM5 scan output bit
1 = COM5 output = FLOAT
0 = COM5 output =LOW

Bit 6: **SCAN[6] :** COM6 scan output bit
1 = COM6 output = FLOAT
0 = COM6 output =LOW

Bit 7: **SCAN[7] :** COM7 scan output bit
1 = COM7 output = FLOAT
0 = COM7 output =LOW

11. OSCILLATOR

ST2024C is with dual-clock system. Programmer can choose between OSC(RC) and OSCX(32.768k), or both as clock source through program. The system clock(SYSCK) also can be switched between OSC and OSCX. The OSC will be switch with "0" and OSCX will be switch with "1" for **XSEL**. Whenever system clock be switch, the warm-up cycles are occur at the same time. That is confirm SYSCK really switched when read **XSEL** bit. LCD driver, Timer1, Base Timer and PSG can utilize these two clock sources as well.

TABLE 11-18: SYSTEM CONTROL REGISTER (SYS)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$030	**SYS**	R/W	XSEL	OSTP	XSTP	TEST	WSKP	WAIT	-	-	0000 00- -

Bit 7: **XSEL : SYS [XSEL] must be 0.**

Bit 6: **OSTP :** OSC stop control bit
1 = Disable OSC
0 = Enable OSC

Bit 5: **XSTP :** OSCX stop control bit
1 = Disable OSCX
0 = Enable OSCX

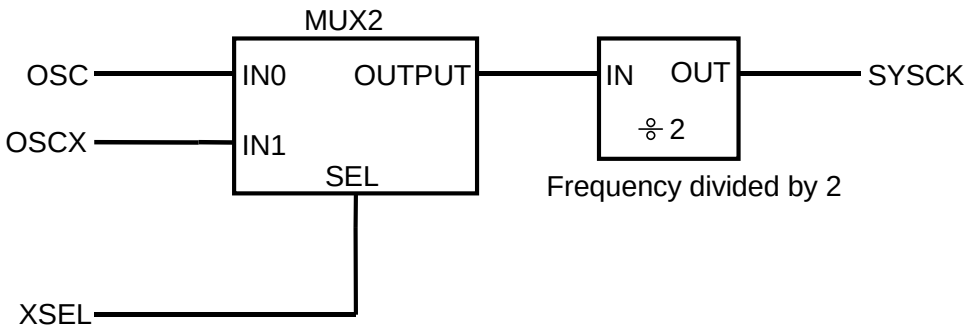
Bit 4: **TEST :** Test bit, must be "0"

Bit 3: **WSKP :** System warm-up control bit
1 = Warm-up to 16 oscillation cycles
0 = Warm-up to 256 oscillation cycles

Bit 2: **WAIT :** WAI-0 / WAI-1mode select bit (Refer to POWER DOWN MODE)
1 = WAI instruction causes the chip to enter WAI-1 mode
0 = WAI instruction causes the chip to enter WAI-0 mode

Note:
The XSEL(SYS[7]) bit will show which real working mode is when it is read.

FIGURE 11-5: System Clock Diagram



12. TIMER/EVENT COUNTER

The ST2024C has two timers: Base timer/Timer1, and two prescalers (PRES and PREW). There are two clock sources for PRES and one clock source(OSCX) for PREW. Please refer to the following table:

TABLE 12-19: CLOCK SOURCE (TCLK) FOR PRES

SENT	Clock source(TCLK)	MODE
1	INTX	Event counter
0	SYSCK	Timer

TABLE 12-20: SUMMARY FOR TIMER REGISTERS

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$021	**BTM**	R/W	-	-	-	-	BTM[3]	BTM[2]	BTM[1]	BTM[0]	- - - - 0000
$023	**PRS**	R	PRS[7]	PRS[6]	PRS[5]	PRS[4]	PRS[3]	PRS[2]	PRS[1]	PRS[0]	0000 0000
		W	SRES	SENA	SENT	-	-	-	-	-	000 - - - - -
$026	**T1M**	R/W	-	-	-	T1M[4]	T1M[3]	T1M[2]	T1M[1]	T1M[0]	- - -0 0000
$027	**T1C**	R/W	T1C[7]	T1C[6]	T1C[5]	T1C[4]	T1C[3]	T1C[2]	T1C[1]	T1C[0]	0000 0000
$030	**SYS**	R/W	XSEL	OSTP	XSTP	TEST	WSKP	WAIT	-	-	0000 00- -
$03C	**IREQ**	R/W	-	-	IRBT	IRPT	IRT1	-	IRDAC	IRX	- - 11 1-11
$03E	**IENA**	R/W	-	-	IEBT	IEPT	IET1	-	IEDAC	IEX	- - 00 0-00

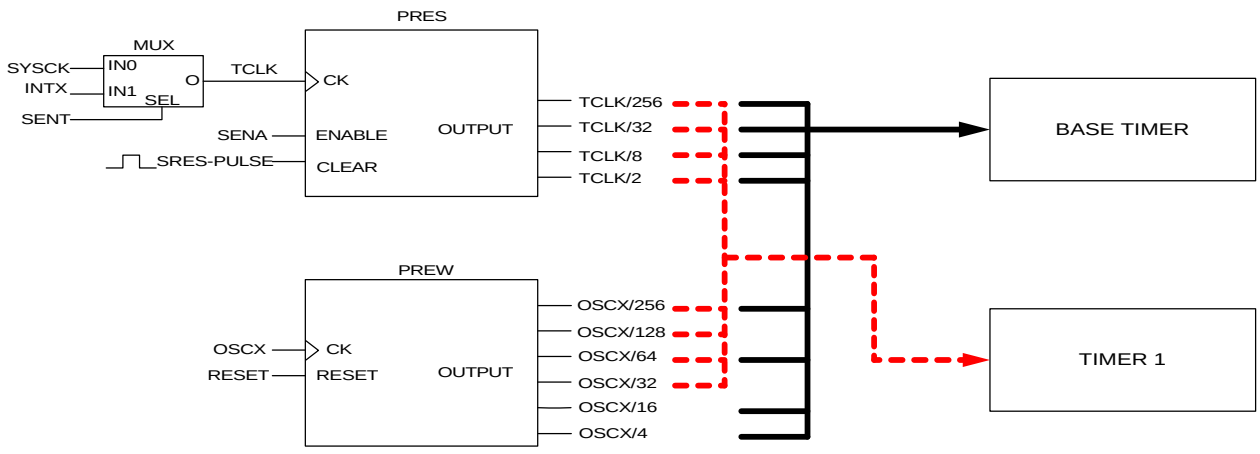


FIGURE 12-6: Prescaler for Timers

12.2 PRES

The prescaler PRES is an 8-bits counter as shown in Figure 12-6. Which provides four clock sources for base timer and timer1, and it is controlled by register PRS. The instruction read toward PRS will bring out the content of PRES and the instruction write toward PRS will reset, enable or select clock sources for PRES.
When user set external interrupt as the input of PRES for event counter, combining PRES and Timer1 will get a 16bit-event counter.

TABLE 12-21: PRESCALER CONTROL REGISTER (PRS)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$023	**PRS**	R	PRS[7]	PRS[6]	PRS[5]	PRS[4]	PRS[3]	PRS[2]	PRS[1]	PRS[0]	0000 0000
		W	SRES	SENA	SENT	-	-	-	-	-	000 - - - - -

READ
Bit 7~0: **PRS[7~0] :** 1's complement of PRES counter

WRITE
Bit 7: **SRES :** Prescaler Reset bit
Write "1" to reset the prescaler (PRS[7~0])

Bit 6: **SENA :** Prescaler enable bit
0 = Disable prescaler counting
1 = Enable prescaler counting

Bit 5: **SENT :** Clock source(TCLK) selection for prescaller PRES
0 = Clock source from system clock "SYSCK"
1 = Clock source from external events "INTX"

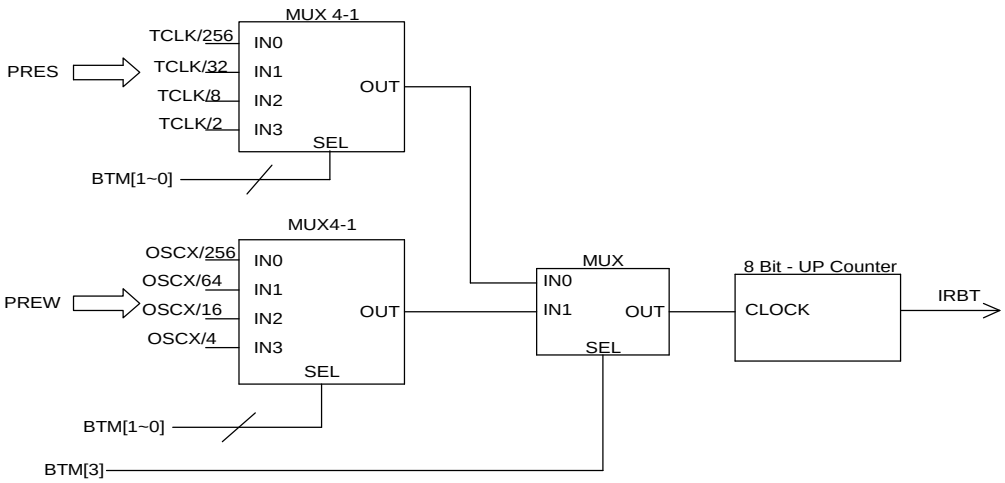
12.3 PREW

The prescaler PREW is an 8-bits counter as shown in Figure 12-6. PREW provides four clock source for base timer and timer1. It stops counting only if OSCX stops or hardware reset occurs.

