

SSD1325

Advance Information

128 x 80, 16 Gray Scale Dot Matrix OLED/PLED Segment/Common Driver with Controller

This document contains information on a new product. Specifications and information herein are subject to change without notice.

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SSD1325

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1 GENERAL DESCRIPTION

SSD1325 is a single-chip CMOS OLED/PLED driver with controller for organic/polymer light emitting diode dot-matrix graphic display system. It consists of 208 high voltage/current driving output pins for driving 128 segments and 80 commons. This IC is designed for Common Cathode type OLED/PLED panel.

SSD1325 displays data directly from its internal 128x80x4 bits Graphic Display Data RAM (GDDRAM). Data/Commands are sent from general MCU through the hardware selectable 6800-/8080-series compatible Parallel Interface or Serial Peripheral Interface.

It has a 128-step contrast control and a 16 gray level control. The embedded on-chip oscillator and DC-DC voltage converter reduce the number of external components.

2 FEATURES

- Support max. 128 x 80 matrix panel
- Power supply: $V_{DD}=2.4V - 3.5V$
 $V_{CC}=8.0V - 16.0V$
- For matrix display:
 - OLED driving output voltage, 14V maximum
 - Can output maximum segment source current: 300uA
 - Common maximum sink current: 40mA
- Embedded 128 x 80 x 4 bit SRAM display memory
- 128 step contrast current control on monochrome passive OLED panel
- 16 gray scale
- Internal Oscillator
- Programmable Frame Rate
- 8-bit 6800-series Parallel Interface, 8080-series Parallel Interface, Serial Peripheral Interface.
- Row re-mapping and Column re-mapping
- Low power consumption (<5.0uA @sleep mode)
- Wide range of operating temperature: -40 to 85 °C

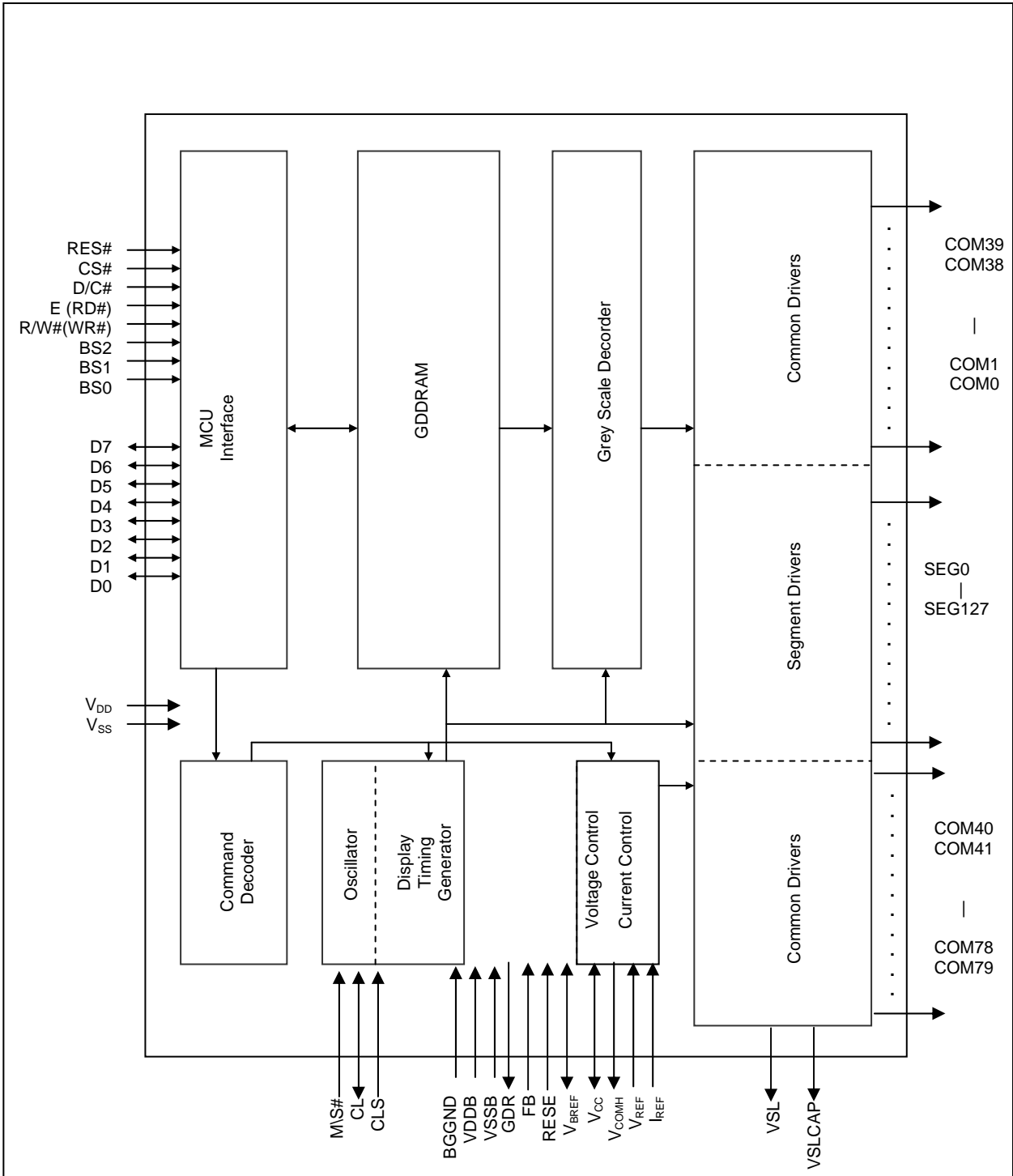
3 ORDERING INFORMATION

Table 1 : Ordering Information

Ordering Part Number	SEG	COM	Package Form	Reference	Remarks
SSD1325Z	128	80	COG	Page 8, 57	<ul style="list-style-type: none">• Min SEG pad pitch: 52.2um• Min COM pad pitch: 51.8um
SSD1325T6R1	128	80	TAB	Page 58	<ul style="list-style-type: none">• 8-bit 80 / 68 / SPI interface• Output lead pitch: 0.12mm x 0.998 = 0.11976mm• 4 SPH, 35m film• Full resolution 128 x 80

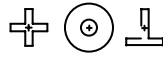
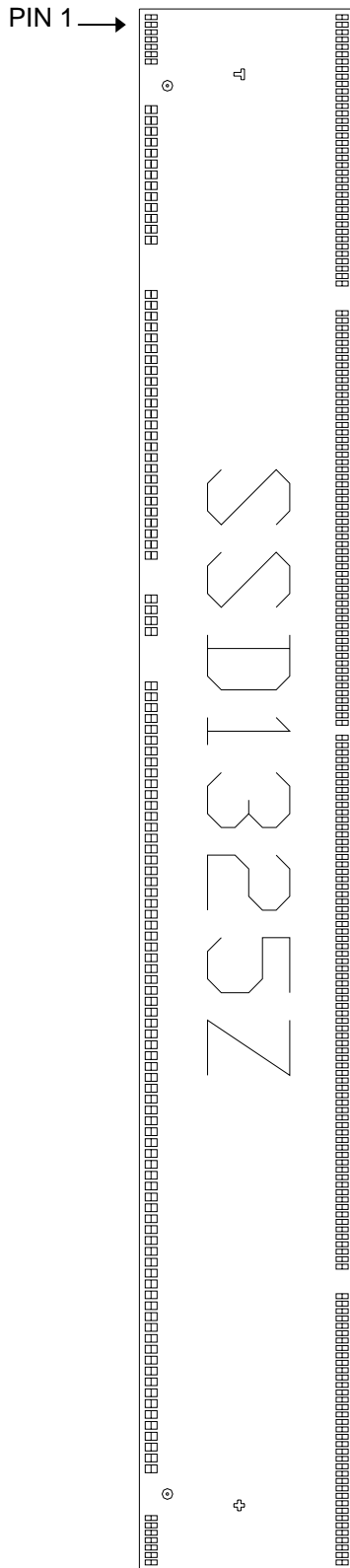
4 BLOCK DIAGRAM

Figure 1 : SSD1325 Block Diagram



5 DIE PAD FLOOR PLAN

Figure 2 : SSD1325Z Die Drawing



Note

¹ + represents the centre of the alignment mark

Alignment Mark	X-pos (µm)	Y-pos (µm)
o Shape	4934.100	-557.675
	-4934.100	-557.675
+ shape	5014.100	-52.200
T shape	-5014.100	-52.200

Die Size	10924µm x 1508µm
Die Thickness	457 +/- 25µm
I/O pad pitch	76.2µm
SEG pad pitch	52.2µm
COM pad pitch	51.8µm
Bump Height	Nominal 18µm

Bump size	X (µm)	Y (µm)
Pad 1-7,123-331	34	84
Pad 8-122	54	84

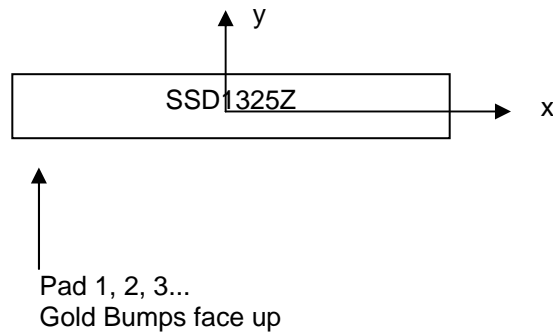
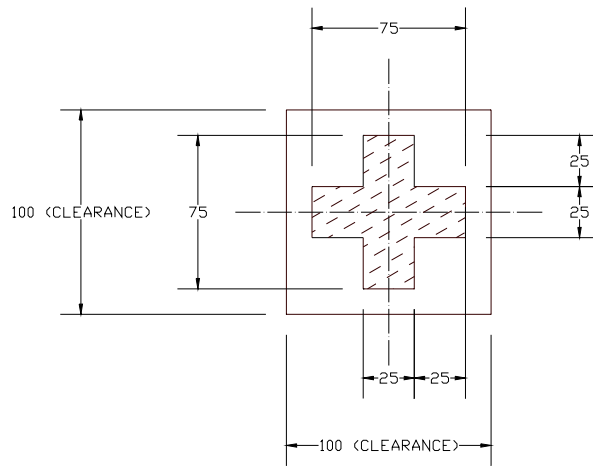
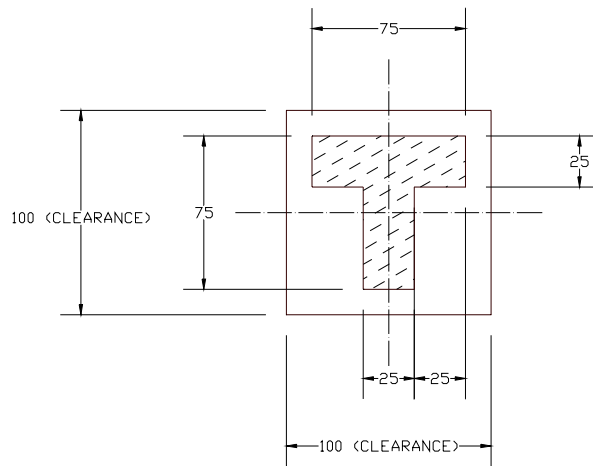


Figure 3 : SSD1325Z Alignment Mark Dimensions



6 PIN ARRANGEMENT

6.1 SSD1325T6R1 pin assignment

Figure 4 : SSD1325T6R1 Pin Assignment

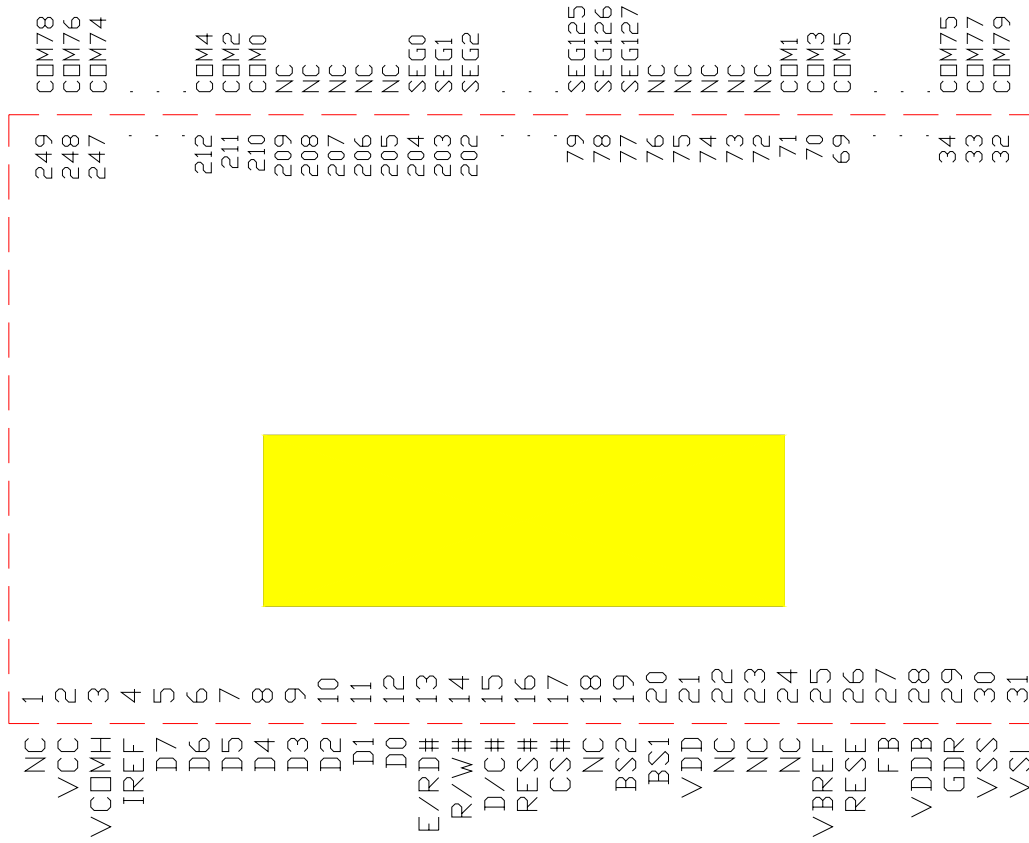


Table 3: SSD1325T6R1 TAB Pin assignment Table

PIN NO.	PIN NAME	PIN NO.	PIN NAME	PIN NO.	PIN NAME	PIN NO.	PIN NAME
1	NC	81	SEG125	161	SEG43	241	COM62
2	VCC	82	SEG122	162	SEG42	242	COM64
3	VCOMH	83	SEG121	163	SEG41	243	COM66
4	IREF	84	SEG120	164	SEG40	244	COM68
5	D7	85	SEG119	165	SEG39	245	COM70
6	D6	86	SEG118	166	SEG38	246	COM72
7	D5	87	SEG117	167	SEG37	247	COM74
8	D4	88	SEG116	168	SEG36	248	COM76
9	D3	89	SEG115	169	SEG35	249	COM78
10	D2	90	SEG114	170	SEG34		
11	D1	91	SEG113	171	SEG33		
12	D0	92	SEG112	172	SEG32		
13	E/RD#	93	SEG111	173	SEG31		
14	R/W#	94	SEG110	174	SEG30		
15	D/C#	95	SEG109	175	SEG29		
16	RES#	96	SEG108	176	SEG28		
17	CS#	97	SEG107	177	SEG27		
18	NC	98	SEG106	178	SEG26		
19	BS2	99	SEG105	179	SEG25		
20	BS1	100	SEG104	180	SEG24		
21	VDD	101	SEG103	181	SEG23		
22	NC	102	SEG102	182	SEG22		
23	NC	103	SEG101	183	SEG21		
24	NC	104	SEG100	184	SEG20		
25	VBREF	105	SEG99	185	SEG19		
26	RESE	106	SEG98	186	SEG18		
27	FR	107	SEG97	187	SEG17		
28	VDDDB	108	SEG96	188	SEG16		
29	GDR	109	SEG95	189	SEG15		
30	VSS	110	SEG94	190	SEG14		
31	VSL	111	SEG93	191	SEG13		
32	COM9	112	SEG92	192	SEG12		
33	COM7	113	SEG91	193	SEG11		
34	COM5	114	SEG90	194	SEG10		
35	COM3	115	SEG89	195	SEG9		
36	COM1	116	SEG88	196	SEG8		
37	COM9	117	SEG87	197	SEG7		
38	COM67	118	SEG86	198	SEG6		
39	COM65	119	SEG85	199	SEG5		
40	COM63	120	SEG84	200	SEG4		
41	COM61	121	SEG83	201	SEG3		
42	COM59	122	SEG82	202	SEG2		
43	COM57	123	SEG81	203	SEG1		
44	COM55	124	SEG80	204	SEG0		
45	COM53	125	SEG79	205	NC		
46	COM51	126	SEG78	206	NC		
47	COM49	127	SEG77	207	NC		
48	COM47	128	SEG76	208	NC		
49	COM45	129	SEG75	209	NC		
50	COM43	130	SEG74	210	COM0		
51	COM41	131	SEG73	211	COM2		
52	COM39	132	SEG72	212	COM4		
53	COM37	133	SEG71	213	COM6		
54	COM35	134	SEG70	214	COM8		
55	COM33	135	SEG69	215	COM10		
56	COM31	136	SEG68	216	COM12		
57	COM29	137	SEG67	217	COM14		
58	COM27	138	SEG66	218	COM16		
59	COM25	139	SEG65	219	COM18		
60	COM23	140	SEG64	220	COM20		
61	COM21	141	SEG63	221	COM22		
62	COM19	142	SEG62	222	COM24		
63	COM17	143	SEG61	223	COM26		
64	COM15	144	SEG60	224	COM28		
65	COM13	145	SEG59	225	COM30		
66	COM11	146	SEG58	226	COM32		
67	COM9	147	SEG57	227	COM34		
68	COM7	148	SEG56	228	COM36		
69	COM5	149	SEG55	229	COM38		
70	COM3	150	SEG54	230	COM40		
71	COM1	151	SEG53	231	COM42		
72	NC	152	SEG52	232	COM44		
73	NC	153	SEG51	233	COM46		
74	NC	154	SEG50	234	COM48		
75	NC	155	SEG49	235	COM50		
76	NC	156	SEG48	236	COM52		
77	SEG127	157	SEG47	237	COM54		
78	SEG126	158	SEG46	238	COM56		
79	SEG125	159	SEG45	239	COM58		
80	SEG124	160	SEG44	240	COM60		

7 PIN DESCRIPTION

Key:

I = Input	NC = Not Connected
O = Output	Pull LOW = Connect to Ground
IO = Bi-directional (input/output)	Pull HIGH = Connect to V _{DD}
P = Power pin	

Table 4: Pin Descriptions

Pin Name	Pin Type	Description																
RES#	I	This pin is reset signal input. When the pin is LOW, initialization of the chip is executed. Keep this pin HIGH during normal operation.																
CS#	I	This pin is the chip select input. The chip is enabled for MCU communication only when CS# is pulled LOW.																
D/C#	I	This pin is Data/Command control pin. When the pin is pulled HIGH, the data at D[7:0] is treated as data. When the pin is pulled LOW, the data at D[7:0] will be transferred to the command register. For detail relationship to MCU interface signals, please refer to the Timing Characteristics Diagrams in Figure 36 to Figure 39.																
E (RD#)	I	This pin is MCU interface input. When interfacing to a 6800-series microprocessor, this pin will be used as the Enable (E) signal. Read/write operation is initiated when this pin is pulled HIGH and the chip is selected. When connecting to an 8080-microprocessor, this pin receives the Read (RD#) signal. Data read operation is initiated when this pin is pulled LOW and the chip is selected.																
R/W# (WR#)	I	This pin is MCU interface input. When interfacing to a 6800-series microprocessor, this pin will be used as Read/Write (R/W#) selection input. Read mode will be carried out when this pin is pulled HIGH and write mode will be carried out when LOW. When 8080 interface mode is selected, this pin will be the Write (WR#) input. Data write operation is initiated when this pin is pulled LOW and the chip is selected.																
D[7:0]	IO	These pins are 8-bit bi-directional data bus to be connected to the microprocessor's data bus. When serial mode is selected, D1 will be the serial data input SDIN and D0 will be the serial clock input SCLK.																
BS[2:0]	I	These pins are MCU bus interface selection. Table 5 : Bus Interface selection <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th></th> <th>6800-parallel interface (8 bit)</th> <th>8080-parallel interface (8 bit)</th> <th>Serial interface</th> </tr> </thead> <tbody> <tr> <td>BS0</td> <td>0</td> <td>0</td> <td>0</td> </tr> <tr> <td>BS1</td> <td>0</td> <td>1</td> <td>0</td> </tr> <tr> <td>BS2</td> <td>1</td> <td>1</td> <td>0</td> </tr> </tbody> </table> Note ⁽¹⁾ 0 is connected to V _{SS} ⁽²⁾ 1 is connected to V _{DD}		6800-parallel interface (8 bit)	8080-parallel interface (8 bit)	Serial interface	BS0	0	0	0	BS1	0	1	0	BS2	1	1	0
	6800-parallel interface (8 bit)	8080-parallel interface (8 bit)	Serial interface															
BS0	0	0	0															
BS1	0	1	0															
BS2	1	1	0															
V _{DD}	P	This is a power supply pin. It must be connected to external source.																
V _{SS}	P	This is a ground pin. It also acts as ground reference for the logic pins. It must be connected to external ground.																
CL	IO	This pin is the system clock input. When internal oscillator is disabled (i.e. CLS is pulled LOW), this pin receives display clock signal from external clock source. When internal																

Pin Name	Pin Type	Description
		clock is enabled (i.e. CLS is pulled HIGH), this pin should be kept NC and left open.
CLS	I	This is the internal clock enable pin. When this pin is pulled HIGH, internal oscillator is selected. The internal clock will be disabled when it is pulled LOW, an external clock source must be connected to CL pin for normal operation.
V _{CC}	P	This pin is the most positive voltage supply of the chip. It is supplied by external high voltage source.
V _{COMH}	P	A capacitor should be connected between this pin and V _{SS} . No external power supply is allowed to connect to this pin.
I _{REF}	I	This pin is the segment output current reference pin. I _{SEG} is derived from I _{REF} . A resistor should be connected between this pin and V _{SS} to maintain the current around 10uA.
COM0 ~ COM79	O	These pins provide the Common switch signals to the OLED panel. These pins are in high impedance state when display is OFF.
SEG0 ~ SEG127	O	These pins provide the OLED segment driving signals. These pins are in high impedance state when display is OFF.
V _{REF}	P	This pin is the voltage reference for the pre-charge voltage in driving OLED device. Voltage should be set matching with the OLED driving voltage in the current drive phase. It can be either supplied externally or connected to V _{CC} .
VCL	O	This is the output pin for the voltage output low level for COM signals. This pin should be connected to V _{SS} .
VSL	O	This is the output pin for the voltage output low level for SEG signals. This pin can be kept NC or connected with a capacitor to V _{SS} for stability. Refer to command BFh for VSL pin connection details.
VSLCAP	O	This is a reserved pin. It has to be kept NC and left open.
M/S#	I	This pin is an input pin and must be pulled HIGH to enable the chip function.
VDDDB	P	This is a reserved pin. It should be connected to V _{DD} .
VSSB	P	This is a reserved pin. It should be connected to V _{SS} .
GDR	O	This is a reserved pin. It should be kept NC.
RESE	I	This is a reserved pin. It should be kept NC.
FB	I	This is a reserved pin. It should be kept NC.
VBREF	I	This is an internal voltage reference pin. It should be kept NC and left open.
FR	-	It is No Connection pin. It should be kept NC and left open.
DOF#	-	It is No Connection pin. It should be kept NC and left open.
GPIO0	IO	This is a reserved pin. It should be kept NC and left open.
GPIO1	IO	This is a reserved pin. It should be kept NC and left open.

Pin Name	Pin Type	Description
TR[8:0]	-	This is a reserved pin. It should be kept NC and left open.
ICAS	-	This is a reserved pin. It should be kept NC and left open.

8 FUNCTIONAL BLOCK DESCRIPTIONS

8.1 MPU Interface selection

SSD1325 MCU interface consist of 8 data pins and 5 control pins. The pin assignment at different interface mode is summarized in Table 6. Different MCU mode can be set by hardware selection on BS[2:0] pins (please refer to Table 5 for BS[2:0] setting).

Table 6 : MCU interface assignment under different bus interface mode

Pin Name Bus Interface	Data/Command Interface								Control Signal				
	D7	D6	D5	D4	D3	D2	D1	D0	E	R/W#	CS#	D/C#	RES#
8-bit 8080	D[7:0]								RD#	WR#	CS#	D/C#	RES#
8-bit 6800	D[7:0]								E	R/W#	CS#	D/C#	RES#
SPI	Tie LOW				NC	SDIN	SCLK	Tie LOW		CS#	D/C#	RES#	

8.1.1 MPU Parallel 6800-series Interface

The parallel interface consists of 8 bi-directional data pins (D[7:0]), R/W#, D/C#, E and CS#.

A LOW in R/W# indicates WRITE operation and HIGH in R/W# indicates READ operation.

A LOW in D/C# indicates COMMAND read/write and HIGH in D/C# indicates DATA read/write.

The E input serves as data latch signal while CS# is LOW. Data is latched at the falling edge of E signal.

Table 7: Control pins of 6800 interface

Function	E	R/W#	CS#	D/C#
Write command	↓	L	L	L
Read status	↓	H	L	L
Write data	↓	L	L	H
Read data	↓	H	L	H

Note

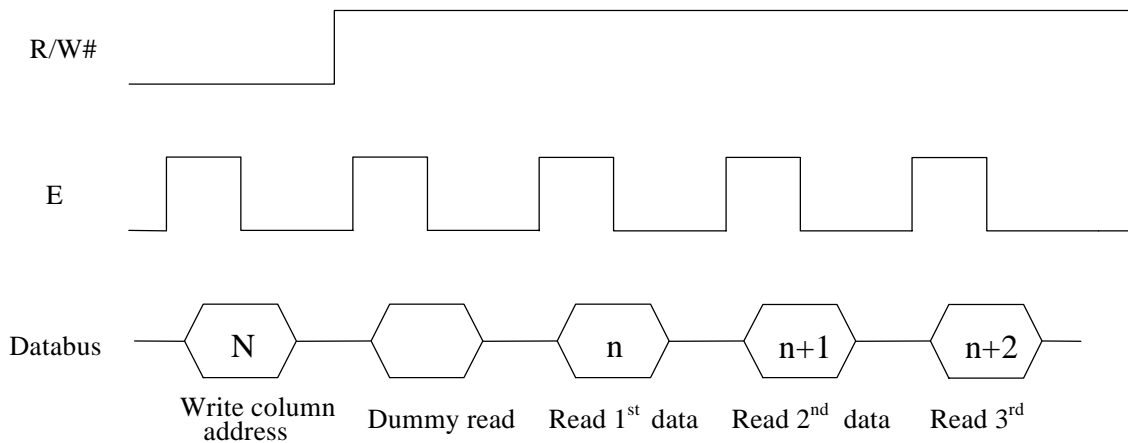
⁽¹⁾↓ stands for falling edge of signal

H stands for HIGH in signal

L stands for LOW in signal

In order to match the operating frequency of display RAM with that of the microprocessor, some pipeline processing is internally performed which requires the insertion of a dummy read before the first actual display data read. This is shown in Figure 5.

Figure 5 : Data read back procedure - insertion of dummy read



8.1.2 MPU Parallel 8080-series Interface

The parallel interface consists of 8 bi-directional data pins (D[7:0]), RD#, WR#, D/C# and CS#.

A LOW in D/C# indicates COMMAND read/write and HIGH in D/C# indicates DATA read/write.

A rising edge of RD# input serves as a data READ latch signal while CS# is kept LOW.

A rising edge of WR# input serves as a data/command WRITE latch signal while CS# is kept LOW.

Figure 6 : Example of Write procedure in 8080 parallel interface mode

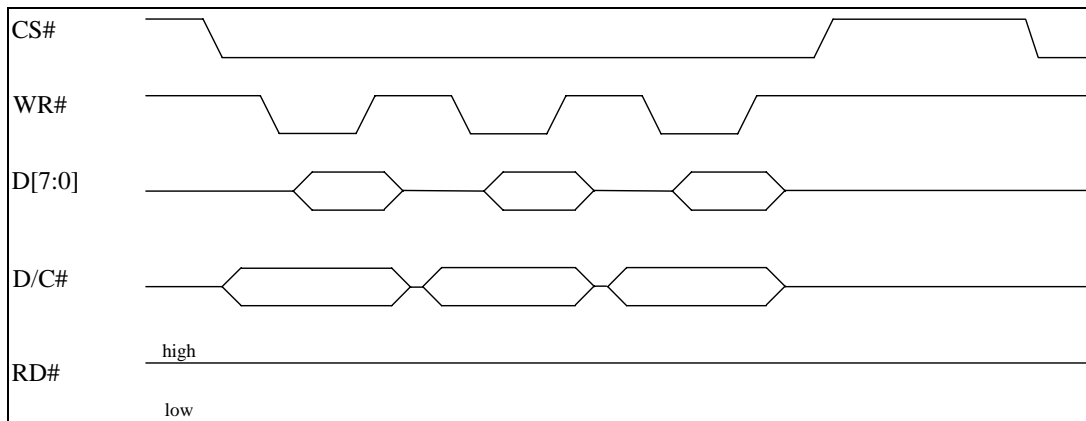


Figure 7 : Example of Read procedure in 8080 parallel interface mode

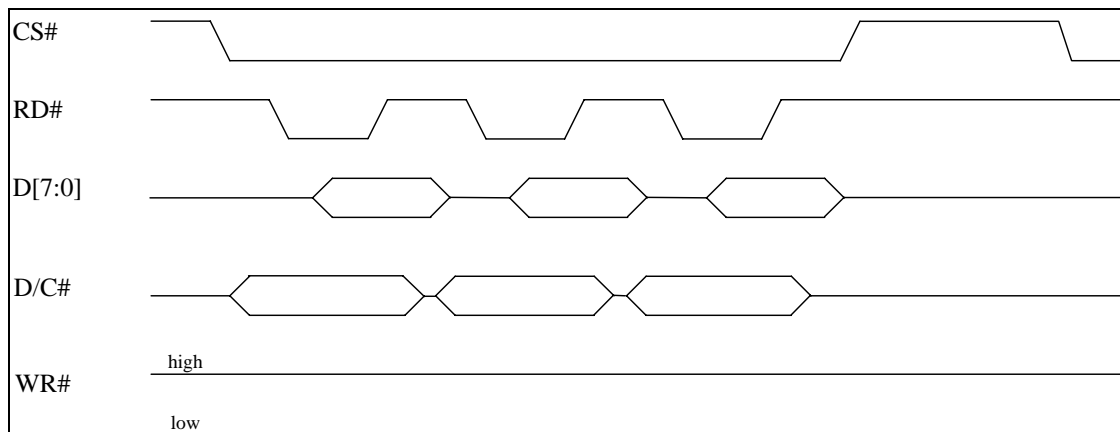


Table 8: Control pins of 8080 interface (Form 1)

Function	RD#	WR#	CS#	D/C#
Write command	H	↑	L	L
Read status	↑	H	L	L
Write data	H	↑	L	H
Read data	↑	H	L	H

Note

- (1) ↑ stands for rising edge of signal
- (2) H stands for HIGH in signal
- (3) L stands for LOW in signal
- (4) Refer to Figure 37 for Form 1 8080-Series MPU Parallel Interface Timing Characteristics

Alternatively, RD# and WR# can be keep stable while CS# serves as the data/command latch signal.