12.4 Base timer

Base timer is an 8-bit up counting timer. When it overflows from $FF to $00, a timer interrupt request IRBT will be generated. Please refer to Figure 11-7. :

FIGURE 12-7: Structure of Base Timer



12.4.2 Clock source control for Base Timer

Several clock sources can be selected for Base Timer. Please refer to the following table:

TABLE 12-22: CLOCK SOURCE FOR BASE TIMER

* SENA	BTM[3]	BTM[2]	BTM[1]	BTM[0]	Base Timer source clock
0	0	X	X	X	STOP
1	0	X	0	0	TCLK / 256
1	0	X	0	1	TCLK / 32
1	0	X	1	0	TCLK / 8
1	0	X	1	1	TCLK / 2
X	1	X	0	0	OSCX / 256
X	1	X	0	1	OSCX / 64
X	1	X	1	0	OSCX / 16
X	1	X	1	1	OSCX / 4

* TCLK will stop when an ‘0’ is written to SENA(PRS[6]).

12.5 Timer 1

The Timer1 is an 8-bit up counter. It can be used as a timer or an event counter. T1C($27) is a real time read/write counter. When an overflow from $FF to $00, a timer interrupt request IRT1 will be generated. Timer1 will stop counting when system clock stops. Please refer to Figure 11-8.

FIGURE 12-8: Timer1 Structure Diagram

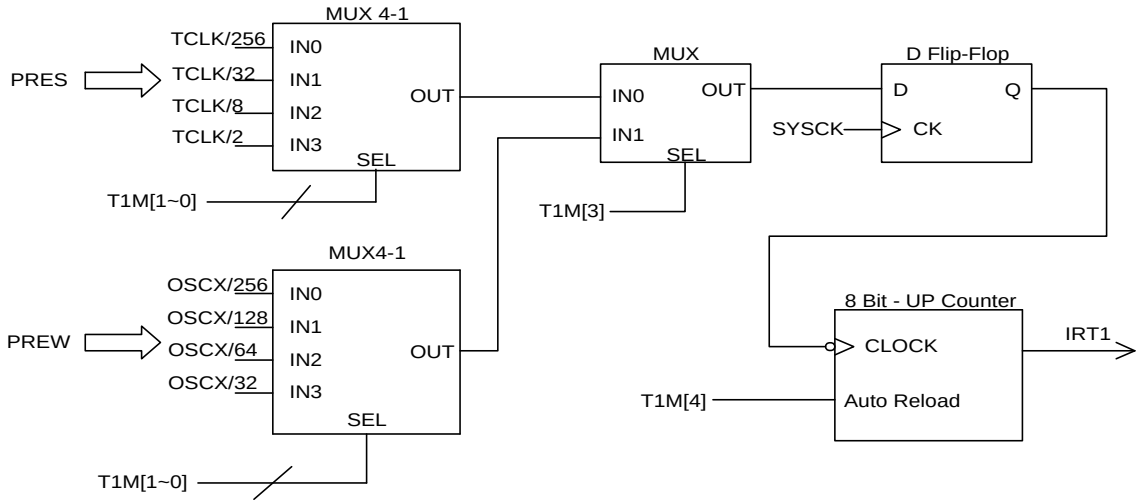


TABLE 12-23: TIMER1 COUNTING REGISTER (T1C)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$027	**T1C**	R/W	T1C[7]	T1C[6]	T1C[5]	T1C[4]	T1C[3]	T1C[2]	T1C[1]	T1C[0]	0000 0000

12.5.1.2

Bit 7-0: **T1C[7-0] :** Timer1 up counter register

12.5.2 Clock source control for Timer1

Several clock source can be chosen from for Timer1. It's very important that Timer1 can keep counting as long as SYSCK stays active. Refer to the following table:

TABLE 12-24: CLOCK SOURCE FOR TIMER1

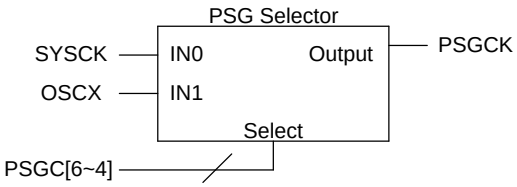
* SENA	T1M[4]	T1M[3]	T1M[2]	T1M[1]	T1M[0]	Clock source	Auto-Reload
0	X	0	X	X	X	STOP	-
1	0	0	X	0	0	TCLK / 256	No
1	0	0	X	0	1	TCLK / 32	No
1	0	0	X	1	0	TCLK / 8	No
1	0	0	X	1	1	TCLK / 2	No
X	0	1	X	0	0	OSCX / 256	No
X	0	1	X	0	1	OSCX / 128	No
X	0	1	X	1	0	OSCX / 64	No
X	0	1	X	1	1	OSCX / 32	No
1	1	0	X	0	0	TCLK / 256	Yes
1	1	0	X	0	1	TCLK / 32	Yes
1	1	0	X	1	0	TCLK / 8	Yes
1	1	0	X	1	1	TCLK / 2	Yes
X	1	1	X	0	0	OSCX / 256	Yes
X	1	1	X	0	1	OSCX / 128	Yes
X	1	1	X	1	0	OSCX / 64	Yes
X	1	1	X	1	1	OSCX / 32	Yes

* TCLK would stop when SENA is set to 0.

13. PSG

The built-in dual channel Programmable Sound Generator (PSG) is controlled by registers directly. Its flexibility through setting several parameters to registers makes it useful in many applications, such as music synthesis, sound effects generation, audible alarms and tone generation. PSG will finish the reset when user needs to create sound effect. The structure of PSG is shown in Figure 12-10 and its clock sources are shown in Figure 12-9. The ST2024C has three PSG playing type.one for channel0(C0) & channel1(C1) square type sound playing.One for ch0 square tone sound and ch1 noise sound.The third sound playing type is DAC PCM playing.

FIGURE 13-9: Clock Source for PSG



PSGC			PSGCK
B6	B5	B4	
0	0	0	SYSCK/2
X	0	1	SYSCK/4
X	1	0	SYSCK/8
0	1	1	SYSCK/16
1	0	0	SYSCK

FIGURE 13-10: Program Sound Generator

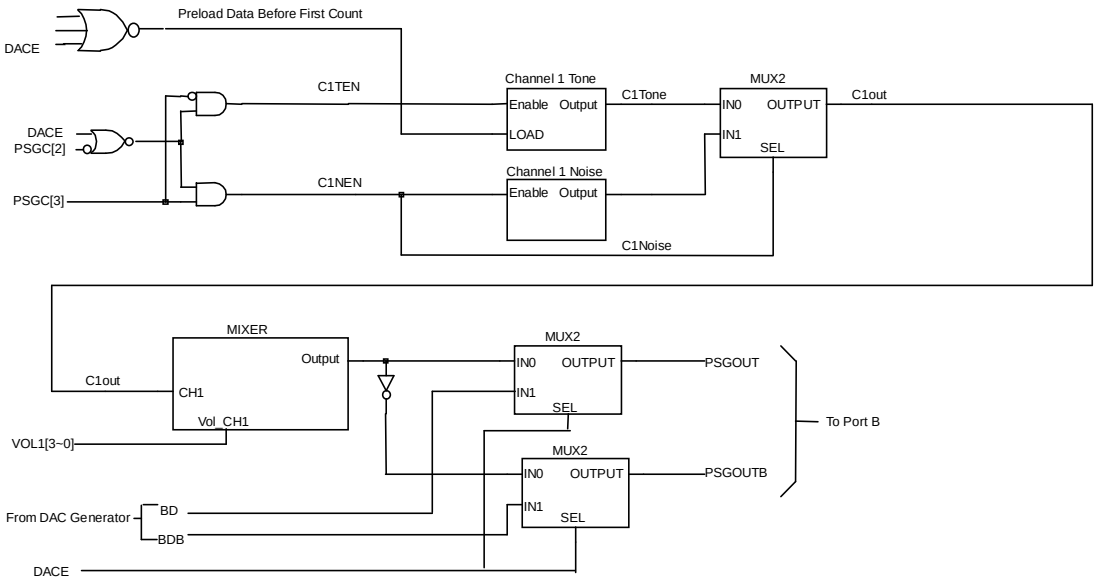


TABLE 13-25: SUMMARY FOR PSG REGISTERS

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$00F	**PMCR**	R/W	PULL	PDBN	INTEG	-	-	-	PSGO	PSGB	100 - - -00
$010	**PSG0L**	R/W	PSG0[7]	PSG0[6]	PSG0[5]	PSG0[4]	PSG0[3]	PSG0[2]	PSG0[1]	PSG0[0]	0000 0000
$11	**PSG0H**	R/W	-	-	-	-	PSG0[11]	PSG0[10]	PSG0[9]	PSG0[8]	- - - - 0000
$012	**PSG1L**	R/W	PSG1[7]	PSG1[6]	PSG1[5]	PSG1[4]	PSG1[3]	PSG1[2]	PSG1[1]	PSG1[0]	0000 0000
$013	**PSG1H**	R/W	-	-	-	-	PSG1[11]	PSG1[10]	PSG1[9]	PSG1[8]	- - - - 0000
$016	**PSGC**	R/W	-	PCK[2]	PCK[1]	PCK[0]	PRBS	C1EN	C0EN	DACE=0	- 000 0000
		R/W	-	PCK[2]	PCK[1]	PCK[0]	DMD[1]	DMD[0]	INH	DACE=1	- 000 0000
$017	**VOL**	R/W	VOL1[3]	VOL1[2]	VOL1[1]	VOL1[0]	VOL0[3]	VOL0[2]	VOL0[1]	VOL0[0]	0000 0000

TABLE 13-26: CONTROL REGISTER FOR PSG OUTPUT (PMCR)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$00F	**PMCR**	R/W	PULL	PDBN	INTEG	-	-	-	PSGO	PSGB	100 - - -00

Bit 1: **PSGO :** PSG output enable bit
1 = PSG data output pin if PB1 is set in output mode
0 = PB1 is normal I/O pin

Bit 0: **PSGB :** PSG inverse signal output enable bit
1 = PB0 is PSG inverse data output pin if PB0 is set in output mode
0 = PB0 is normal I/O pin