Table 9: Control pins of 8080 interface (Form 2)

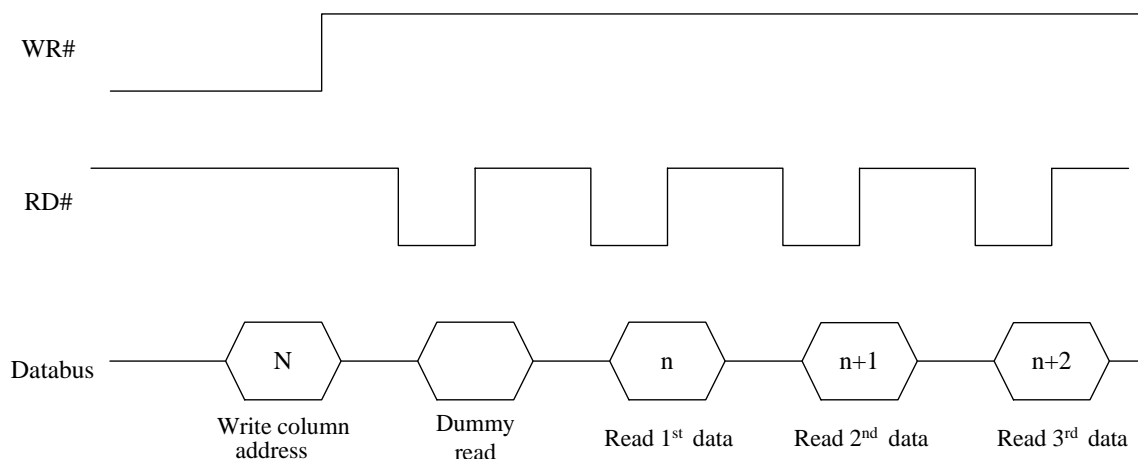
Function	RD#	WR#	CS#	D/C#
Write command	H	L	↑	L
Read status	L	H	↑	L
Write data	H	L	↑	H
Read data	L	H	↑	H

Note

- (1) ↑ stands for rising edge of signal
- (2) H stands for HIGH in signal
- (3) L stands for LOW in signal
- (4) Refer to Figure 38 for Form 2 8080-Series MPU Parallel Interface Timing Characteristics

In order to match the operating frequency of display RAM with that of the microprocessor, some pipeline processing is internally performed which requires the insertion of a dummy read before the first actual display data read. This is shown in Figure 8.

Figure 8: Display data read back procedure - insertion of dummy read



8.1.3 MPU Serial Interface

The serial interface consists of serial clock SCLK, serial data SDIN, D/C#, CS#. In SPI mode, D0 acts as SCLK, D1 acts as SDIN. For the unused data pins, D2 should be left open. The pins from D3 to D7, E and R/W# can be connected to an external ground.

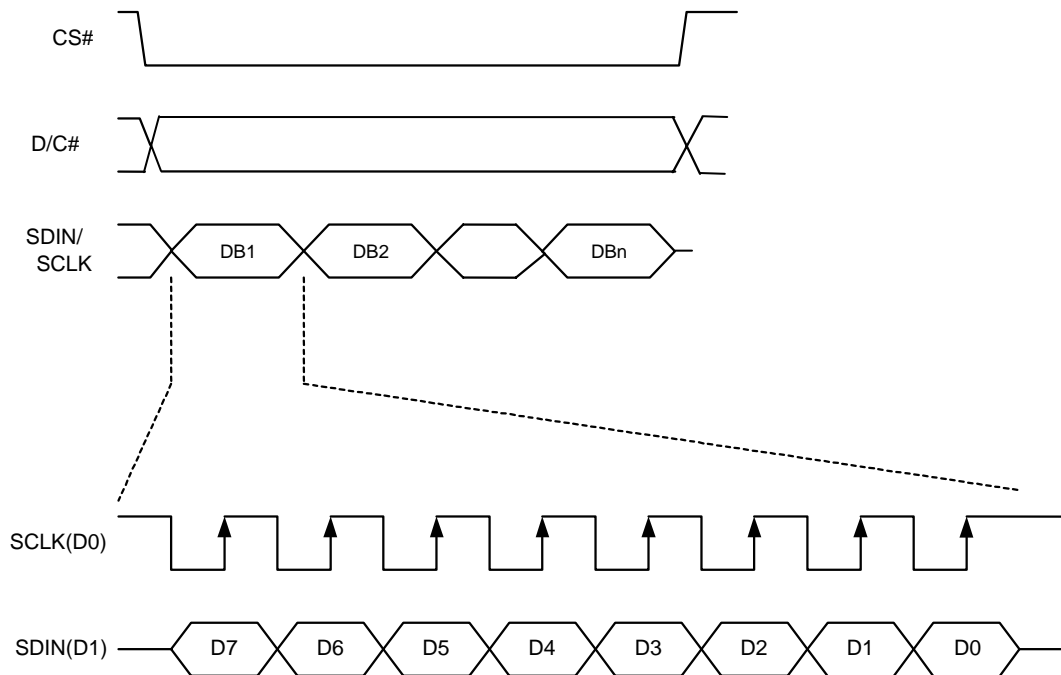
Table 10: Control pins of Serial interface

Function	E	R/W#	CS#	D/C#
Write command	Tie LOW	Tie LOW	L	L
Write data	Tie LOW	Tie LOW	L	H

SDIN is shifted into an 8-bit shift register on every rising edge of SCLK in the order of D7, D6, ... D0. D/C# is sampled on every eighth clock and the data byte in the shift register is written to the Graphic Display Data RAM (GDDRAM) or command register in the same clock.

Under serial mode, only write operations are allowed.

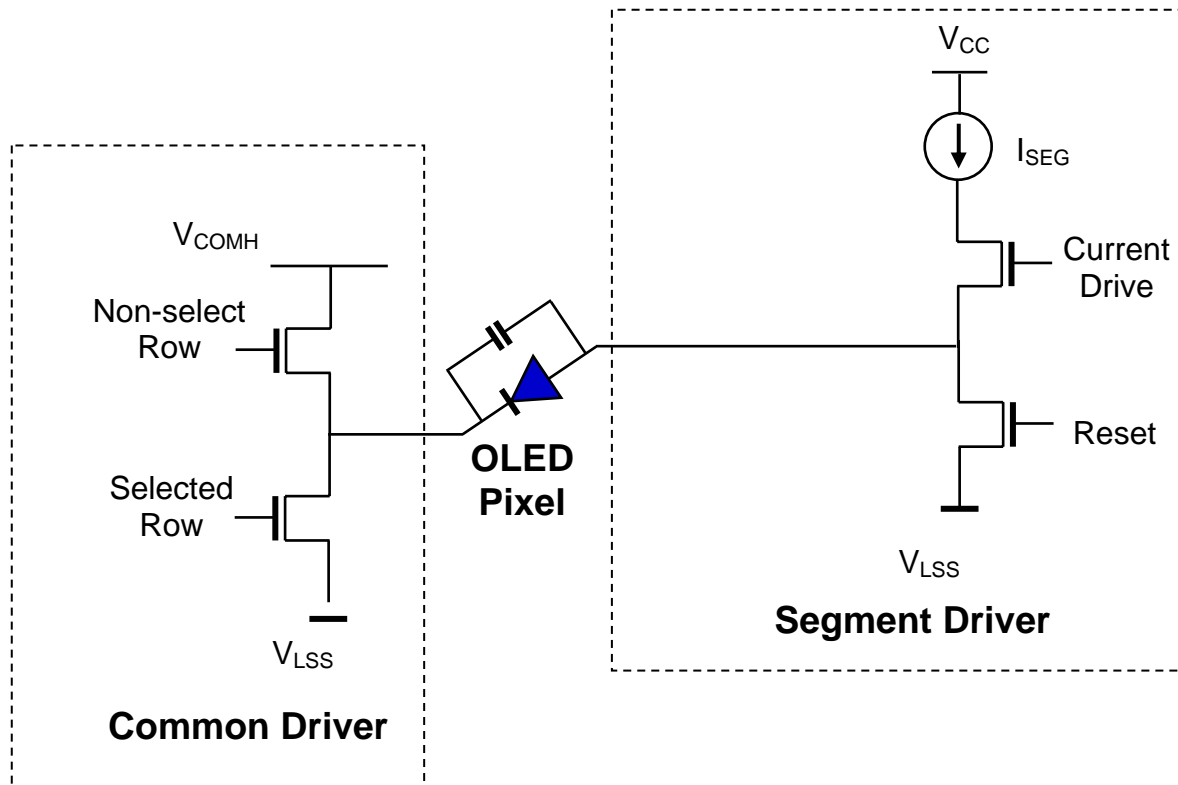
Figure 9: Display data write procedure in SPI mode



8.2 Segment Drivers/Common Drivers

Segment drivers have 128 current sources to drive OLED panel. The driving current can be adjusted from 0 to 300uA with 7 bits, 128 steps. Common drivers generate voltage scanning pulses. The block diagrams and waveforms of the segment and common driver are shown as follow.

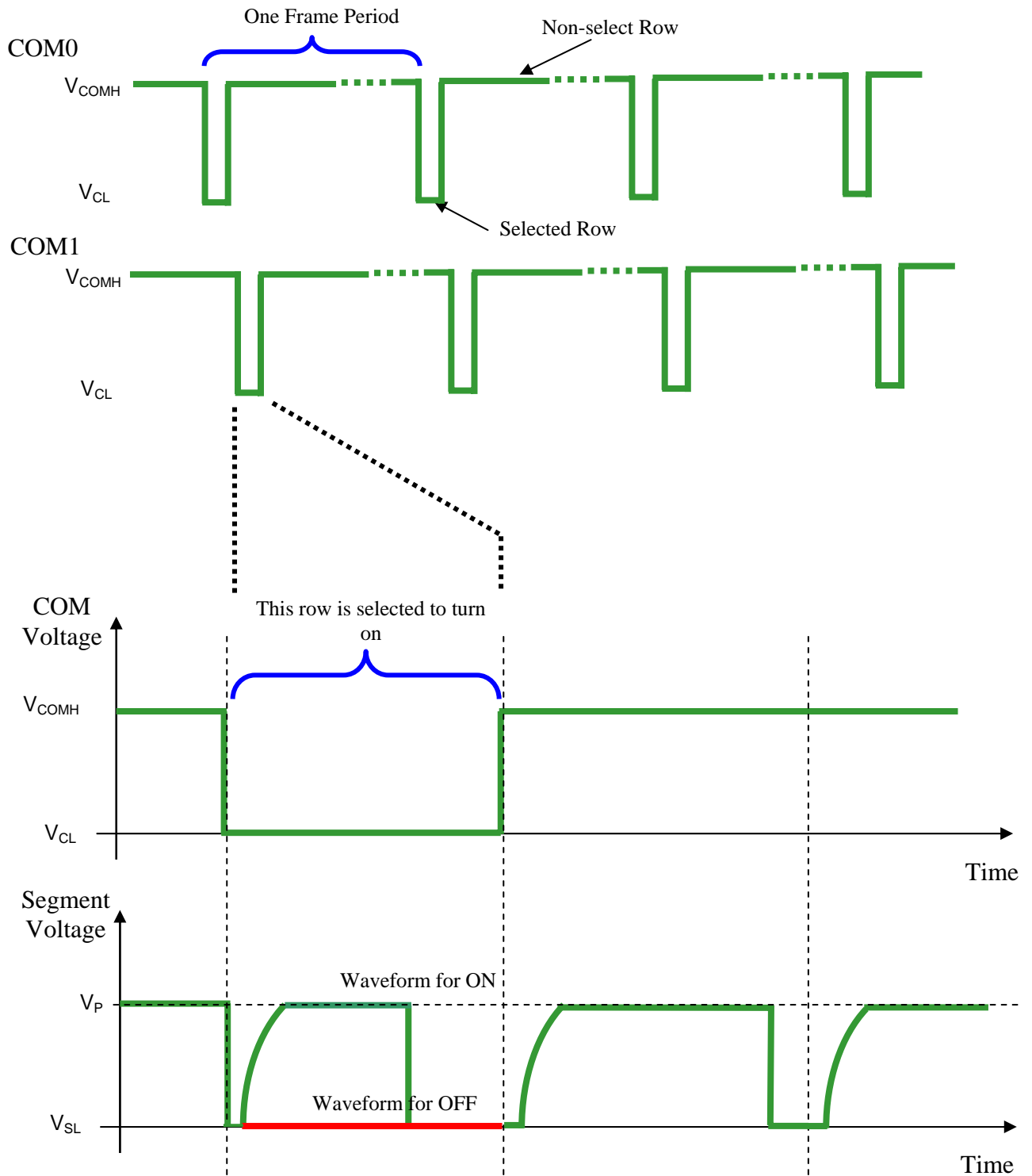
Figure 10 : Segment and Common Driver Block Diagram



The commons are scanned sequentially, row by row. If a row is not selected, all the pixels on the row are in reverse bias by driving those commons to voltage V_{COMH} as shown in Figure 11.

In the scanned row, the pixels on the row will be turned ON or OFF by sending the corresponding data signal to the segment pins. If the pixel is turned OFF, the segment current is kept at 0. On the other hand, the segment drives to I_{SEG} when the pixel is turned ON.

Figure 11 : Segment and Common Driver Signal Waveform

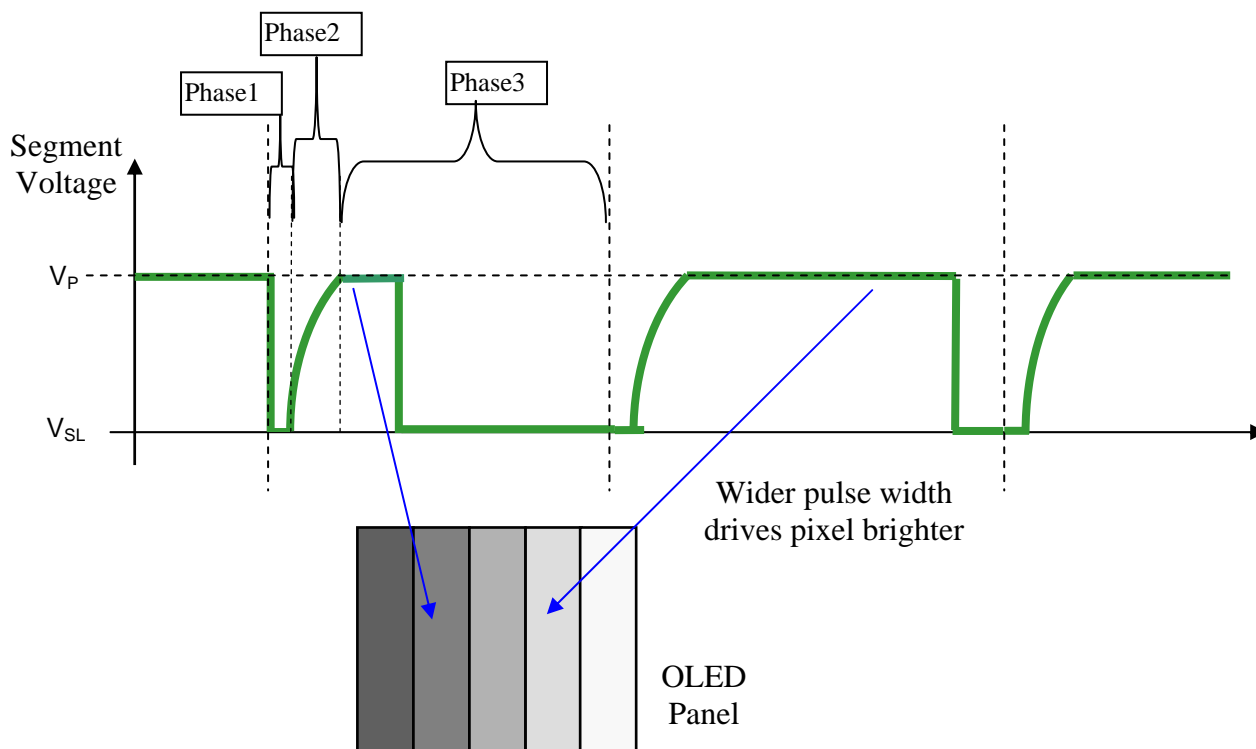


There are three phases to driving an OLED a pixel. In phase 1, the pixel is reset by the segment driver to V_{SS} in order to discharge the previous data charge stored in the parasitic capacitance along the segment electrode. The period of phase 1 can be programmed by command B1h A[3:0] from 1 to 15 DCLK. An OLED panel with larger capacitance requires a longer period for discharging.

In phase 2, pre-charge is performed. The pixel is driven to attain the corresponding voltage level V_P from V_{SS} . The amplitude of V_P can be programmed by the command BCh. The period of phase 2 can be programmed in length from 1 to 15 DCLK by command B1h A[7:4]. If the capacitance value of the pixel of OLED panel is larger, a longer period is required to charge up the capacitor to reach the desired voltage.

Last phase (phase 3 is current drive stage. The current source in the segment driver delivers constant current to the pixel. The driver IC employs PWM (Pulse Width Modulation) method to control the gray scale of each pixel individually. The wider pulse widths in the current drive stage results in brighter pixels and vice versa. This is shown in the following figure.

Figure 12 : Gray Scale Control by PWM in Segment



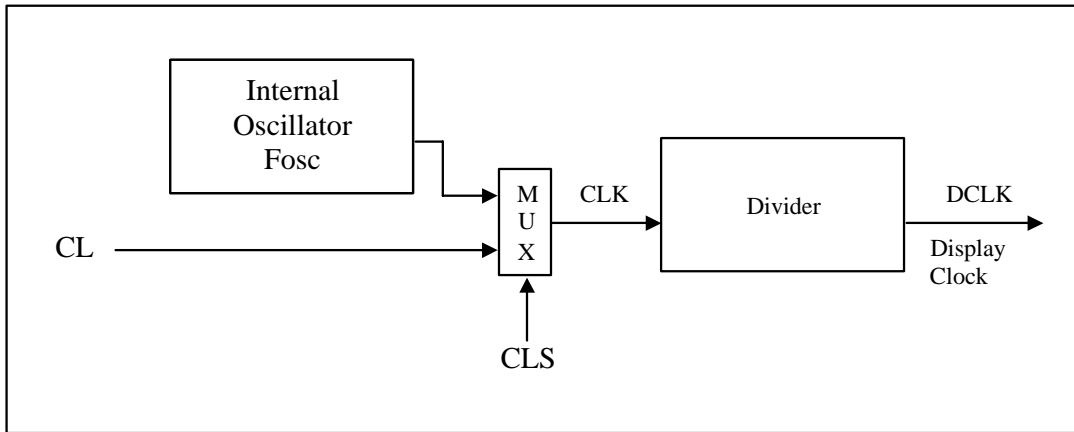
After finishing phase 3, the driver IC will go back to phase 1 to display the next row image data. This three-step cycle is run continuously to refresh image display on OLED panel.

The pulse width, which is counted from Phase 2 to Phase 3, is defined by command B8h “Set Gray Scale Table”. In the table, the gray scale is defined in incremental way, with reference to the length of previous table entry.

8.3 Oscillator Circuit and Display Time Generator

This module is an On-Chip low power RC oscillator circuitry. The operation clock (CLK) can be generated either from internal oscillator or external source CL pin. This selection is done by CLS pin. If CLS pin is pulled HIGH, internal oscillator is chosen and CL should be left open. Pulling CLS pin LOW disables internal oscillator and external clock must be connected to CL pins for proper operation. When the internal oscillator is selected, its output frequency F_{OSC} can be changed by command B3h, please refer to Table 18.

Figure 13 : Oscillator Circuit



The display clock (DCLK) for the Display Timing Generator is derived from CLK. The division factor “D” can be programmed from 1 to 16 by command B3h

$$DCLK = F_{OSC} / D$$

The frame frequency of display is determined by the following formula.

$$F_{FRM} = \frac{F_{osc}}{D \times K \times \text{No. of Mux}}$$

where

- D stands for clock divide ratio. It is set by command B3h A[3:0]. The divide ratio has the range from 1 to 16.
- K is row period. It is configured by command B2h. This value should comply with following condition.

$$K \geq \text{Phase 1} + \text{Phase 2} + \text{Phase 3} + \text{GS15}$$

- Number of multiplex ratio is set by command A8h. The power ON reset value is 4Fh.
- F_{OSC} is the oscillator frequency. It can be changed by command B3h A[7:4]. The higher the register setting results in faster frequency.

If the frame frequency is set too low, flickering may occur. On the other hand, higher frame frequency leads to higher power consumption on the whole system.

8.4 Command Decoder and Command Interface

This module determines whether the input data is interpreted as data or command. Data is interpreted based upon the input of the D/C# pin.

If D/C# pin is HIGH, the input at D_7-D_0 is written to Graphic Display Data RAM (GDDRAM). If it is LOW, the input at D_7-D_0 is interpreted as a Command which will be decoded and be written to the corresponding command register.

8.5 Reset Circuit

When RES# input is LOW, the chip is initialized with the following status:

1. Display is OFF
2. 128 x 80 Display Mode
3. Normal segment and display data column address and row address mapping (SEG0 mapped to address 00h and COM0 mapped to address 00h)
4. Shift register data clear in serial interface
5. Display start line is set at display RAM address 0
6. Column address counter is set at 0
7. Normal scan direction of the COM outputs
8. Contrast control register is set at 40h

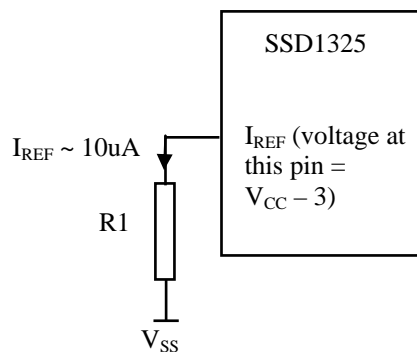
8.6 Current Control and Voltage Control

This block is used to derive the incoming power sources into the different levels of internal use voltage and current.

- V_{DD} is an external voltage supply.
- V_{CC} is the most positive external voltage supply.
- V_{COMH} is the Common deselected level. It is internally regulated.
- V_{SS} is the ground path of the analog and panel current.
- I_{REF} is a reference current source for segment current drivers I_{SEG} .

Note that V_{REF} is reference voltage, which is used to derive driving voltage for segments and commons. The magnitude of I_{REF} is controlled by the value of resistor, which is connected between I_{REF} pin and V_{SS} as shown in **Error! Reference source not found.** It is recommended to set I_{REF} to 10uA +/- 2uA so as to achieve $I_{SEG} = 300uA$ at maximum contrast 127.

Figure 14: I_{REF} Current Setting by Resistor Value



Since the voltage at I_{REF} pin is $V_{CC} - 3V$, the value of resistor R1 can be found as below.

$$R1 = (\text{Voltage at } I_{REF} - V_{SS}) / I_{REF} = (V_{CC} - 3) / 10uA \approx 910k\Omega \text{ for } V_{CC} = 12V.$$

8.7 Graphic Display Data RAM (GDDRAM)

The GDDRAM is a bit mapped static RAM holding the bit pattern to be displayed. The size of the RAM is 128x80x4 bits. For mechanical flexibility, re-mapping on both Segment and Common outputs can be selected by software. The GDDRAM address maps in

Table 11 to Table 15 show some examples on using the command “Set Re-map” A0h to re-map the GDDRAM. In the following tables, the lower nibble and higher nibble of D0, D1, D2 ... D5117, D5118, D5119 represent the 128x80 data bytes in the GDDRAM.

Table 11 shows the GDDRAM map under the following condition:

- Command “Set Re-map” A0h is set to:
 - Disable Column Address Re-map (A[0]=0)
 - Disable Nibble Re-map (A[1]=0)
 - Enable Horizontal Address Increment (A[2]=0)
 - Disable COM Re-map (A[4]=0)
- Display Start Line=00h
- Data byte sequence: D0, D1, D2 ... D5119

Table 11 : GDDRAM address map 1

		SEG0	SEG1	SEG2	SEG3		SEG124	SEG125	SEG126	SEG127	SEG Outputs Column Address (HEX)
		00		01			3E		3F		
COM0	00	D0[3:0]	D0[7:4]	D1[3:0]	D1[7:4]		D62[3:0]	D62[7:4]	D63[3:0]	D63[7:4]	
COM1	01	D64[3:0]	D64[7:4]	D65[3:0]	D65[7:4]		D126[3:0]	D126[7:4]	D127[3:0]	D127[7:4]	
COM78	4E										
COM79	4F	D5056[3:0]	D5056[7:4]	D5057[3:0]	D5057[7:4]		D5118[3:0]	D5118[7:4]	D5119[3:0]	D5119[7:4]	

COM Outputs (Display Startline=0) Row Address (HEX) Nibble re-map A[1]=0

Table 12 shows the GDDRAM map under the following condition:

- Command “Set Re-map” A0h is set to:
 - Disable Column Address Re-map (A[0]=0)
 - Disable Nibble Re-map (A[1]=0)
 - Enable Vertical Address Increment (A[2]=1)
 - Disable COM Re-map (A[4]=0)
- Display Start Line=00h
- Data byte sequence: D0, D1, D2 ... D5119

Table 12 : GDDRAM address map 2

		SEG0	SEG1	SEG2	SEG3		SEG124	SEG125	SEG126	SEG127	SEG Outputs Column Address (HEX)
		00		01			3E		3F		
COM0	00	D0[3:0]	D0[7:4]	D80[3:0]	D80[7:4]		D4960[3:0]	D4960[7:4]	D5040[3:0]	D5040[7:4]	
COM1	01	D1[3:0]	D1[7:4]	D81[3:0]	D81[7:4]		D4961[3:0]	D4961[7:4]	D5041[3:0]	D5041[7:4]	
COM78	4E										
COM79	4F	D79[3:0]	D79[7:4]	D159[3:0]	D159[7:4]		D5039[3:0]	D5039[7:4]	D5119[3:0]	D5119[7:4]	

COM Outputs (Display Startline=0) Row Address (HEX) Nibble re-map A[1]=0

Table 13 shows the GDDRAM map under the following condition:

- Command “Set Re-map” A0h is set to:
 - Enable Column Address Re-map (A[0]=1)
 - Enable Nibble Re-map (A[1]=1)
 - Enable Horizontal Address Increment (A[2]=0)
 - Disable COM Re-map (A[4]=0)
- Display Start Line=00h
- Data byte sequence: D0, D1, D2 ... D5119

Table 13 : GDDRAM address map 3

		SEG0	SEG1	SEG2	SEG3		SEG124	SEG125	SEG126	SEG127	SEG Outputs Column Address (HEX)
		3F		3E			01		00		
COM0	00	D63[7:4]	D63[3:0]	D62[7:4]	D62[3:0]		D1[7:4]	D1[3:0]	D0[7:4]	D0[3:0]	
COM1	01	D127[7:4]	D127[3:0]	D126[7:4]	D126[3:0]		D65[7:4]	D65[3:0]	D64[7:4]	D64[3:0]	
		←									
COM78	4E	D5055[7:4]	D5055[3:0]	D5054[7:4]	D5054[3:0]		D4993[7:4]	D4993[3:0]	D4992[7:4]	D4992[3:0]	
COM79	4F	D5119[7:4]	D5119[3:0]	D5118[7:4]	D5118[3:0]		D5057[7:4]	D5057[3:0]	D5056[7:4]	D5056[3:0]	
COM Outputs	Row Address (HEX)										

(Display Startline=0)

Nibble re-map A[1]=1

For vertical scrolling of the display, an internal register storing display start line can be set to control the portion of the RAM data to be mapped to the display.