TABLE 13-27: CONTROL REGISTER FOR PSG VOLUME (VOL)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$017	**VOL**	R/W	VOL1[3]	VOL1[2]	VOL1[1]	VOL1[0]	VOL0[3]	VOL0[2]	VOL0[1]	VOL0[0]	0000 0000

Bit 3~0: **VOL0[3~0] :** PSG volume control bit
＊0000 = No sound output
0001 = 1/16 volume (PSGCK must >= 320K Hz)
0010 = 2/16 volume
:
1110 = 15/16 volume
1111 = Maximum volume (PSGCK must >= 20K Hz)

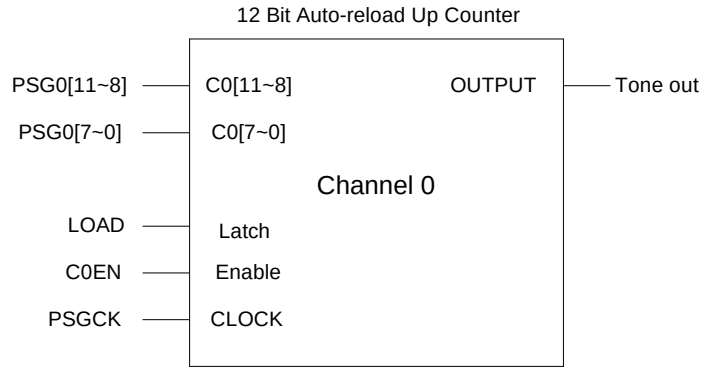
Bit 7~4: **VOL1[3~0] :** PSG volume control bit
＊0000 = No sound output
0001 = 1/16 volume (PSGCK must >= 320K Hz)
0010 = 2/16 volume
:
1110 = 15/16 volume
1111 = Maximum volume (PSGCK must >= 20K Hz)

＊ Only use Channel-0 and VOL=0FFH，volume is maximum.

13.2 Tone Generator

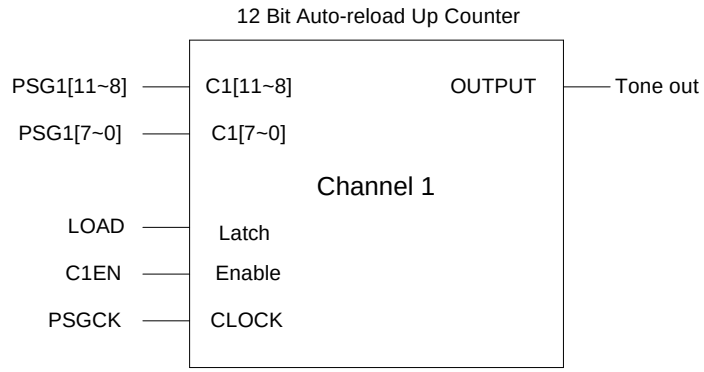
The tone frequency is decided by PSGCK and 12-bit programmable divider (PSG0[11~0]) and (PSG1[11~0]) Please refert Figure12-11.

FIGURE 13-11: Channel0 PSG Tone Counter



Frequency of Channel 0 Tone = PSGCK/(1000H-PSG0[11~0])/2

FIGURE 13-12: Channel1 PSG Tone Counter



Frequency of Channel 1 Tone = PSGCK/(1000H-PSG1[11~0])/2

13.3 PSG Tone programming

To program tone generator, PSGO (PMCR[1]) or PSGB (PMCR[0]) should be set to “1” for PB1 or PB0 in order to be in the PSG output mode. Tone or DAC function is defined by DACE, writing to C1EN will enable tone generator when PSG is in tone function. Noise or tone function is selected by PRBS.

TABLE 13-28: PSG CONTROL REGISTER (PSGC)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$016	**PSGC**	R/W	-	PCK[2]	PCK[1]	PCK[0]	PRBS	C1EN	C0EN	DACE=0	- 000 0000
		R/W	-	PCK[2]	PCK[1]	PCK[0]	DMD[1]	DMD[0]	INH	DACE=1	- 000 0000

Bit 0: **DACE :** Tone(Noise) or DAC Generator selection bit
1 = PSG is used as the DAC generator
0 = PSG is used as the Tone(Noise) generator

Bit 1: **C0EN :** PSG Channel-0(Tone) enable bit
1 = PSG0 enable
0 = PSG0 disable

Bit 2: **C1EN :** PSG Channel-1(Tone or Noise) enable bit
1 = PSG1 (Tone or Noise) enable
0 = PSG1 (Tone or Noise) disable

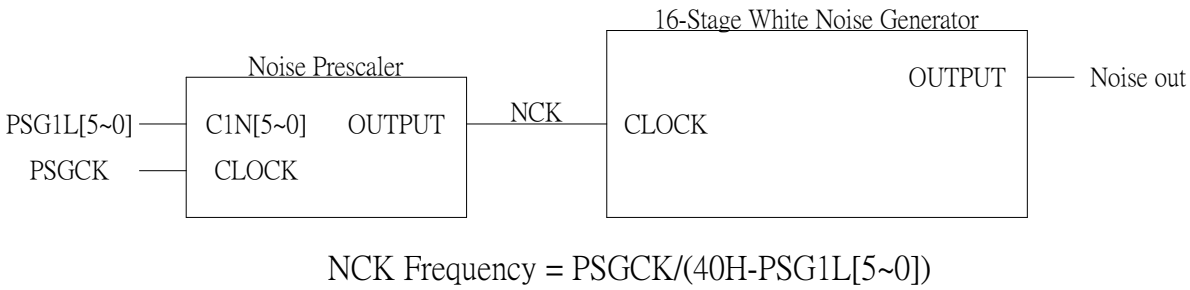
Bit 3: **PRBS :** Tone or Noise generator selection bit
1 = Noise generator
0 = Tone generator

Bit 6~4: **PCK[2~0] :** clock source(PSGCK) selection for PSG and DAC
000 = SYSCK / 2
X01 = SYSCK / 4
X10 = SYSCK / 8
011 = SYSCK / 16
100 = SYSCK

13.4 Noise Generator Control

Noise generator is shown in Figure 12-12., which base frequency is controlled by PSG1L[5~0].

FIGURE 13-13: Noise Generator Diagram



NCK Frequency = PSGCK/(40H-PSG1L[5~0])

13.5 PSG Noise programming

To program noise generator, PSGO (PMCR[1]) or PSGB (PMCR[0]) should be set to “1” for PB1 or PB0 in order to be in PSG output. Noise or DAC function is defined by DACE.

Writing a “1” to C1EN will enable noise generator when PSG is in noise mode.

14. DIGITAL DAC

A built-in digital DAC is for analog sampling data or voice signals. The structure of DAC is shown in Figure 13-13. There is an interrupt signal from DAC to CPU whenever DAC data update is needed and the same signal will decide the sampling rate of voice. In DAC mode, the OSC can't less 4 M Hz.

TABLE 14-29: SUMMARY FOR DAC REGISTERS

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$00F	**PMCR**	R/W	PULL	PDBN	INTEG	-	-	-	PSG0	PSGB	100 - - -00
$012	**PSG1L**	R/W	PSG1[7]	PSG1[6]	PSG1[5]	PSG1[4]	PSG1[3]	PSG1[2]	PSG1[1]	PSG1[0]	0000 0000
$013	**PSG1H**	R/W	-	-	-	-	PSG1[11]	PSG1[10]	PSG1[9]	PSG1[8]	- - - - 0000
$014	**DAC**	R/W	DAC[7]	DAC[6]	DAC[5]	DAC[4]	DAC[3]	DAC[2]	DAC[1]	DAC[0]	0000 0000
$016	**PSGC**	R/W	-	PCK[2]	PCK[1]	PCK[0]	PRBS	C1EN	C0EN	DACE=0	- 000 0000
		R/W	-	PCK[2]	PCK[1]	PCK[0]	DMD[1]	DMD[0]	INH	DACE=1	- 000 0000

TABLE 14-30: DAC DATA REGISTER (DAC)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$014	**DAC**	R/W	DAC[7]	DAC[6]	DAC[5]	DAC[4]	DAC[3]	DAC[2]	DAC[1]	DAC[0]	0000 0000

Bit 7~0: **DAC[7~0] :** DAC output data

Note: For Single-Pin Single Ended mode, the effective output resolution is 7 bit.

TABLE 14-31: DAC CONTROL REGISTER (PSGC)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$016	**PSGC**	R/W	-	PCK[2]	PCK[1]	PCK[0]	PRBS	C1EN	-	DACE=0	- 000 00-0
		R/W	-	PCK[2]	PCK[1]	PCK[0]	DMD[1]	DMD[0]	INH	DACE=1	- 000 0000

Bit 0: **DACE :** PSG play as Tone(Noise) or DAC Generator selection bit
1 = PSG is used as DAC Generator
0 = PSG is used as Tone(Noise) Generator

Bit 1: **INH :** DAC output inhibit control bit
1 = DAC output inhibit
0 = DAC output enable

Bit 3~2: **DMD[1~0] :** DAC output mode selection
00 = Single-Pin mode : 7 bit resolution
01 = Two-Pin Two Ended mode : 8 bit resolution
10 = Reserved
11 = Two-Pin Push Pull mode : 8 bit resolution

Bit 6~4: **PCK[2~0] :** PSGCK selection for PSG and DAC
000 = SYSCK / 2
X01 = SYSCK / 4
X10 = SYSCK / 8
011 = SYSCK / 16
100 = SYSCK *

*** In DAC mode, PSGCK must select SYSCK.**

14.2 Sampling Rate Control

The sample rate is controlled by PSG1L and PSG1H. PSG1[11~7] controls sample rate/post scaling and PSG1[6] must set '0' and PSG1[5~0] must set '1'. The input clock source is controlled by PCK[2~0]. The block diagram is shown as the following:

FIGURE 14-14: DAC Generator Diagram

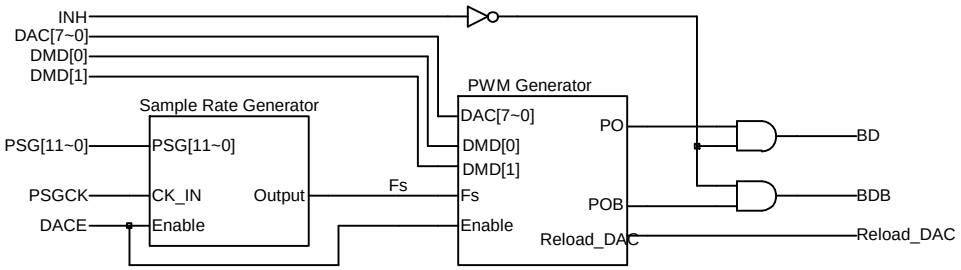
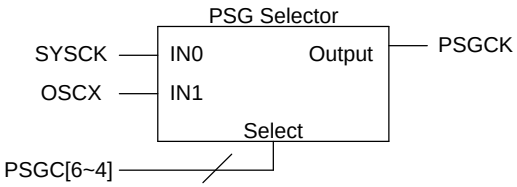


FIGURE 14-15: Clock Source for DAC



PSGC			PSGCK
B6	B5	B4	
0	0	0	SYSCK/2
X	0	1	SYSCK/4
X	1	0	SYSCK/8
0	1	1	SYSCK/16
1	0	0	SYSCK

TABLE 14-32: Sample Rate description table

DAC SAMPLE RATE ALGORITHM DESCRIPTION
Sample-Rate = PSGCK / 128 / (20H-PSG1[11~7])
Note: PSG1[6] must set '0' and PSG1[5~0] must set '1' by DAC mode.

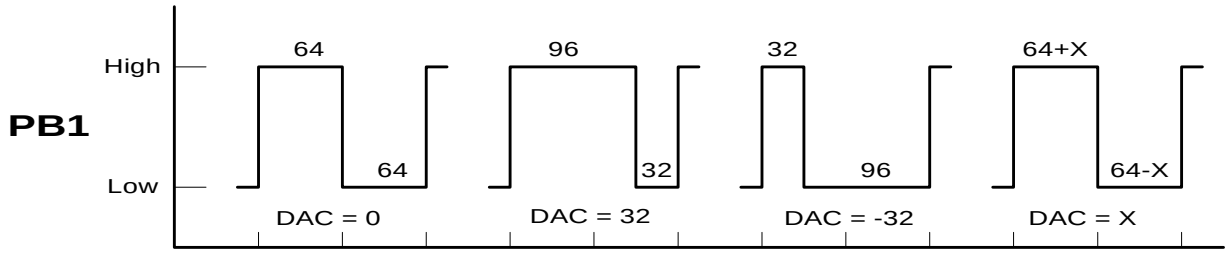
14.3 PWM DAC Mode Select

The PWM DAC generator has three modes, Single-pin mode, Two-pin two ended mode and Two-pin push pull mode. They are depended on the application used. The DAC mode is controlled by DMD[1~0]. (TABLE 13-31)

14.3.1 Single-Pin Mode (Accurate to 7 bits)

Single-pin mode is designed for use with a single-transistor amplifier. It has 7 bits of resolution. The duty cycle of the **PB1** is proportional to the output value. If the output value is 0, the duty cycle is 50%. As the output value increases from 0 to 63, the duty cycle goes from being high 50% of the time up to 100% high. As the value goes from 0 to -64, the duty cycle decreases from 50% high to 0%. **PB0** is inverse of **PB1**'s waveform. Figure 13-15 shows the **PB1** wave-forms.

FIGURE 14-16: Single-Pin PWM DAC Wave-form



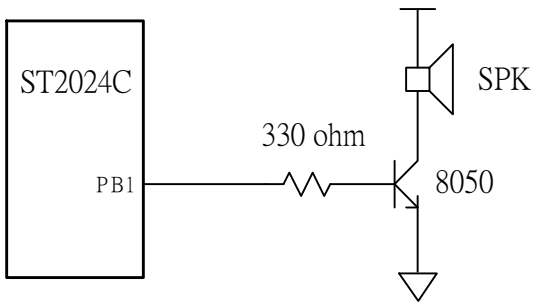


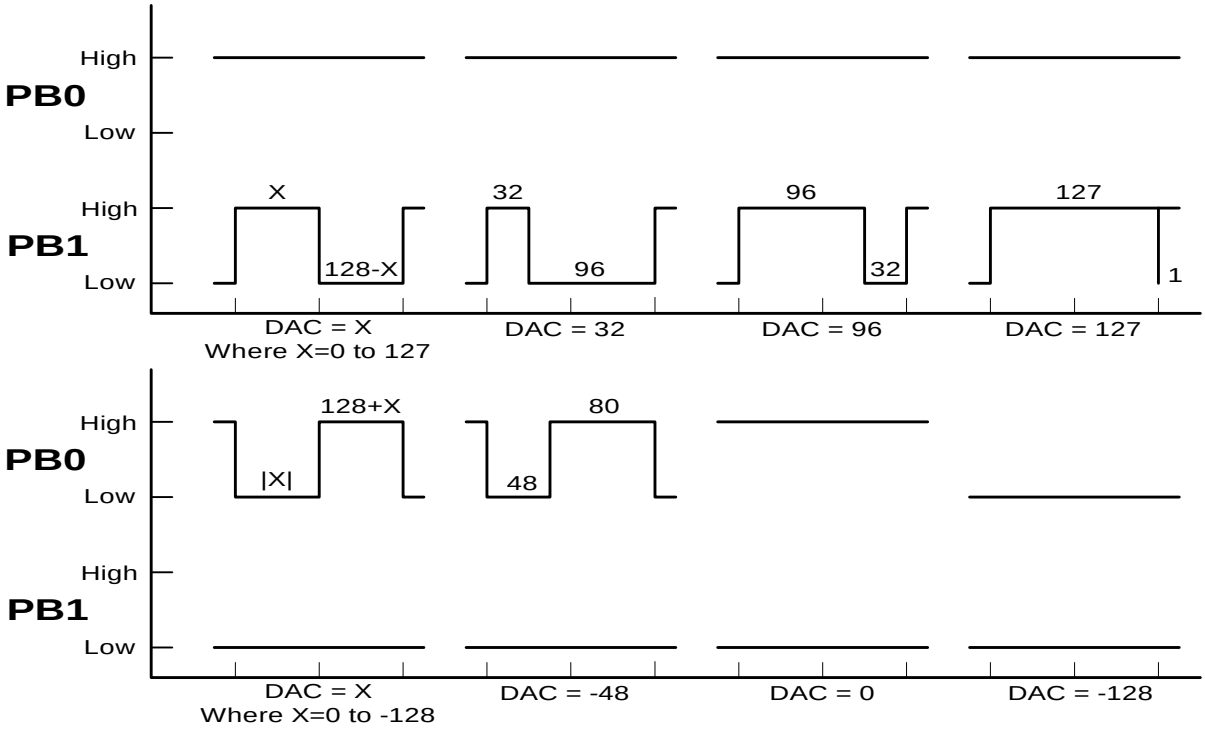
FIGURE 14-17: Single-Pin Application Circuit

14.3.2 Two-Pin Two Ended mode (Accurate to 8 bits)

Two-Pin Two Ended mode is designed for use with a single transistor amplifier. It requires two pins that **PB0** and **PB1**. When the DAC value is positive, **PB1** goes high with a duty cycle proportional to the output value, while **PB0** stays high. When the DAC value is negative, **PB0** goes low with a duty cycle proportional to the output value, while **PB1** stays low. This mode offers a resolution of 8 bits.

Figure 13-17 shows examples of DAC output waveforms with different output values. Each pulse of the DAC is divided into 128 segments per sample period. For a positive output value x=0 to 127, **PB1** goes high for X segments while **PB0** stays high. For a negative output value x=0 to -127, **PB0** goes low for |X| segments while **PB1** stays low.