Table 14 shows the example in which the display start line register is set to 10h with the following condition:

- Command “Set Re-map” A0h is set to:
 - Disable Column Address Re-map (A[0]=0)
 - Disable Nibble Re-map (A[1]=0)
 - Enable Horizontal Address Increment (A[2]=0)
 - Enable COM Re-map (A[4]=1)
- Display Start Line=10h (corresponds to COM15)
- Data byte sequence: D0, D1, D2 ... D5119

Table 14 : GDDRAM address map 4

		SEG0	SEG1	SEG2	SEG3		SEG124	SEG125	SEG126	SEG127	SEG Outputs Column Address (HEX)
		00		01			3E		3F		
COM15	0F	D0[3:0]	D0[7:4]	D1[3:0]	D1[7:4]		D62[3:0]	D62[7:4]	D63[3:0]	D63[7:4]	
COM14	0E	D64[3:0]	D64[7:4]	D65[3:0]	D65[7:4]		D126[3:0]	D126[7:4]	D127[3:0]	D127[7:4]	
		→									
COM17	11	D4992[3:0]	D4992[7:4]	D4993[3:0]	D4993[7:4]		D5054[3:0]	D5054[7:4]	D5055[3:0]	D5055[7:4]	
COM16	10	D5056[3:0]	D5056[7:4]	D5057[3:0]	D5057[7:4]		D5118[3:0]	D5118[7:4]	D5119[3:0]	D5119[7:4]	
COM Outputs	Row Address (HEX)										

(Display Startline=10H)

Nibble re-map A[1]=0

Table 15 shows the GDDRAM map under the following condition:

- Command “Set Re-map” A0h is set to:
 - Disable Column Address Re-map (A[0]=0)
 - Disable Nibble Re-map (A[1]=0)
 - Enable Horizontal Address Increment (A[2]=0)
 - Disable COM Re-map (A[4]=0)
- Display Start Line=00h
- Column Start Address=01h
- Column End Address=3Eh
- Row Start Address=01h
- Row End Address=4Eh
- Data byte sequence: D0, D1, D2 ... D4835

Table 15 : GDDRAM address map 5

		SEG0	SEG1	SEG2	SEG3		SEG124	SEG125	SEG126	SEG127	SEG Outputs Column Address (HEX)	
		00		01			3E		3F			
COM0	00											
COM1	01			D0[3:0]	D0[7:4]		D61[3:0]	D61[7:4]				
COM78	4E			D4774[3:0]	D4774[7:4]		D4835[3:0]	D4835[7:4]				
COM79	4F											
COM Outputs (Display Startline=0)	Row Address (HEX)											Nibble re-map A[1]=0

Note

- (1) Please refer to Table 18 for the details of setting command “Set Re-map”A0h.
- (2) The “Display Start Line” is set by the command “Set Display Start Line” A1h and please refer to Table 18 for the setting details
- (3) The “Column Start/End Address” is set by the command “Set Column Address” 15h and please refer to Table 18 for the setting details
- (4) The “Row Start/End Address” is set by the command “Set Row Address” 75h and please refer to Table 18 for the setting detail

8.8 Gray Scale Decoder

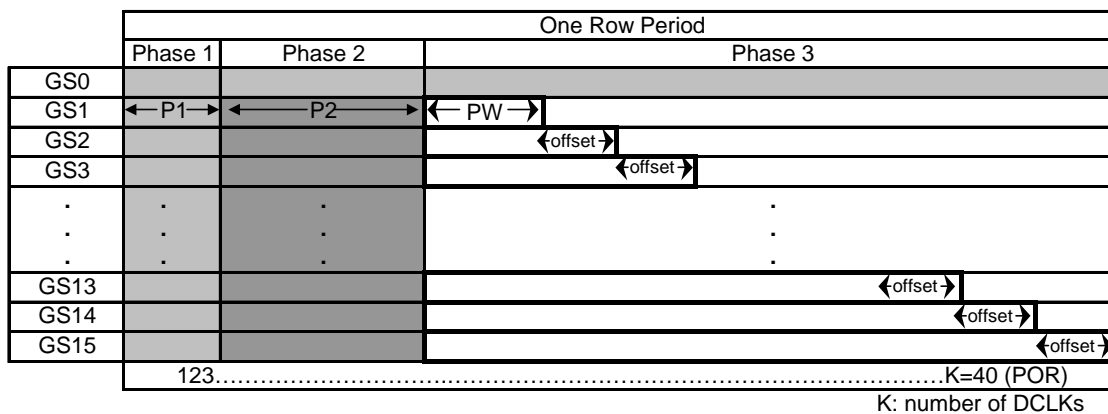
There are 16 gray levels from GS0 to GS15. The gray scale of the display is defined by the pulse width (PW) of current drive phase, GS0 has no pre-charge (phase 2) and no current drive (phase 3). Each L value represents an offset to the corresponding gray scale level. See below table and graphical representation:

Table16 : Gray scale pulse width set table

	Description	Number of DCLKs
L1	Set GS1 level Pulse Width	0-7
L2	Set GS2 level Pulse Width Offset	1-8
L3	Set GS3 level Pulse Width Offset	1-8
·	·	·
·	·	·
·	·	·
L13	Set GS13 level Pulse Width Offset	1-8
L14	Set GS14 level Pulse Width Offset	1-8
L15	Set GS15 level Pulse Width Offset	1-8

DCLK: Internal Display Clock. It is used for defining phase clock period.

Figure 15 : Gray scale pulse width set diagram



- no precharge and current drive
- Precharge
- Current Drive

Table 17 : Gray scale pulse width default values

RESET	Result
L1=1	GS1 level Pulse width=1
L2=1	GS2 level Pulse width=3
L3=1	GS3 level Pulse width=5
L4=1	GS4 level Pulse width=7
L5=1	GS5 level Pulse width=9
L6=1	GS6 level Pulse width=11
L7=1	GS7 level Pulse width=13
L8=1	GS8 level Pulse width=15
L9=1	GS9 level Pulse width=17
L10=1	GS10 level Pulse width=19
L11=1	GS11 level Pulse width=21
L12=1	GS12 level Pulse width=23
L13=1	GS13 level Pulse width=25
L14=1	GS14 level Pulse width=27
L15=1	GS15 level Pulse width=29

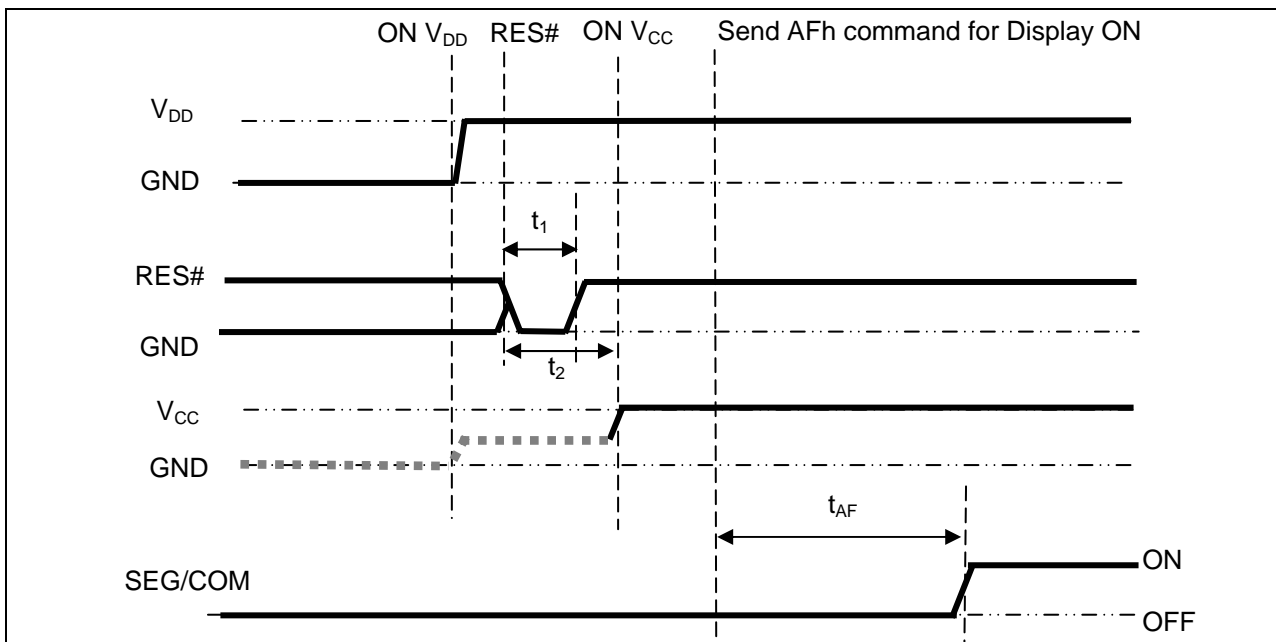
8.9 Power ON and OFF sequence

The following figures illustrate the recommended power ON and power OFF sequence of SSD1325.

Power ON sequence:

1. Power ON V_{DD} .
2. After V_{DD} become stable, set RES# pin LOW (logic LOW) for at least 3 μ s (t_1) and then HIGH (logic HIGH).
3. After set RES# pin LOW (logic LOW), wait for at least 3 μ s (t_2). Then Power ON V_{CC} .⁽¹⁾
4. After V_{CC} become stable, send command AFh for display ON. SEG/COM will be ON after 100ms (t_{AF}).

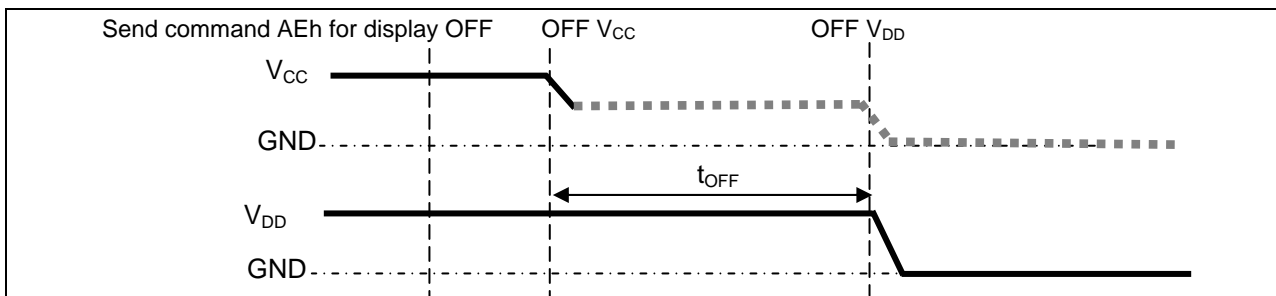
Figure 16 : The Power ON sequence



Power OFF sequence:

1. Send command AEh for display OFF.
2. Wait until panel discharges completely.
3. Power OFF V_{CC} .^{(1), (2)}
4. Wait for t_{OFF} . Power OFF V_{DD} . (where Minimum t_{OFF} =0ms, Typical t_{OFF} =100ms)

Figure 17 : The Power OFF sequence



Note:

⁽¹⁾ Since an ESD protection circuit is connected between V_{DD} and V_{CC} , V_{CC} becomes lower than V_{DD} whenever V_{DD} is ON and V_{CC} is OFF as shown in the dotted line of V_{CC} in Figure 16 and Figure 17.

⁽²⁾ V_{CC} should be kept float when it is OFF.

9 COMMAND TABLE

Table 18: Command Table

(D/C# = 0, R/W# (WR#) = 0, E (RD#) = 1) unless specific setting is stated

Fundamental Command Table											
D/C	Hex	D7	D6	D5	D4	D3	D2	D1	D0	Command	Description
0 0 0	15 A[5:0] B[5:0]	0 * *	0 * *	0 A ₅ B ₅	1 A ₄ B ₄	0 A ₃ B ₃	1 A ₂ B ₂	0 A ₁ B ₁	1 A ₀ B ₀	Set Column Address	Second command A[5:0] sets the column start address from 0-63, POR = 00h Third command B[5:0] sets the column end address from 0-63, RESET = 3Fh
0 0 0	75 A[6:0] B[6:0]	0 * *	1 A ₆ B ₆	1 A ₅ B ₅	1 A ₄ B ₄	0 A ₃ B ₃	1 A ₂ B ₂	0 A ₁ B ₁	1 A ₀ B ₀	Set Row address	Second command A[6:0]sets the row start address from 0-79, RESET = 00h Third command B[6:0] sets the row end address from 0-79, RESET = 4Fh
0 0	81 A[6:0]	1 *	0 A ₆	0 A ₅	0 A ₄	0 A ₃	0 A ₂	0 A ₁	1 A ₀	Set Contrast Current	Double byte command to select 1 out of 128 contrast steps. Contrast increases as level increase The level is set to 40h after RESET
0	84~86	1	0	0	0	0	1	X ₁	X ₀	Set Current Range	84h = Quarter Current Range (RESET) 85h = Half Current Range 86h = Full Current Range
0 0	A0 A[6:0]	1 *	0 A ₆	1 A ₅	0 A ₄	0 A ₃	0 A ₂	0 A ₁	0 A ₀	Set Re-map	A[0]=0, Disable Column Address Re-map (RESET) A[0]=1, Enable Column Address Re-map A[1]=0, Disable Nibble Re-map (RESET) A[1]=1, Enable Nibble Re-map A[2]=0, Horizontal Address Increment (RESET) A[2]=1, Vertical Address Increment A[4]=0, Disable COM Re-map disable (RESET) A[4]=1, Enable COM Re-map A[5]=0, Reserved (RESET) A[5]=1, Reserved A[6]=0, Disable COM Split Odd Even (RESET) A[6]=1, Enable COM Split Odd Even
0 0	A1 A[6:0]	1 *	0 A ₆	1 A ₅	0 A ₄	0 A ₃	0 A ₂	0 A ₁	1 A ₀	Set Display Start Line	Set display RAM display start line register from 0-79 Display start line register is reset to 00h after RESET
0 0	A2 A[6:0]	1 *	0 A ₆	1 A ₅	0 A ₄	0 A ₃	0 A ₂	1 A ₁	0 A ₀	Set Display Offset	Set vertical scroll by COM from 0-79 The value is reset to 00H after RESET
0	A4~A7	1	0	1	0	0	X ₂	X ₁	X ₀	Set Display Mode	A4h = Normal Display (RESET) A5h = Entire Display ON,

Fundamental Command Table											
D/C	Hex	D7	D6	D5	D4	D3	D2	D1	D0	Command	Description
											all pixels turns ON in GS level 15 A6h = Entire Display OFF, all pixels turns OFF A7h = Inverse Display
0 0	A8 A[6:0]	1 *	0 A ₆	1 A ₅	0 A ₄	1 A ₃	0 A ₂	0 A ₁	0 A ₀	Set Multiplex Ratio	The next command determines multiplex ratio N from 16MUX-80MUX, A[6:0] = 15 represents 16MUX A[6:0] = 16 represents 17MUX : A[6:0] = 78 represents 79MUX A[6:0] = 79 represents 80MUX
0 0	AD A[1:0]	1 *	0 *	1 *	0 *	1 *	1 *	0 1	1 A ₀	Set Master Configuration	A[0] = 0, Select external V _{CC} supply A[0] = 1, Reserved (RESET) Note (¹) Bit A[0] must be set to 0b after RESET. (²) The setting will be activated after issuing Set Display ON command (AFh)
0	AE	1	0	1	0	1	1	1	0	Set Display ON	A Eh = Display OFF (Sleep mode) (RESET)
0	AF	1	0	1	0	1	1	1	1	Set Display OFF	AFh = Display ON
0 0	B0 A[5:0]	1 *	0 *	1 A ₅	1 A ₄	0 A ₃	0 A ₂	0 A ₁	0 A ₀	Set Pre-charge Compensation Enable	A[5:0] = 08h (RESET) A[5:0] = 28h, Enable pre-charge compensation
0 0 0	B1 A[3:0] A[7:4]	1 * A ₇	0 * A ₆	1 * A ₅	1 * A ₄	0 A ₃	0 A ₂	0 A ₁	1 A ₀	Set Phase Length	A[3:0] = P1, phase 1 period of 1-15 DCLKs, RESET = 3DCLKS = 3h A[7:4] = P2, phase 2 period of 1-15 DCLKs, RESET = 5DCLKS = 5h Note (¹) 0 DCLK is invalid in phase 1 & phase 2
0 0	B2 A[7:0]	1 A ₇	0 A ₆	1 A ₅	1 A ₄	0 A ₃	0 A ₂	1 A ₁	0 A ₀	Set Row Period (set frame frequency)	The next command sets the number of DCLKs, K, per row between 2-158 DCLKS RESET = 37DCLKS = 25h The K value should be set as K = P1+P2+GS15 pulse width (RESET: 3+5+29DCLKS)
0 0 0	B3 A[3:0] A[7:4]	1 * A ₇	0 * A ₆	1 * A ₅	1 * A ₄	0 A ₃	0 A ₂	1 A ₁	1 A ₀	Set Display Clock Divide Ratio / Oscillator Frequency	The lower nibble (A[3:0]) of the next command defines the divide ratio (D) of display clock (DCLK) Divide ratio (D)=A[3:0]+1 (A[3:0]RESET is 0001b, i.e. divide ratio (D) = 2)

Fundamental Command Table											
D/C	Hex	D7	D6	D5	D4	D3	D2	D1	D0	Command	Description
											The higher nibble (A[7:4]) of the next command sets the Oscillator Frequency Oscillator Frequency increases with the value of A[7:4] and vice versa Range: 0000b~1111b RESET= 0100b represents 655KHz, typical step value: 5% of previous value
0 0	B4 A[2:0]	1 *	0 *	1 *	1 *	0 *	1 A ₂	0 A ₁	0 A ₀	Set Pre-charge Compensation Level	A[2:0] = 0 (RESET) A[2:0] = 3h, Recommended level
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	B8 A[2:0] B[2:0] B[6:4] C[2:0] C[6:4] D[2:0] D[6:4] E[2:0] E[6:4] F[2:0] F[6:4] G[2:0] G[6:4] H[2:0] H[6:4]	1 * * * * * * * * * * * * * * * * * * *	0 * * B ₆ * C ₆ * D ₆ * E ₆ * F ₆ * G ₆ * H ₆	1 * * B ₅ * C ₅ * D ₅ * E ₅ * F ₅ * G ₅ * H ₅	1 * * B ₄ * C ₄ * D ₄ * E ₄ * F ₄ * G ₄ * H ₄	1 * * * * * * * * * * * * * * * * * * *	0 A ₂ B ₂ * C ₂ * D ₂ * E ₂ * F ₂ * G ₂ * H ₂	0 A ₁ B ₁ * C ₁ * D ₁ * E ₁ * F ₁ * G ₁ * H ₁	0 A ₀ B ₀ * C ₀ * D ₀ * E ₀ * F ₀ * G ₀ * H ₀	Set Gray Scale Table	The next eight bytes of command set the gray scale level of GS1-15 as below: A[2:0] = Gray scale level of GS1, RESET=1 B[2:0] = Gray scale level of GS2, RESET=1 B[6:4] = Gray scale level of GS3, RESET=1 C[2:0] = Gray scale level of GS4, RESET=1 C[6:4] = Gray scale level of GS5, RESET=1 D[2:0] = Gray scale level of GS6, RESET=1 D[6:4] = Gray scale level of GS7, RESET=1 E[2:0] = Gray scale level of GS8, RESET=1 E[6:4] = Gray scale level of GS9, RESET=1 F[2:0] = Gray scale level of GS10, RESET=1 F[6:4] = Gray scale level of GS11, RESET=1 G[2:0] = Gray scale level of GS12, RESET=1 G[6:4] = Gray scale level of GS13, RESET=1 H[2:0] = Gray scale level of GS14, RESET=1 H[6:4] = Gray scale level of GS15, RESET=1
0 0	BC A[7:0]	1 A ₇	0 A ₆	1 A ₅	1 A ₄	1 A ₃	1 A ₂	0 A ₁	0 A ₀	Set Precharge Voltage	Second command A[7:0] sets the precharge voltage level, A[7:0] 1xxxxxxx connects to V _{COMH} (RESET) 001xxxxx 1.0 * V _{REF} 00000000 0.51* V _{REF} 00000001 0.52* V _{REF} 00011111 0.84* V _{REF}
0 0	BE A[4 :0]	1 *	0 *	1 0	1 A ₄	1 A ₃	1 A ₂	1 A ₁	0 A ₀	Set V _{COMH} Voltage	Second command A[4:0] sets the V _{COMH} voltage level , A[4:0] 00000 0.51*V _{REF} 00001 0.52* V _{REF} 11101 0.81* V _{REF} (RESET) 11110 0.82* V _{REF} 11111 0.84* V _{REF}
0 0	BF A[3:0]	1 *	0 *	1 *	1 *	1 A ₃	1 A ₂	1 A ₁	1 A ₀	Set Segment Low Voltage (VSL)	Second command A[3:0] sets the VSL voltage as follow: A[3:0] = 0010 kept VSL pin NC A[3:0] = 1110 (RESET) connect a capacitor between VSL pin and V _{SS}
0	E3	1	1	1	0	0	0	1	1	NOP	Command for No Operation

Table 19: Graphic acceleration command

Set (GAC) (D/C# = 0, R/W#(WR#)= 0, E(RD#) = 1) unless specific setting is stated

Graphic acceleration command										Command	Description
D/C#	Hex	D7	D6	D5	D4	D3	D2	D2	D0		
0 0	23 A[4:0]	0 *	0 *	1 *	0 A ₄	0 *	0 *	1 A ₁	1 A ₀	Graphic Acceleration Command Options	A[0] = 0b: Disable Fill rectangle A[0] = 1b: Enable Fill rectangle (RESET) A[1] = 0b: Disable x-wrap(RESET) A[1] = 1b: Enable wrap around in x-direction during copying and scrolling A[4] = 0b: Disable reverse copy (RESET) A[4] = 1b: Enable reverse during copying.
0 0 0 0 0 0	24 A[5:0] B[6:0] C[5:0] D[6:0] E[7:0]	0 * * * * E ₇	0 * B ₆ * D ₆ E ₆	1 A ₅ B ₅ C ₅ D ₅ E ₅	0 A ₄ B ₄ C ₄ D ₄ E ₄	0 A ₃ B ₃ C ₃ D ₃ E ₃	1 A ₂ B ₂ C ₂ D ₂ E ₂	0 A ₁ B ₁ C ₁ D ₁ E ₁	0 A ₀ B ₀ C ₀ D ₀ E ₀	Draw Rectangle	A[5:0]: Column Address of Start B[6:0]: Row Address of Start C[5:0]: Column Address of End D[6:0]: Row Address of End E[7:0]: Set Gray scale pattern E[7:0] This byte is divided into two nibbles. The most significant 4 bits represent the gray scale level of the left pixel of each group. The least significant 4 bits represent the gray scale level of the right pixel of each group. Please refer to Figure 33 for the gray scale pattern setting examples. Note: (¹) 0 ≤ A < C ≤ 63 (²) 0 ≤ B < D ≤ 79
0 0 0 0 0 0	25 A[5:0] B[6:0] C[5:0] D[6:0] E[5:0] F[6:0]	0 * * * * *	0 * B ₆ * D ₆ * F ₆	1 A ₅ B ₅ C ₅ D ₅ E ₅ F ₅	0 A ₄ B ₄ C ₄ D ₄ E ₄ F ₄	0 A ₃ B ₃ C ₃ D ₃ E ₃ F ₃	1 A ₂ B ₂ C ₂ D ₂ E ₂ F ₂	0 A ₁ B ₁ C ₁ D ₁ E ₁ F ₁	1 A ₀ B ₀ C ₀ D ₀ E ₀ F ₀	Copy	A[5:0]: Column Address of Start B[6:0]: Row Address of Start C[5:0]: Column Address of End D[6:0]: Row Address of End E[5:0]: Column Address of New Start F[6:0]: Row Address of New Start Note: (¹) 0 ≤ A < C ≤ 63 (²) 0 ≤ B < D ≤ 79 (³) 0 ≤ E ≤ 63 (⁴) 0 ≤ F ≤ 79

Graphic acceleration command											
D/C#	Hex	D7	D6	D5	D4	D3	D2	D2	D0	Command	Description
0	26	0	0	1	0	0	1	1	0	Horizontal Scroll	A[5:0]: 1~63 horizontal offset in number of 2~127 column 0 no horizontal scroll
0	A[5:0]	*	*	A ₅	A ₄	A ₃	A ₂	A ₁	A ₀		B[6:0]: 2~80 number of rows to be H-scrolled
0	B[6:0]	*	B ₆	B ₅	B ₄	B ₃	B ₂	B ₁	B ₀		C[1:0]: scrolling time interval
0	C[1:0]	*	*	*	*	*	*	C ₁	C ₀		00b 12 frames 01b 64 frames 10b 128 frames 11b 256 frames
											Note: (1) Scrolling operates during display ON. (2) The parameters should not be changed after scrolling is activated
0	2E	0	0	1	0	1	1	1	0	Stop Moving	This command deactivates the scrolling action. Note (1) After sending 2Eh command to deactivate the scrolling action, the ram data needs to be rewritten.
0	2F	0	0	1	0	1	1	1	1	Start Moving	This command activates the scrolling function according to the setting done by Horizontal Scroll command 26h. Note (1) The “wrap around in x-direction” function must be enabled before scrolling start. i.e. Bit A{1} of command 23h must be set to 1b before issuing 2F command.

Table 20: Read Command Table

(D/C#=0, R/W# (WR#)=1, E (RD#)=1 for 6800 or E (RD#)=0 for 8080)

D ₇ D ₆ D ₅ D ₄ D ₃ D ₂ D ₁ D ₀	Status Register Read	D7 = 0:reserved D7 = 1:reserved D6 = 0:indicates the display is ON D6 = 1:indicated the display is OFF D5 = 0:reserved D5 = 1:reserved D4 = 0:reserved D4 = 1:reserved
--	----------------------	---

Note

(1) Patterns other than that given in Command Table are prohibited to enter to the chip as a command; Otherwise, unexpected result will occur

9.1 Data Read / Write

To read data from the GDDRAM, input HIGH to R/W# (WR#) pin and D/C# pin for 6800-series parallel mode, LOW to E (RD#) pin and HIGH to D/C# pin for 8080-series parallel mode.

In horizontal address increment mode, GDDRAM column address pointer will be increased by one automatically after each data read. In vertical address increment mode, GDDRAM row address pointer will be increased by one automatically after each data read.

Also, a dummy read is required before the first data read. See Figure 5 and Figure 8 in Functional Description.

To write data to the GDDRAM, input LOW to R/W#(WR#) pin and HIGH to D/C# pin for 6800-series parallel mode and 8080-series parallel mode. For serial interface mode, it is always in write mode. In horizontal address increment mode, GDDRAM column address pointer will be increased by one automatically after each data write. In vertical address increment mode, GDDRAM row address pointer will be increased by one automatically after each data write.

It should be noted that, in horizontal address increment mode, the row address pointer would be increased by one automatically if the column address pointer wraps around. In vertical address increment mode, the column address pointer will be increased by one automatically if the row address pointer wraps around.

Table 21: Address Increment Table (Automatic)

D/C#	R/W# (WR#)	Comment	Address Increment
0	0	Write Command	No
0	1	Read Status	No
1	0	Write Data	Yes
1	1	Read Data	Yes

10 COMMAND DESCRIPTIONS

10.1 Fundamental command description

10.1.1 Set Column Address (15h)

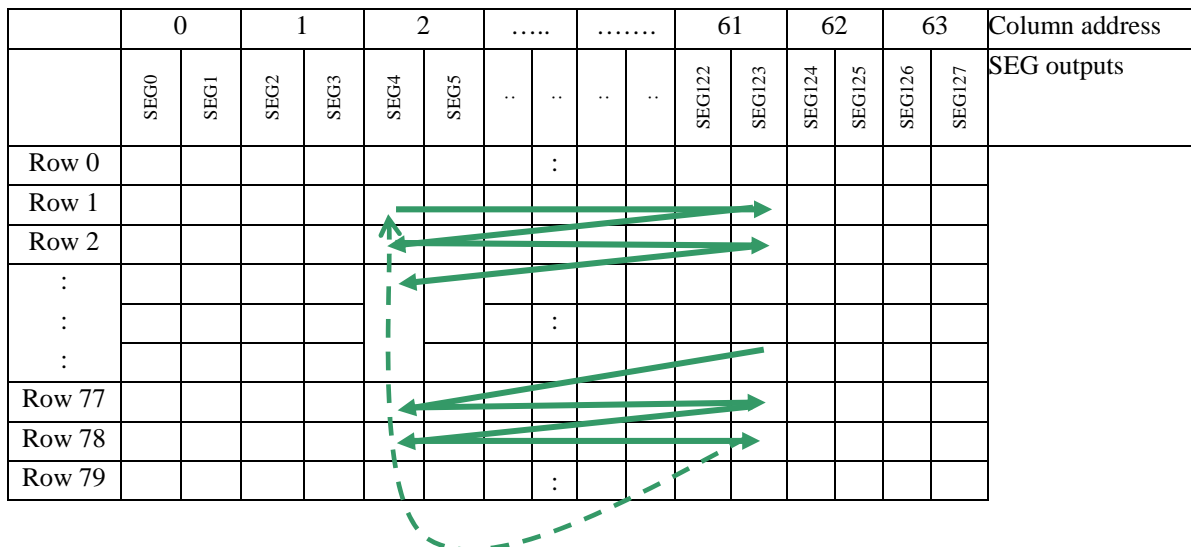
This triple byte command specifies column start address and end address of the display data RAM. This command also sets the column address pointer to column start address. This pointer is used to define the current read/write column address in graphic display data RAM. If horizontal address increment mode is enabled by command A0h, after finishing read/write one column data, it is incremented automatically to the next column address. Whenever the column address pointer finishes accessing the end column address, it is reset back to start column address and the row address is incremented to the next row.

10.1.2 Set Row Address (75h)

This triple byte command specifies row start address and end address of the display data RAM. This command also sets the row address pointer to row start address. This pointer is used to define the current read/write row address in graphic display data RAM. If vertical address increment mode is enabled by command A0h, after finishing read/write one row data, it is incremented automatically to the next row address. Whenever the row address pointer finishes accessing the end row address, it is reset back to start row address.

The diagram below shows the way of column and row address pointer movement through the example: column start address is set to 2 and column end address is set to 61, row start address is set to 1 and row end address is set to 78; horizontal address increment mode is enabled by command A0h. In this case, the graphic display data RAM column accessible range is from column 2 to column 61 and from row 1 to row 78 only. In addition, the column address pointer is set to 2 and row address pointer is set to 1. After finishing read/write one pixel of data, the column address is increased automatically by 1 to access the next RAM location for next read/write operation (*solid line in Figure 18*). Whenever the column address pointer finishes accessing the end column 61, it is reset back to column 2 and row address is automatically increased by 1 (*solid line in Figure 18*). While the end row 78 and end column 61 RAM location is accessed, the row address is reset back to 1 and the column address is reset back to 2 (*dotted line in Figure 18*).

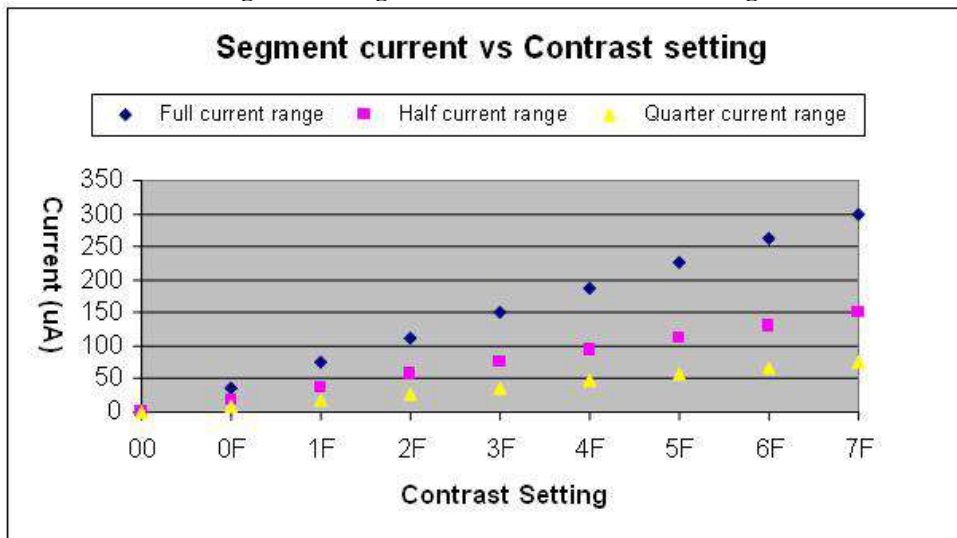
Figure 18 : Example of Column and Row Address Pointer Movement



10.1.3 Set Contrast Current (81h)

This command is to set Contrast Setting of the display. The chip has 128 contrast steps from 00H to 7FH. The segment output current increases with the increase of contrast step. See Figure 19 below.