FIGURE 14-18: Two-Pin Two Ended PWM DAC Wave-form



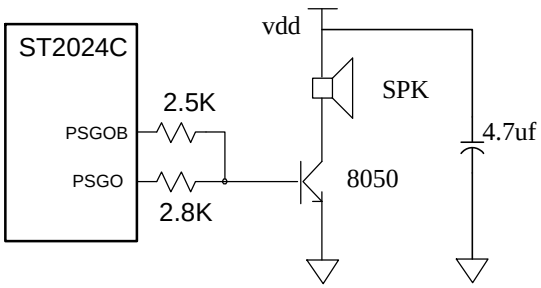


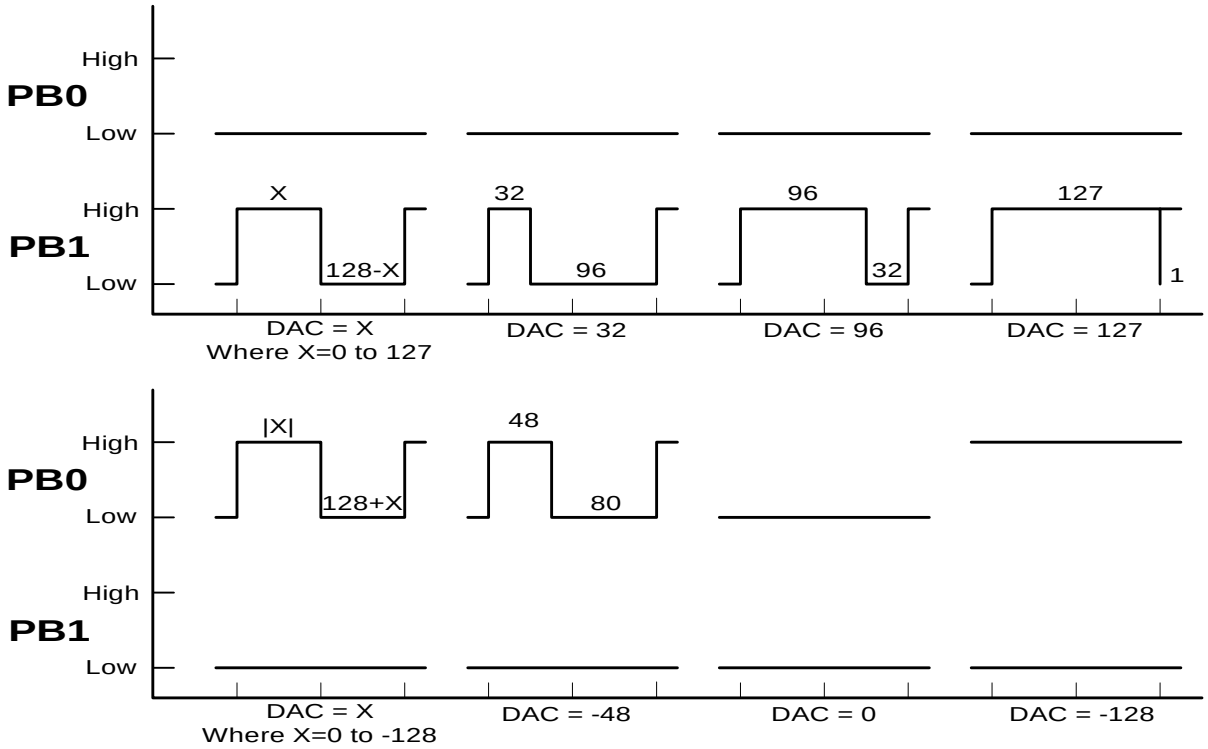
FIGURE 14-19: Two-Pin Two Ended mode Application Circuit

14.3.3 Two-Pin Push Pull mode (Accurate to 8 bits)

Two-Pin Push Pull mode is designed for buzzer. It requires two pins that **PB0** and **PB1**. When the DAC value is 0, both pins are low. When the DAC value is positive, **PB1** goes high with a duty cycle proportional to the output value, while **PB0** stays low. When the DAC value is negative, **PB0** goes high with a duty cycle proportional to the output value, while **PB1** stays low. This mode offers a resolution of 8 bits.

Figure 13-19 shows examples of DAC output waveforms with different output values. Each pulse of the DAC is divided into 128 segments per sample period. For a positive output value x=0 to 127, **PB1** goes high for X segments while **PB0** stays low. For a negative output value x=0 to -127, **PB0** goes high for |X| segments while **PB1** stays low.

FIGURE 14-20: Two-Pin Push Pull PWM DAC Wave-form



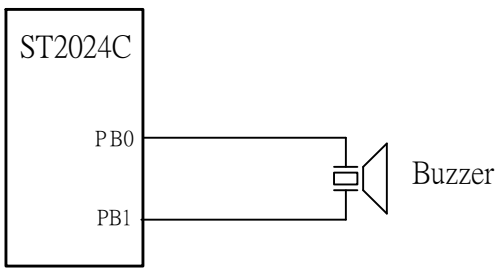


FIGURE 14-21: Two-Pin Push Pull Application Circuit

15. LCD

The ST2024C can drive up to 320 dots of LCD panel directly. The LCD driver can control by 1/4 duty(160 dots) and 1/8 duty (320 dots). LCD block include display RAM ($200~ $227) for storing the display data, 40-segment output pins (SEG0~SEG39), 8-common output pins (COM0~COM7).

All LCD RAM are random after power on reset. The bias voltage circuits of the LCD display is built-in and no external resistor is needs.

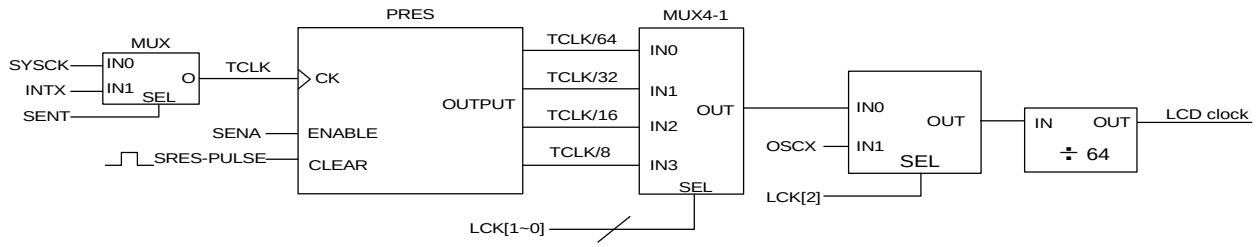
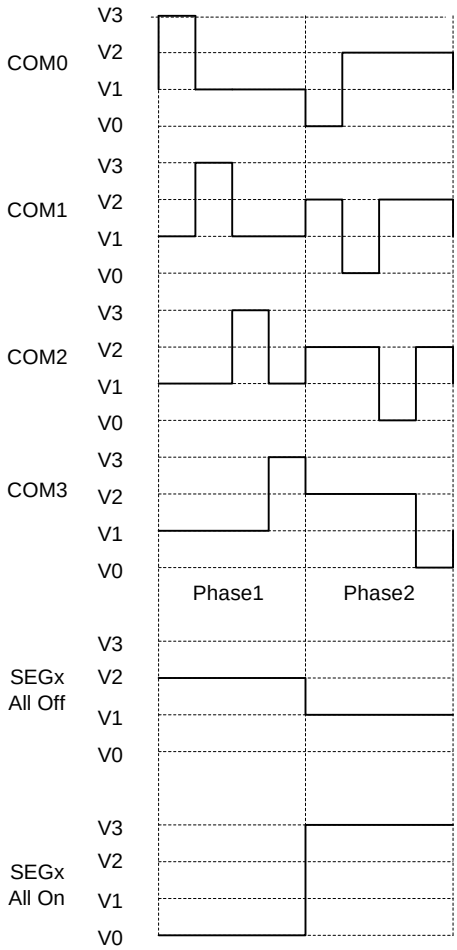