Figure 19 : Segment current vs Contrast setting



10.1.4 Set Current Range (84h, 85h, 87h)

This command is used to select quarter range or half range or full range current mode. With the same contrast level, quarter range mode will give a quarter of the current output of the full range mode. Similar to half range current mode, it will give a half of the current output of the full range mode. See Figure 19. In RESET, quarter range current mode is default.

10.1.5 Set Re-map (A0h)

This double command has multiple configurations and each bit setting is described as follows:

- Column Address Remapping (A[0])
This bit is made for increase the flexibility layout of segment signals in OLED module with segment arranged from left to right (when A[0] is set to 0) or from right to left (when A[0] is set to 1).
- Nibble Remapping (A[1])
When A[1] is set to 1, the two nibbles of the data bus for RAM access are re-mapped, such that (D7, D6, D5, D4, D3, D2, D1, D0) acts like (D3, D2, D1, D0, D7, D6, D5, D4).
If this feature works together with Column Address Re-map, it would produce an effect of flipping the outputs from SEG0~127 to SEG127~SEG0 as show in Table 13.
- Address increment mode (A[2])
When A[2] is set to 0, the driver is set as horizontal address increment mode. After the display RAM is read / written, the column address pointer is increased automatically by 1. If the column address pointer reaches column end address, the column address pointer is reset to column start address and row address pointer is increased by 1. The sequence of movement of the row and column address point for horizontal address increment mode is shown in Figure 20

Figure 20 : Address Pointer Movement of Horizontal Address Increment Mode

	0	1	62	63	Column address
Row 0						
Row 1						
:	:	:	:	:	:	
Row 78						
Row 79						

When A[2] is set to 1, the driver is set to vertical address increment mode. After the display RAM is read / written, the row address pointer is increased automatically by 1. If the row address pointer reaches the row end address, the row address pointer is reset to row start address and column address pointer is increased by 1. The sequence of movement of the row and column address point for vertical address increment mode is shown in Figure 21.

Figure 21: Address Pointer Movement of Vertical Address Increment Mode

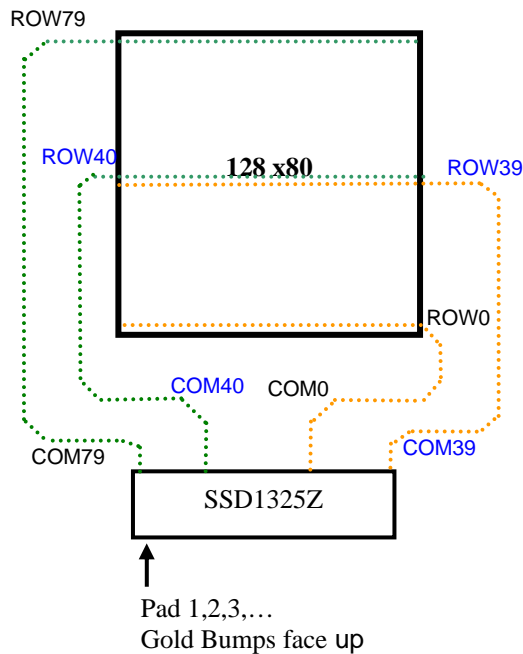
	0	1	62	63	Column address
Row 0						
Row 1						
:			:			
Row 126						
Row 127						

- COM Remapping (A[4])
This bit defines the scanning direction of the common for flexible layout of common signals in OLED module either from up to down (when A[4] is set to 0) or from bottom to up (when A[4] is set to 1). Table 14 shows an example of the using the COM Remapping to perform vertical scrolling.

- Splitting of Odd / Even COM Signals (A[6])
This bit is made to match the COM layout connection on the panel.

When A[6] is set to 0, no splitting odd / even of the COM signal is performed, output pin assignment sequence is shown as below (for 80MUX ratio):

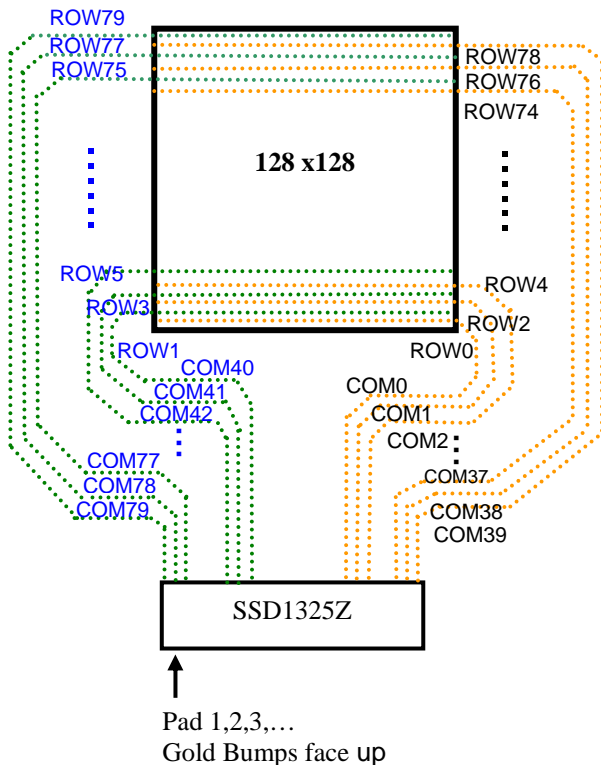
Figure 22: Output pin assignment when command A0h bit A[6]=0.



Output Pin Connection	
SSD1325Z	Panel
COM0	ROW0
COM1	ROW1
COM2	ROW2
COM3	ROW3
:	:
COM39	ROW39
COM40	ROW40
:	:
COM77	ROW77
COM78	ROW78
COM79	ROW79

When A[6] is set to 1, splitting odd / even of the COM signal is performed, output pin assignment sequence is shown as below (for 128MUX ratio):

Figure 23 : Output pin assignment when command A0h bit A[6]=1.







Output Pin Connection	
SSD1325Z	Panel
COM0	ROW0 (Even)
COM1	ROW2
COM2	ROW4
:	:
COM37	ROW74
COM38	ROW76
COM39	ROW78
COM40	ROW1 (Odd)
COM41	ROW3
COM42	ROW5
:	:
COM77	ROW75
COM78	ROW77
COM79	ROW79

10.1.6 Set Display Start Line (A1h)

This double byte command is to set Display Start Line register for determining the starting address of display RAM to be displayed by selecting a value from 0 to 79. Figure 24 shows an example using this command of this command when MUX ratio= 80 and MUX ratio= 54 and Display Start Line = 28. In there, “ROW” means the graphic display data RAM row.





Figure 24: Example of Set Display Start Line with no Remapping

	MUX ratio (A8h) = 80	MUX ratio (A8h) = 80	MUX ratio (A8h) = 54	MUX ratio (A8h) = 54
COM Pin	Display Start Line (A1h) = 0	Display Start Line (A1h) = 28	Display Start Line (A1h) = 0	Display Start Line (A1h) = 28
COM0	ROW0	ROW28	ROW0	ROW28
COM1	ROW1	ROW29	ROW1	ROW29
COM2	ROW2	ROW30	ROW2	ROW30
COM3	ROW3	ROW31	ROW3	ROW31
:	:	:	:	:
:	:	:	:	:
COM23	ROW23	ROW51	ROW23	ROW51
COM24	ROW24	ROW52	ROW24	ROW52
COM25	ROW25	ROW53	ROW25	ROW53
COM26	ROW26	ROW54	ROW26	ROW54
:	:	:	:	:
:	:	:	:	:
COM49	ROW50	ROW77	ROW50	ROW77
COM51	ROW51	ROW78	ROW51	ROW78
COM52	ROW52	ROW79	ROW52	ROW79
COM53	ROW53	ROW0	ROW53	ROW0
COM54	ROW54	ROW1	-	-
COM55	ROW55	ROW2	-	-
:	:	:	:	:
:	:	:	:	:
COM76	ROW76	ROW24	-	-
COM77	ROW77	ROW25	-	-
COM78	ROW78	ROW26	-	-
COM79	ROW79	ROW27	-	-
Display Example				

10.1.7 Set Display Offset (A2h)

This double byte command specifies the mapping of display start line (it is assumed that COM0 is the display start line, display start line register equals to 0) to one of COM0~COM79. Figure 25 shows an example using this command when MUX ratio= 80 and MUX ratio= 54 and Display Offset = 28. In there, “Row” means the graphic display data RAM row.

Figure 25: Example of Set Display Offset with no Remapping

	MUX ratio (A8h) = 80	MUX ratio (A8h) = 80	MUX ratio (A8h) = 64	MUX ratio (A8h) = 64
COM Pin	Display Offset (A2h)=0	Display Offset (A2h)=18	Display Offset (A2h)=0	Display Offset (A2h)=18
COM0	ROW0	ROW28	ROW0	ROW28
COM1	ROW1	ROW29	ROW1	ROW29
COM2	ROW2	ROW30	ROW2	ROW30
COM3	ROW3	ROW31	ROW3	ROW31
:	:	:	:	:
:	:	:	:	:
COM23	ROW23	ROW51	ROW23	ROW51
COM24	ROW24	ROW52	ROW24	ROW52
COM25	ROW25	ROW53	ROW25	ROW53
COM26	ROW26	ROW54	ROW26	-
:	:	:	:	:
:	:	:	:	:
COM49	ROW50	ROW77	ROW50	-
COM51	ROW51	ROW78	ROW51	-
COM52	ROW52	ROW79	ROW52	-
COM53	ROW53	ROW0	ROW53	ROW0
COM54	ROW54	ROW1	-	ROW1
COM55	ROW55	ROW2	-	ROW2
:	:	:	:	:
:	:	:	:	:
COM76	ROW76	ROW24	-	ROW24
COM77	ROW77	ROW25	-	ROW25
COM78	ROW78	ROW26	-	ROW26
COM79	ROW79	ROW27	-	ROW27
Display Example				

10.1.8 Set Display Mode (A4h ~ A7h)

These are single byte commands (A4h ~ A7h) and are used to set display status to Normal Display, Entire Display ON, Entire Display OFF or Inverse Display, respectively.

- Normal Display (A4h)
Reset the “Entire Display ON, Entire Display OFF or Inverse Display” effects and turn the data to ON at the corresponding gray level. Figure 26 shows an example of Normal Display.

Figure 26: Example of Normal Display



- Set Entire Display ON (A5h)
Force the entire display to be at gray scale level GS15, regardless of the contents of the display data RAM, as shown on Figure 27.

Figure 27: Example of Entire Display ON



- Set Entire Display OFF (A6h)
Force the entire display to be at gray scale level GS0, regardless of the contents of the display data RAM, as shown on Figure 28.

Figure 28 : Example of Entire Display OFF



- Inverse Display (A7h)
The gray scale level of display data are swapped such that “GS0” <-> “GS15”, “GS1” <-> “GS14”, etc. Figure 29 shows an example of inverse display.

Figure 29: Example of Inverse Display



10.1.9 Set Multiplex Ratio (A8h)

This double byte command sets multiplex ratio (MUX ratio) from 16MUX to 80MUX. In RESET, multiplex ratio is 80MUX. Please refer to Figure 24 and Figure 25 for the example of setting different MUX ratio.

10.1.10 Set Master Configuration (ADh)

This command selects the external V_{CC} power supply. External V_{CC} power should be connected to the V_{CC} pin. A[0] bit must be set to 0b after RESET.

This command will be activated after issuing Set Display ON command (AFh)

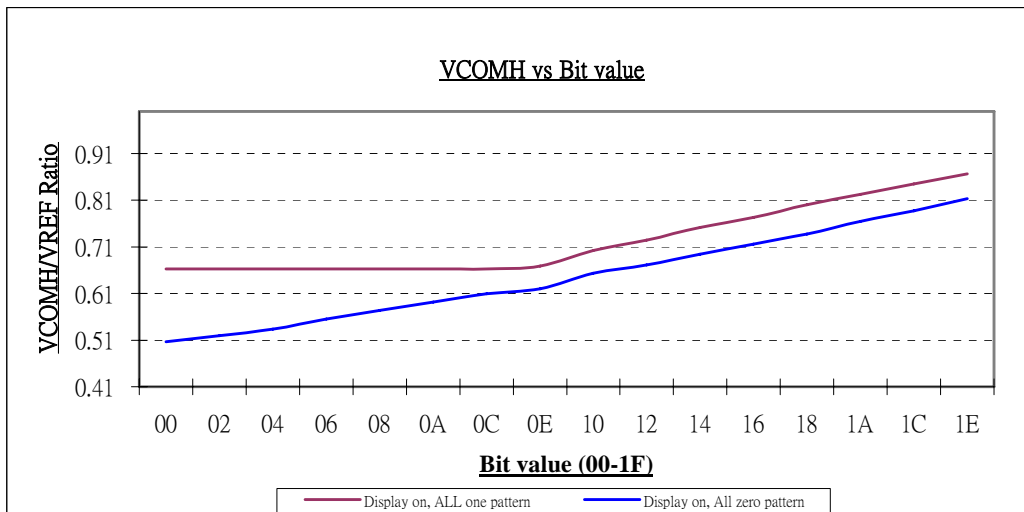
10.1.11 Set Display ON/OFF (AEh / AFh)

These single byte commands are used to turn the matrix display on the OLED panel display either ON or OFF. For AEh, the display is OFF, the segment and common output are in high impedance state and circuits will be turned OFF. When the sleep mode is set to OFF (AFh), the display is ON.

10.1.12 Set V_{COMH} Voltage (BEh)

This double byte command sets the high voltage level of common pins, V_{COMH}. The level of V_{COMH} is programmed with reference to V_{CC}. Please refer to Table 18 and Figure 30 for detail information and breakdown levels of each step.

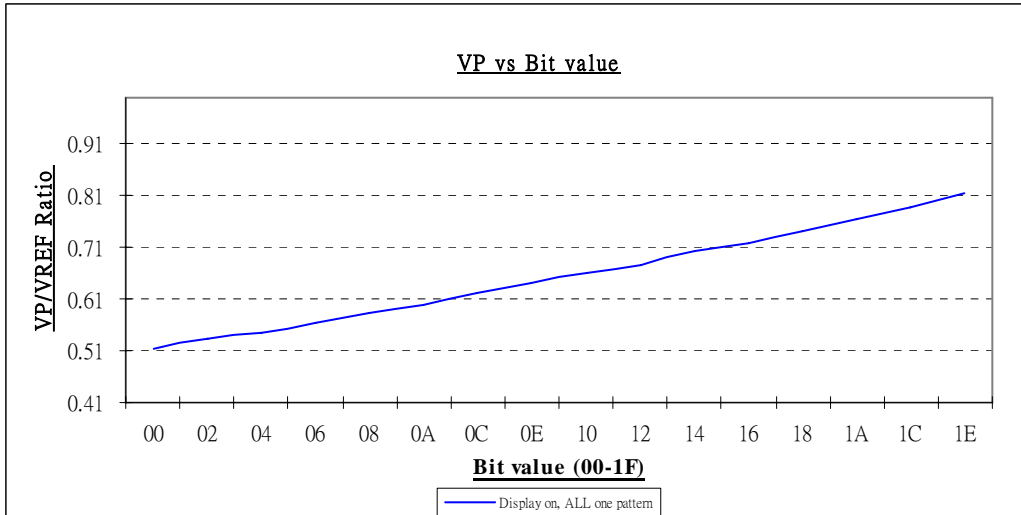
Figure 30 : V_{COMH} vs Bit value



10.1.13 Set Precharge Voltage (BCh)

This double byte command is used to set the pre-charge voltage (phase 2) level. Please refer to Table 18 and Figure 31 for detail information and breakdown levels of each step.