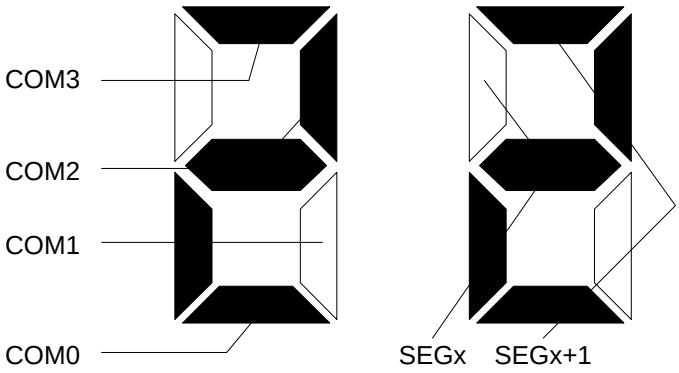
FIGURE 15-22: Clock source of LCD

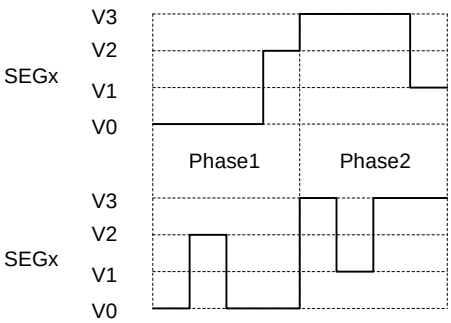
15.2 LCD driver 1/4 duty output

1/4 duty , 1/3 bias LCD signal



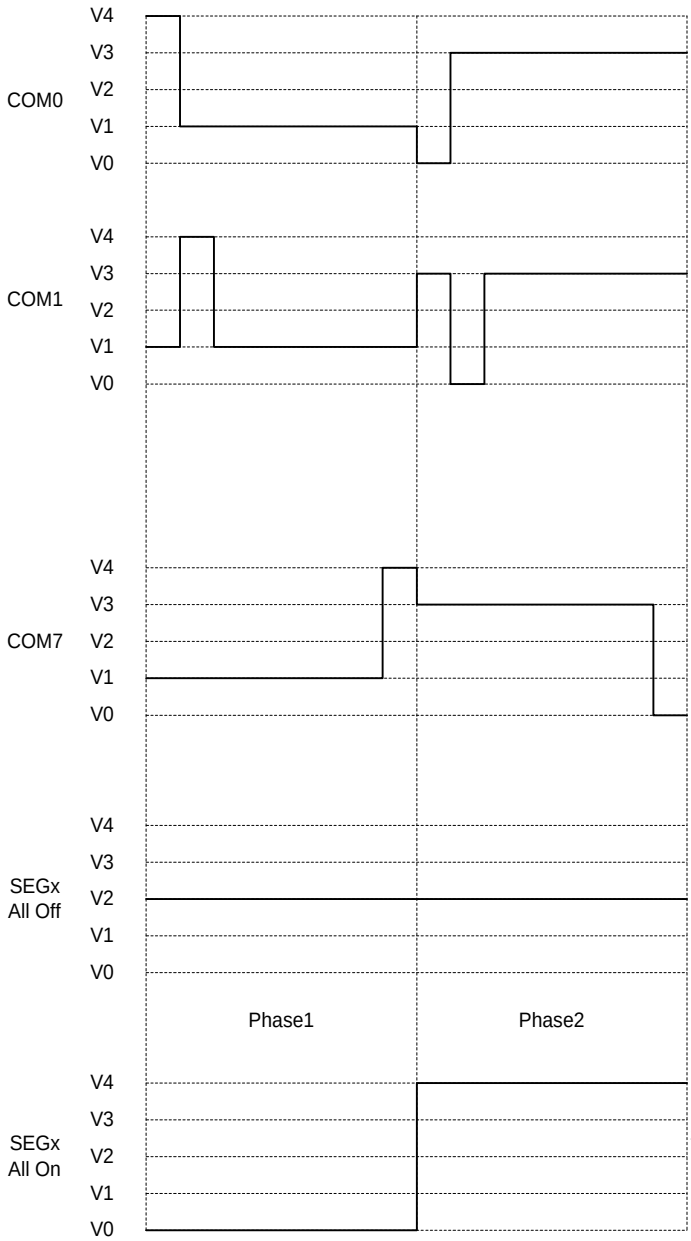
Example



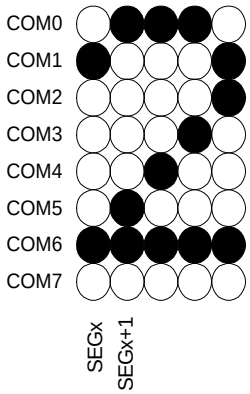


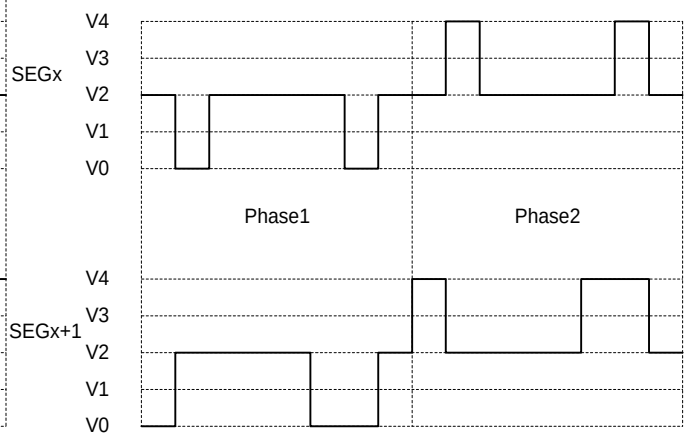
15.3 LCD driver 1/8 duty output

1/8 duty , 1/4 bias LCD signal



Example





15.4 LCD control register

TABLE 15-33: LCD CONTROL REGISTERS

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$020	**LCK**	R/W	-	-	DRV[2]	DRV[1]	DRV[0]	LCK[2]	LCK[1]	LCK[0]	- - 00 0100
$023	**PRS**	R/W	SRES	SENA	SENT	-	-	-	-	-	000 - - - - -
$038	**XLCD**	R/W	-	-	-	-	-	-	HEAV	-	- - - - - -0-
$03A	**LCTL**	W	LPWR	BLANK	COMO	LENH	SEGO	CTR[1]	CTR[0]	DUTY	0000 0000

TABLE 15-34: LCD FREQUENCY REGISTER (LCK)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$020	**LCK**	R/W	-	-	DRV[2]	DRV[1]	DRV[0]	LCK[2]	LCK[1]	LCK[0]	- -00 0100

Bit 2~0: **LCK[2~0] :** LCD clock source

LCK[2:0]	Frame Rate
000	OSC / 131072 (4MHz / 131072 = 30.5Hz)
001	OSC / 65536 (4MHz / 65536 = 61.0Hz)
010	OSC / 32768 (4MHz / 32768 = 122.1Hz)
011	OSC / 16384 (4MHz / 16384 = 244.1Hz)
1XX	OSCX / 512 (32768 / 512 = 64Hz)

*****SENA must switch "1". (refer to FIGURE 14-21)**

Note: If LCD clock source is from OSCX, after power on, wait one second for OSCX to be stable and then turn on LCD.

Bit 5~3: **DRV[2~0] :** LCD driving strength control.

The LCD driving strength control will combine **HEAV(XLCD[1])** and **LENH(LCTL[4])** to select 32 level.

Unit: uA

LCD driving strength level	HEAV	LENH	DRV[2]	DRV[1]	DRV[0]	1/4 Duty power consumption	1/8 Duty power consumption
LEVEL 0	0	0	0	0	0	16.49	13.37
LEVEL 1	0	0	0	0	1	21.09	16.78
LEVEL 2	0	0	0	1	0	25.56	20.16
LEVEL 3	0	0	0	1	1	30	23.5
LEVEL 4	0	0	1	0	0	34.42	25.99
LEVEL 5	0	0	1	0	1	38.83	30.05
LEVEL 6	0	0	1	1	0	43.23	33.41
LEVEL 7	0	0	1	1	1	47.63	36.73
LEVEL 8	0	1	0	0	0	52.03	40.1
LEVEL 9	0	1	0	0	1	56.42	43.43
LEVEL 10	0	1	0	1	0	60.82	46.79
LEVEL 11	0	1	0	1	1	65.21	50.13
: **:**			**:** **:**			**:** **:**	
LEVEL 28	1	1	1	0	0	139.8	106.83
LEVEL 29	1	1	1	0	1	144.17	110.15
LEVEL 30	1	1	1	1	0	148.57	113.47
LEVEL 31	1	1	1	1	1	152.95	116.79

*** Measure Condition: Vdd=3V, LCD frame rate=64Hz, OSCX on , in WAI1.

TABLE 15-35: HEAVY DRIVING LCD MODE CONTROL

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$038	**XLCD**	R/W	-	-	-	-	-	-	HEAV	-	- - - - - - 0-

Bit 1: **HEAV :** LCD driving mode control
1 = Heavy driving mode
0 = Normal driving mode

TABLE 15-36: LCD CONTROL REGISTER (LCTL)

Address	Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
$03A	**LCTL**	W	LPWR	BLANK	COMO	LENH	SEGO	CTR[1]	CTR[0]	DUTY	0000 0000

Bit 7: **LPWR :** LCD power ON/OFF bit
1 = LCD power OFF
0 = LCD power ON

Bit 6: **BLANK :** LCD display ON/OFF bit
1 = Disable LCD display (Common line is still scanning)
0 = Enable LCD display

Bit 5: **COMO :** Output mode for LCD common
1 = COM7~COM4 will be general purpose output only pin
0 = All common output is used as LCD common driver.

Bit 4: **LENH :** heavy load control for LCD display
1 = Enhanced driving (For large size LCD panel with more power consumption)
0 = Normal driving

Bit 3: **SEGO :** mode control for LCD segment output
1 = SEG3~SEG0 will be general purpose output pin only
0 = All segment output is used as LCD segment driver

Bit 2~1: **CTR[1~0] :** LCD Contrast Control
00 = LCD Contrast maximum (level 4)
01 = LCD Contrast level 3
10 = LCD Contrast level 2
11 = LCD Contrast minimum (level 1)

Bit 0: **DUTY :** LCD duty control bit
1 = 1/8 duty (1/4 bias) *
0 = 1/4 duty (1/3 bias)

* Under 1/8 duty condition with writing a “1” to COMO, LCD output pin COM7~COM4 will be controlled by the SCAN register. (Please refer to 9.5 Common port)

15.5 LCD RAM map

The LCD RAM map is shown as following:

TABLE 15-37: LCD RAM MAPPING

SEG	ADDRESS	COM0	COM1	COM2	COM3	COM4	COM5	COM6	COM7
0	200H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
1	201H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
2	202H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
3	203H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
4	204H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
5	205H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
6	206H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
7	207H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
8	208H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
9	209H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
10	20AH	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
11	20BH	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
12	20CH	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
13	20DH	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
14	20EH	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
15	20FH	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
16	210H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
17	211H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
18	212H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
19	213H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
20	214H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
21	215H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
22	216H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
23	217H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
24	218H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
25	219H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
26	21AH	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
27	21BH	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
28	21CH	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
29	21DH	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
30	21EH	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
31	21FH	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
32	220H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
33	221H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
34	222H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
35	223H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
36	224H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
37	225H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
38	226H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7
39	227H	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7

Note:

1. The LCD RAM address is allocated at page 2 of memory map. Only bit0 ~ bit3 is useful when it is 1/4 duty mode.
2. The LCD RAM can be **write & read** as like general purpose RAM.

16. POWER DOWN MODE

The ST2024C has three power down modes: WAI-0, WAI-1 and STP. The instruction WAI will enable mode WAI-0 or WAI-1, which are controlled by WAIT(SYS[2]). The instruction WAI (WAI-0 and WAI-1 modes) can be wake-up by interrupt. However, the instruction of STP can only be wake-up by hardware reset.

16.1 WAI-0 Mode:

When **WAIT** is cleared, WAI instruction lets MCU enter WAI-0 mode. In the mean time, oscillator circuit is be active and interrupts, timer/counter, and PSG will all be working. Under such circumstance, CPU stops and the related instruction execution will stop. All registers, RAM, and I/O pins will retain their states before the MCU enter standby mode. WAI-0 mode can be wake-up by reset or interrupt request. If user disable interrupt(CPU register **I**='1'), MCU will still be wake-up but not go into the interrupt service routine. If interrupt is enabled(CPU register **I**='0'), the corresponding interrupt vector will be fetched and interrupt service routines will executed.
The sample program is showed as followed:

```
LDA #$00
STA SYS
WAI          ; WAI 0 mode
```

16.2 WAI-1 Mode:

When **WAIT** is set, WAI instruction let MCU to enter WAI-1 mode. In this mode, the CPU will stop, but PSG, timer/counter won't stop if the clock source is from OSCX. The wake-up procedure is the same as the one for WAI-0. But the warm-up cycles are occur when WAI-1 wake-up.
The sample program is shown as the following:

```
LDA #$04
STA SYS
WAI          ; WAI 1 mode
```

16.3 STP Mode:

STP instruction will force MCU to enter stop mode. In this mode, MCU stops, but PSG, timer/counter won't stop if the clock source is from OSCX. In power-down mode, MCU only be wake-up by hardware reset, and the warm-up cycles are occur at the same time.
The sample program is showed as the following:

```
:
STP
:
:
```

TABLE 16-38: STATUS UNDER POWER DOWN MODE

(SYSCK source from OSC)

Mode	FIGURE imer1	SYSCK	OSC	OSCX	Base Timer	RAM	REG.	LCD	I/O	Wake-up condition
WAI-0	Retain									Reset, Any interrupt
WAI-1	Stop	Stop	Stop	Retain						Reset, Any interrupt
STP	Stop	Stop	Stop	Retain						Reset

(SYSCK source from OSCX)

Mode	FIGURE imer1	SYSCK	OSC	OSCX	Base Timer	RAM	REG.	LCD	I/O	Wake-up condition
WAI-0	Retain									Reset, Any interrupt
WAI-1	Stop	Stop	Retain							Reset, Any interrupt
STP	Stop	Stop	Retain							Reset

17. ST2024C ELECTRICAL CHARACTERISTICS

DC Supply Voltage ---------- -0.3V to +7.0V

Operating Ambient Temperature ---------- -10°C to +60°C

Storage Temperature ---------- -10°C to +125°C

***Notice:** Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. All the ranges are stress ratings only. Functional operation of this device at these or any other conditions above those indicated in the operational sections of this specification is not implied or intended. Exposed to the absolute maximum rating conditions for extended periods may affect device reliability.

17.1 DC Electrical Characteristics

Standard operation conditions: V_{DD} = 3.0V, GND = 0V, T_A = 25°C, OSC = 4M Hz, OSCX = 32768 Hz,unless otherwise specified

Parameter	Symbol	Min.	Typ.	Max.	Unit	Condition
Operating Voltage	V_{DD}	2.4	3	3.6	V	
Operating Current	I_{OP}		850	1275	μA	All output pins unload, execute NOP instruction, LCD on
Standby Current 1	I_{SB1}	-	0.8	1.2	μA	All output pins unload, OSCX off, LCD off (WAIT1/STOP mode)
Standby Current 2	I_{SB2}	-	4.58	6.87	μA	All output pins unload, OSCX on, LCD off (WAIT1/STOP mode)
Standby Current 3	I_{SB3}	-	16.7	-	μA	All output pins unload, OSCX on, LCD on (level0, 1/4duty) (WAIT1/STOP mode)
Standby Current 4	I_{SB4}	-	13.7	-	μA	All output pins unload, OSCX on, LCD on (level0, 1/8duty) (WAIT1/STOP mode)
Standby Current 5	I_{SB5}	-	95.7	141	μA	All output pins unload, OSCX off, LCD on (WAIT0 mode)
Input High Voltage	V_{IH}	$0.7V_{DD}$	-	V_{DD} + 0.3	V	PORT A, PORT B
		$0.85V_{DD}$	-		V	$\overline{INT}$
Input Low Voltage	V_{IL}	GND -0.3	-	$0.3V_{DD}$	V	PORT A, PORT B
			-	$0.15V_{DD}$	V	$\overline{INT}$
Pull-up resistance	R_{OH}		45		KΩ	PORTA, PORTB (IOH = -20uA, VOH=0.7Vdd).
Port A output high voltage	V_{OH1}	0.7 V_{DD}	-		V	PORTA, PORTB (IOH = -10mA).
Port A output low voltage	V_{OL1}			0.3 V_{DD}	V	PORTA, PORTB (IOL= 4mA).
Port B output high voltage	V_{OH1}	0.7 V_{DD}	-		V	PORTA, PORTB (IOH = -62mA).
Port B output low voltage	V_{OL1}			0.3 V_{DD}	V	PORTA, PORTB (IOL= 33mA).
SEG output low voltage	V_{OL2}			0.3 V_{DD}	V	SEGx, I_{OL} = 4mA
COM output low voltage	V_{OL3}			0.3 V_{DD}	V	COMx, I_{OL} = 4mA.
OSCX start time	T_{STT}	-	1	3	s	
Frequency stability	Δ F / F				PPM	[F(3.0)-F(2.5)]/F(3.0)(crystal oscillator)
Frequency variation	Δ F / F				PPM	C1= 15 – 30P.

FIGURE 17-25: Relation between Operation Voltage & Frequency

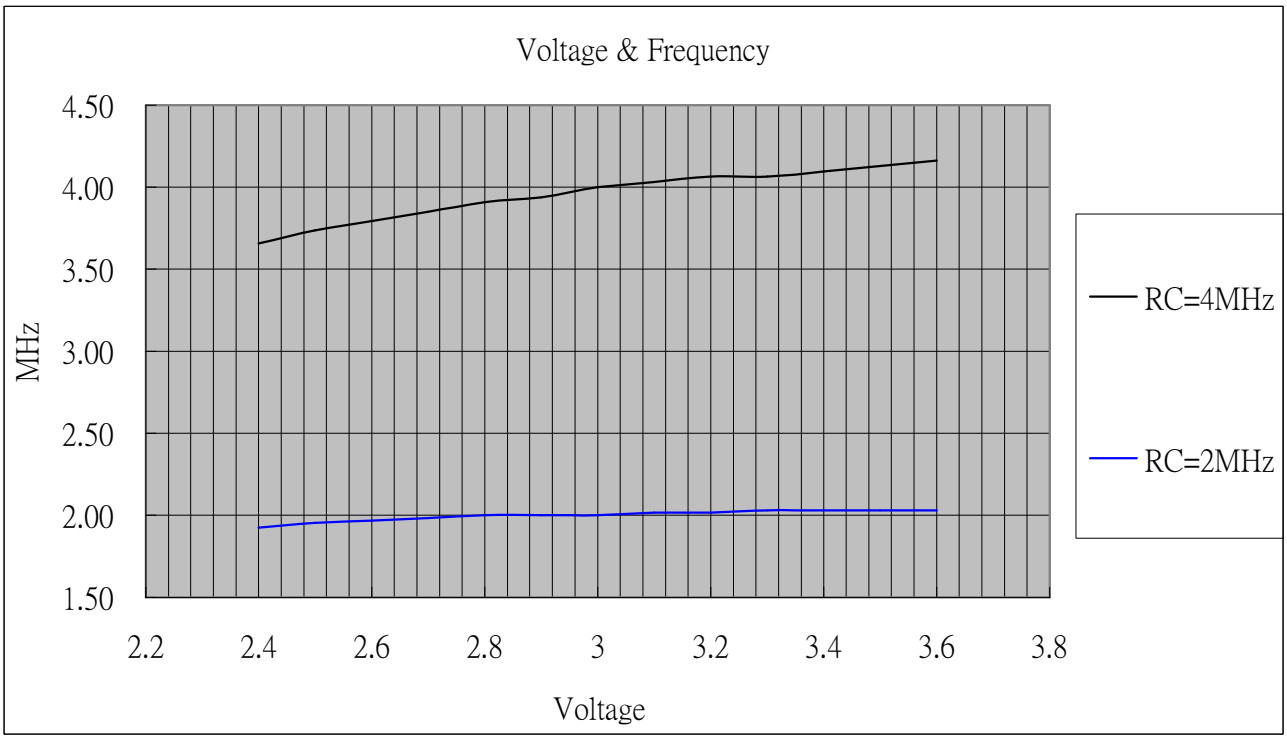


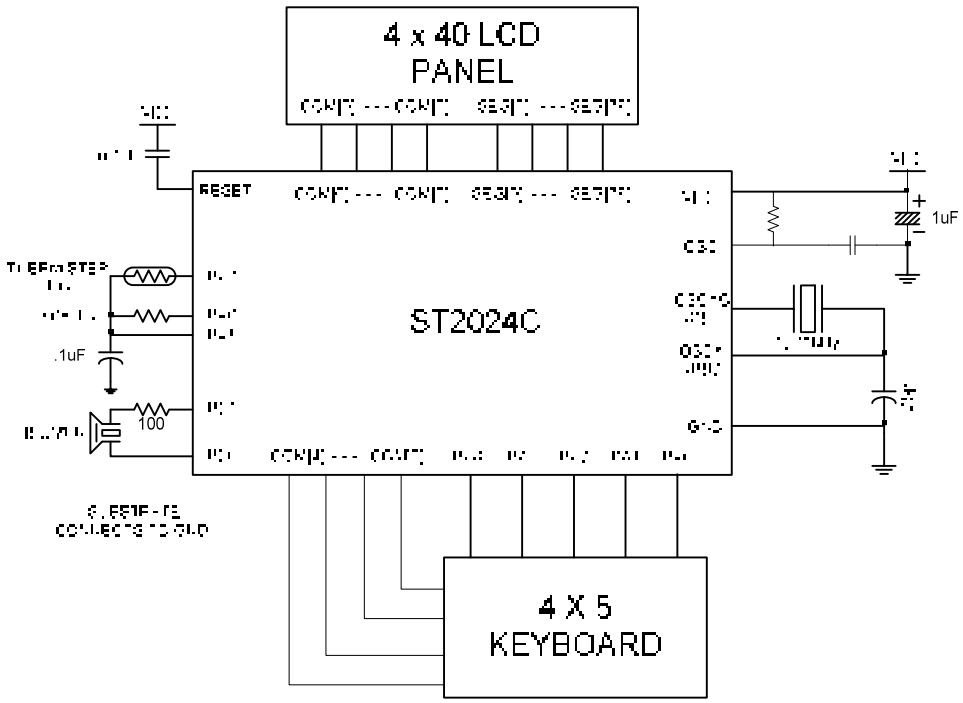
TABLE 17-39: R-Oscillator V.S. Frequency

OSCI Resistance	OSC Frequency
180 KΩ	4 MHz
425 KΩ	2 MHz
940 KΩ	1 MHz
2000 KΩ	0.5 MHz

18. APPLICATION CIRCUITS

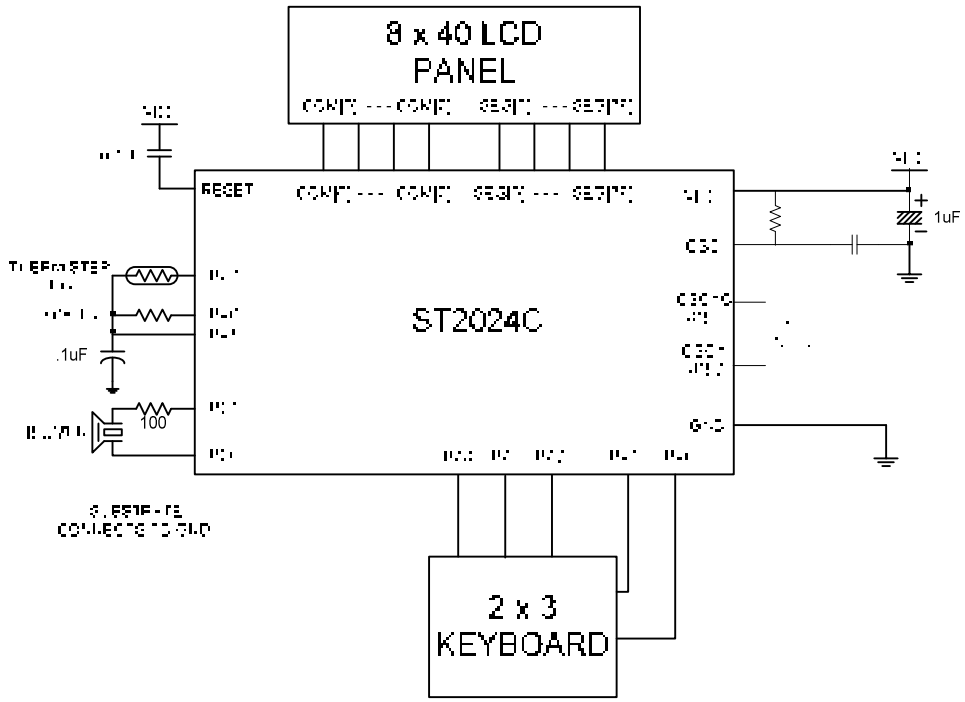
18.1 Application 1:

VDD : 3V
Clock : 32768Hz crystal and 4.0MHz R-oscillator
LCD : 1/8 duty, 1/4 bias
Input : PORT A
Output : COM4~7
ALARM : PB0, PB1
PB2,PB3…....: Crystal mode



18.2 Application 2:

VDD : 3V
Clock : 32768Hz crystal and 4.0MHz R-oscillator
LCD : 1/4 duty, 1/3 bias
I/O : PORT A
ALARM : PB0, PB1
PB2,PB3…….: Input mode



Note:

Connect one capacitor of 100PF to OSCI stabilize oscillation frequency. This capacitor must be placed close to OSCI.

ST2024C EVB PCB108

FIGURE 18-26: The PCB 108 of ST2024C EVB

ST2024C-□□□□ **checklist**	
8 bits Micro-controller with 320 ~ 144 dots LCD driver	
Operation Voltage	□ 2.4V ~ 3.6V
Oscillator	□ OSC： MHz.（ROSC = KΩ）
Power Down mode	□ WAI-0 □ WAI-1 □ STP
LCD Panel Size：_____ X _____ dot; _____ X _____mm	
LCD Driving: LEVEL _____ (1~32) LCD Contrast : LEVEL _____	
LCD Frame Rate : □ OSCX / 512 □ OSC / _____(note: Must check item25,26)	
Port-B[2~3] Option	□ Input Pin □32768Hz Crystal
COM[4~7] Option	□ LCD Common □ Open Drain Output
SEG[0~3] Option	□ LCD Common □ Open Drain Output
ST2024C EVB	PCB □□□
Program file： .hex	Date（Y/M/D）： / /
E.V. Board bios version：	Specification version：
Check sum（See appendix）：	
Appendix： Convert mask code into Intel HEX from A000h ~ FFFFh Use EPROM writer and Select EPROM device 27512 Fill memory buffer with “FFh” Load .hex file of customer code Read check sum value Function must be checked on emulation board. Electrical characteristics of emulation boards are different with real chip.	
Customer	
Company Name	
Signature	
Sitronix	
FAE / SA	
Sales Signature	

Project name _____ ____ / __ /

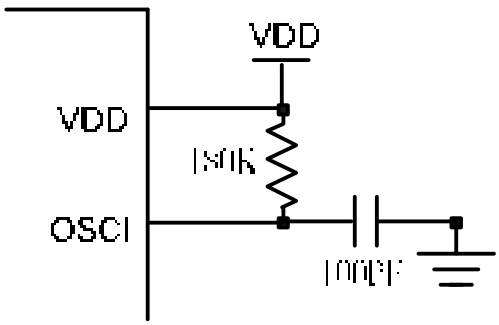
	Confirmed Item	Check	Note
1	After power on，initial user RAM and confirm control register．		
2	Confirm LCD panel's V_{OP}（contrast level）、Duty and Bias．		
3	Confirm the difference between E.V. Board and real chip（ex. V_{OP}、driving strength、F_{OSC}、power consumption、noise…etc.）		
4	Before entry power down mode，turn off un-used peripheral.（LCD driver、PSG、OSC or OSCX）		
5	Make sure power down mode work．		
6	Calculate average operating current．（Wake up time ratio）		
7	Confirm I/O directions and set pull-up for un-used input pins．		
8	For input mode with pull-up function，Please set bit 7 of port condition control register（PMCR[7]）and each bit of port data register．		
9	If use I/O for pin option，please re-configure I/O status after reading．（directions and pull-up resistor）		
10	Pay attention to"bit instructions"，because some registers have different function for read and write acting. ex. PA、PB、PRS、SYS and control register for write only．		
11	Disable un-used function's control register and put"RTI"Instruction at un-used interrupt vector．		
12	Make sure timer counting correct．		
13	Make sure temperature counting correct．		
14	Make sure software key de-bounce work．（10 ~ 50 mS）		
15	Make sure calendar counting correct．（include user setting）		
16	Make sure stack memory will not overflow．		
17	Under test mode，every functions / parts must be tested．ex. LCD、LED、speaker / buzzer、key、motor and sensor…etc.		
18	Please use same parts when developing and producing．		
19	Please select general parts for production.		
20	When testing，write every unusual situation down and find out the reasons indeed.		
21	Make sure the program accept un-normal operatings and system will not hold or crash down．		
22	When you set I/O port as input mode，please make sure signal level stable before reading．ex. When key scan，please delay 12 uS then get key code．		
23	Make sure LCD contrast is controlled by LCTL[3~0].		
24	If PSG output (PB0 & PB1) wiring a buzzer or speaker, set it to output high even the PSG isn't working.		
25	Make sure resister of R-OSC on EV-Chip matches desired frequency and equals the crytal on EV-Board.		
26	If LCD clock source is from R-OSC, LCD will have no clock in WAI1 and can't display.		
27	Always disable interrupt function(by an " SEI " instruction) when modify the IENAL,IENAH,IREQL and IREQH register		
28	After Power on ,enter wait 0 mode 0.5s before normal operation		

Special Notice

Confirmed Item		Check	Note
Special Notice 1			
1	The 32-level LCD driving strength is controlled by XLCD[1]、LCTL[4] and LCK[5~3]. Select one setting suitable for the panel size.		
2	Checking the current source clock of LCD frame rate which is different from old version. Frame rate should be around 64Hz.		
Special Notice 2			
1	Do not use 32768HZ as system clock.		

Engineer _____ **Manager** _____

Application Circuit：



Note:

Connect one capacitor of 100PF to OSCI stabilize oscillation frequency. This capacitor must be placed close to OSCI.

19. REVISES

Version2.1 Page52 Add system clock regulation in Special Notice 2
Page22 Modify SYS [XSEL] in Table of SYSTEM CONTROL REGISTER……2007/9/12

Version2.0 Page24 Modify description figure 11-6 to 12-6.
Page49 Add PCB 108 of ST2024C EVB photo
Page50 Add checklist for customer to confirm ST2024C EVB PCB number ……2007/5/21

Version1.9
Page22,23 Change register SYS bit4 TEST to Test bit and must be set "0"
Page41, Modify driving strength level 0~31 in heavy mode
Page48, Modify standby current 1~5 in heavy mode
Page50, Remove Item 28 normal mode in checklist……2006/8/1

Version 1.8 Page 1 Add CPU clock 250K ~ 2M Hz…… 2006/6/23

Version 1.7 Page51 Add checklist item 29=>after Power on ,enter wait 0 mode 0.5s before normal operation……2006/5/8

Version 1.6 Page45 modify oscillation start time to OSCX heavy start time
Page49/5051 add checklist……..2006/02/08

Version 1.5 Page 1 remove IR remote controller
Page 28/31/33/34 take off PSG/DAC clock source from oscx
Page36 modify Two-Pin Two Ended Mode Application Circuit
Page12 add pad number and note: all of unused input pins should be pulled up to minimize standby current……2005/11/8

Version 1.4
Page 22 OSCX work under heavy load mode to support more kinds of 32KHz crystals
Page 41 Add a note about LCD display quality ……2004/4/7

Version E1.0 Page41 Adding Measure Condition on TABLE 15-34:
Page 45 Modifying DC Characteristic
Page 47/48 Modifying Application Circuit (1000P→100P)……2003/8/4

Version E0.6 Page45 Modifying FIGURE 17-25: TABLE 17-39:
Page1 Modifying operation voltage 2.4V~3.4V to 2.4V~3.6V ……2003/4/16

Version E0.5 Page1 Modifying operation voltage 2.4V~5.2V to 2.4V~3.2V
Page19/20 Modifying SEGs & COMs output HIGH to FLOAT.
Page47/48 Modifying application circuit……2003/4/4

Version E0.4 -Page40 Filling the LCD power consumption table TABLE 15-34: .
-Page44 Filling the Power consumption table
-Page45 Adding, FIGURE 17-25: ……2003/2/25

Version E0.3 -Page3 Adding pad location
-Page48 Adding bonding description
-Page41 Modify **LCK[2:0]** of TABLE 15-34: ……2002/12/10

Version E0.2 -Page40 Modify the register **LCK[2:0]**……2002/10/11

Version E0.1 -Page8 Added DRV[ ] of LCD driving strength in address20H.
-Page40 Added DRV[ ] of LCD driving strength in address20H & Modify TABLE 15-34: …… 2002/9/2

ST2024C is modified from ST2024