Figure 31 : V_P vs Bit value



10.1.14 Set Phase Length (B1h)

This is a double byte command. In the second byte of this double command, lower nibble and higher nibble is defined separately. The lower nibble adjusts the phase length of Reset (phase 1). The higher nibble is used to select the phase length of the pre-charge phase (phase 2). The phase length is ranged from 1 to 16 DCLK's. RESET for A[3:0] is set to 3h while reset for A[7:4] is set to 5h. Please refer to Table 18 for detail breakdown levels of each step.

10.1.15 Set Row Period (B2h)

This command is used to set the row period. It is defined by multiplying the internal display clock period by the number of internal display clocks per row (valued from 14h to 7Fh), and RESET is 25h. The larger the value, the more precise of each gray scale level can be tuned. See “Gray Scale Table” command (B8h) for details. Also, it is used to define the frame frequency altogether with the use of “Display Clock Divide Ratio” command (B3h). Row period equals to the sum of phase 1 and phase 2 periods and the pulse width of GS15. See equation in Table 18.

10.1.16 Set Display Clock Divide Ratio (B3h)

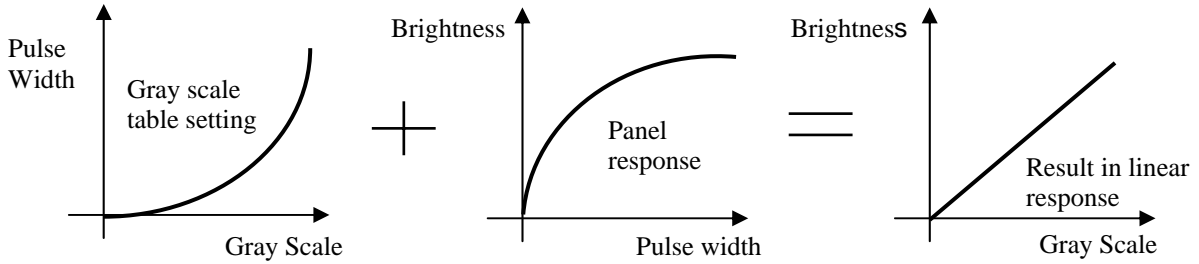
This double command is used to set the frequency of the internal display clocks, DCLK's. It is defined by dividing the oscillator frequency by the divide ratio (valued from 1 to 16). Frame frequency is determined by divide ratio, number of display clocks per row, MUX ratio and oscillator frequency. The lower nibble of the second byte is used to select the oscillator frequency. Please refer to Table 18 for detail breakdown levels of each step.

10.1.17 Set Gray Scale Table

This command is used to set each individual gray scale level for the display. Except gray scale level GS0 that has no pre-charge and current drive, the pulse width of each gray scale level is programmed with unit of DCLK. The longer the length of the pulse width, the brighter the OLED pixel when it is turned ON.

The setting of gray scale table entry can perform gamma correction on OLED panel display. Normally, it is desired that the brightness response of the panel is linearly proportional to the image data value in display data RAM. However, the OLED panel is somehow responded in non-linear way. Appropriate gray scale table setting like example below can compensate this effect.

Figure 32 : Example of gamma correction by gray scale table setting



As shown in Table16 and

Table 17, GS1 is defined with pulse width equals to the first offset value, L1, select from 0-7 internal display clocks. GS2 is defined with pulse width equals to GS1 plus the next offset value, L2, select from 1-8 internal display clocks. Similarly, the next GS level is defined with pulse width equals to its lower one GS level plus the next offset value, select from 1-8 internal display clocks. In normal operation, GS15 should take the full current drive period as its pulse width. Therefore, the row period should be set as the sum of phase 1 period, phase 2 periods, and the pulse width of GS15 with the use of “Row period” command.

10.1.18 NOP (E3h)

This is a no operation command.

10.1.19 Status register Read

This command is issued by setting D/C# LOW during a data read (refer to Figure 36 to Figure 38 parallel interface waveform). It allows the MCU to monitor the internal status of the chip.

10.2 Graphic Acceleration Command Set Description

10.2.1 Graphic Acceleration Command Options (23h)

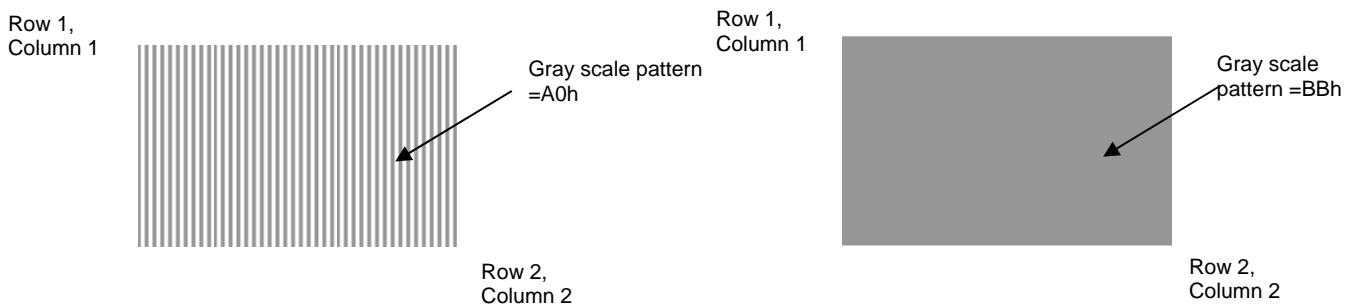
This command has two functions.

- Enable / Disable fill (A[0])
0 = Disable filling of rectangle in draw rectangle command.
1 = Enable filling of rectangle in draw rectangle command. (RESET)
- Enable / Disable x-warp (A[1])
0 = Disable wrap around in x-direction during copying and scrolling
1 = Enable wrap around in x-direction during copying and scrolling (RESET)
- Enable / Disable reverse copy (A[4])
0 = Disable reverse copy (RESET)
1 = During copy command, the new image colors are swapped such that “GS0” <-> “GS15”, “GS1” <-> “GS14”,

10.2.2 Draw Rectangle (24h)

Specify a starting point (Row 1, Column 1) and an ending point (Row 2, Column 2) as well as giving the desired gray scale pattern, a rectangle will then be drawn.

Figure 33 : Example of draw rectangle command



The following example illustrates the rectangle drawing command sequence.

1. Enter the “draw rectangle mode” by execute the command 24h
2. Set the starting column coordinates, Column 1. e.g., 01h.
3. Set the starting row coordinates, Row 1. e.g., 01h.
4. Set the finishing column coordinates, Column 9. e.g., 09h
5. Set the finishing row coordinates, Row 5. e.g., 05h
6. Set the gray scale pattern:

This byte is divided into two nibbles. The most significant 4 bits represent the gray scale level of the left pixel of each group. The least significant 4 bits represent the gray scale level of the right pixel of each group. Please refer to Figure 33 for the gray scale pattern setting examples.

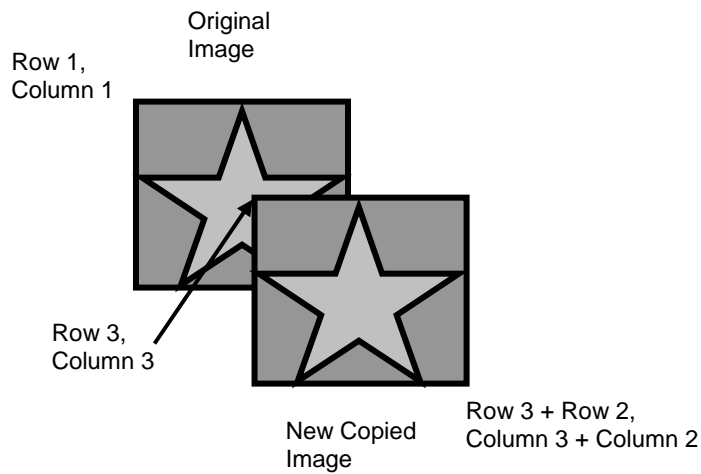
10.2.3 Copy (25h)

Copy the rectangular region defined by the starting point (Row 1, Column 1) and the ending point (Row 2, Column 2) to location (Row 3, Column 3). If the new coordinates are smaller than the ending points, the new image will overlap the original one.

The following example illustrates the copy procedure.

1. Enter the “copy mode” by execute the command 25h
2. Set the starting column coordinates, Column 1. E.g., 00h.
3. Set the starting row coordinates, Row 1. E.g., 00h.
4. Set the finishing column coordinates, Column 2. E.g., 05h
5. Set the finishing row coordinates, Row 2. E.g., 05h
6. Set the new column coordinates, Column 3. E.g., 03h
7. Set the new row coordinates, Row 3. E.g., 03h

Figure 34: Example of copy command





10.2.4 Horizontal Scroll (26h)

This command consists of 3 consecutive bytes to set up the scrolling parameters. It determined the horizontal scrolling offset, no of scrolling row and scrolling speed. Some scrolling examples are shown in Figure 35 .

Before issuing this command, the scrolling must be deactivated (2Eh). Otherwise, RAM content may be corrupted.

Figure 35: Scrolling examples

<div style="border: 1px solid black; padding: 2px; text-align: center; font-size: small;">Display before scrolling start</div> 	<div style="border: 1px solid black; padding: 2px; text-align: center; font-size: small;">Display snap shot after scrolling start</div>  <div style="font-size: x-small; margin-top: 5px;">No of scrolling rows</div>	<div style="border: 1px solid black; padding: 5px; font-size: small;"> <p style="text-align: center;">Example 1 : Partial screen horizontal scrolling with 1 column shift in every 64 frames</p> <p><u>Sample code</u></p> <pre style="font-family: monospace; font-size: x-small;"> 23h // Enable wrap around in x-direction 02h // during scrolling 26h // Horizontal scroll 01h // Horizontal scroll by 1 column 30h // Scrolling 48 rows 01h // Set time interval between each scroll step as 64 frames 2Fh // Activate scrolling </pre> </div>
--	--	--

10.2.5 Stop Moving (2Eh)

Stop motion of scrolling. After sending 2Eh command to deactivate the scrolling action, the ram data needs to be rewritten.

10.2.6 Start Moving (2Fh)

Start motion of scrolling. This command should only be issued after scrolling setup parameters are defined through command 26h and the function of wrap around in x-direction is enabled through 23h.

The following actions are prohibited after the horizontal scroll is activated

1. RAM access (Data write or read)
2. Changing scrolling setup parameters

11 MAXIMUM RATINGS

Table 22 : Maximum Ratings (Voltage Reference to V_{SS})

Symbol	Parameter	Value	Unit
V _{DD}	Supply Voltage	-0.3 to +4.0	V
V _{CC}		0 to +17.0	V
V _{REF}		0 to +17.0	V
V _{SEG}	SEG output voltage	0 to +V _{CC}	V
V _{COM}	COM output voltage	0 to +0.9xV _{CC}	
V _{in}	Input voltage	V _{SS} -0.3 to V _{DD} +0.3	V
T _A	Operating Temperature	-40 to +85	°C
T _{stg}	Storage Temperature Range	-65 to +150	°C

Maximum Ratings are those values beyond which damage to the device may occur. Functional operation should be restricted to the limits in the Electrical Characteristics tables or Pin Description.

This device may be light sensitive. Caution should be taken to avoid exposure of this device to any light source during normal operation. This device is not radiation protected.

12 DC CHARACTERISTICS

Conditions (unless specified):

Voltage referenced to V_{SS} ;

$V_{DD} = 2.7$, $V_{CC} = 12.0V$, $I_{REF} = 10\mu A$, at $T_A = 25^\circ C$.

Table 23 : DC Characteristics

Symbol	Parameter	Test Condition	Min	Typ	Max	Unit
V_{CC}	Operating Voltage	-	8.0	12.0	16.0	V
V_{DD}	Logic Supply Voltage	-	2.4	2.7	3.5	V
V_{OH}	HIGH Logic Output Level	$I_{OUT} = 100\mu A$, 3.3MHz	$0.9 * V_{DD}$	-	V_{DD}	V
V_{OL}	LOW Logic Output Level	$I_{OUT} = 100\mu A$, 3.3MHz	0	-	$0.1 * V_{DD}$	V
V_{IH}	HIGH Logic Input Level	-	$0.8 * V_{DD}$	-	V_{DD}	V
V_{IL}	LOW Logic Input Level	-	0	-	$0.2 * V_{DD}$	V
I_{SLEEP}	Sleep mode Current	No loading	-	0.2	5	μA
I_{CC}	V_{CC} Supply Current $V_{DD} = 2.7V$, external $V_{CC} = 12V$, $I_{REF} = 10\mu A$, Frame rate=110Hz, All one pattern, Display ON, no loading	Contrast = 7F	-	700	-	μA
I_{DD}	V_{DD} Supply Current $V_{DD} = 2.7V$, external $V_{CC} = 12V$, $I_{REF} = 10\mu A$, Frame rate=110Hz, All one pattern, Display ON, no loading	Contrast = 7F	-	-	650	μA
I_{SEG}	Segment Output Current $V_{DD} = 2.7V$, $V_{CC} = 12V$, $I_{REF} = 10\mu A$, Frame rate=110Hz, Display ON, Segment pin under test is connected with a 20K resistive load to V_{SS}	Contrast = 7F	270	300	370	μA
		Contrast = 5F	-	225	-	
		Contrast = 3F	-	150	-	
		Contrast = 1F	-	75	-	
Dev	Segment output current uniformity $V_{DD} = 2.7V$, $V_{CC} = 12V$, $I_{REF} = 10\mu A$, Contrast=7F	Adjacent pin	-1.5	-	+1.5	%
		Overall pin to pin	-3	-	+3	

13 AC CHARACTERISTICS

Conditions (Unless otherwise specified):

Voltage referenced to V_{SS}

$V_{DD} = 2.4V$ to $3.5V$

$V_{CC} = 8.0V$ to $16.0V$

$T_A = 25^\circ C$

Table 24 : AC Characteristics

Symbol	Parameter	Test Condition	Min	Typ	Max	Unit
F_{OSC}	Oscillation Frequency of Display Timing Generator	$V_{DD} = 2.7V$	535	630	725	kHz
F_{FRM}	Frame Frequency for 128 MUX Mode	128x80 Graphic Display Mode, Display ON, Internal Oscillator Enabled	-	$F_{OSC} * 1/(D*K*80)$	-	Hz
RES#	Reset LOW pulse width	-	3	-	-	us
	Reset complete time	-	-	-	2	us

Note:

- (1) F_{OSC} stands for the frequency value of the internal oscillator and the value is measured when command B3h A[7:4] is in default value.
- (2) D stands for divide ratio
- (3) K stands for total number of display clocks per row defined by command B2h
- (4) N stands for number of MUX selected by command A8h

Conditions:

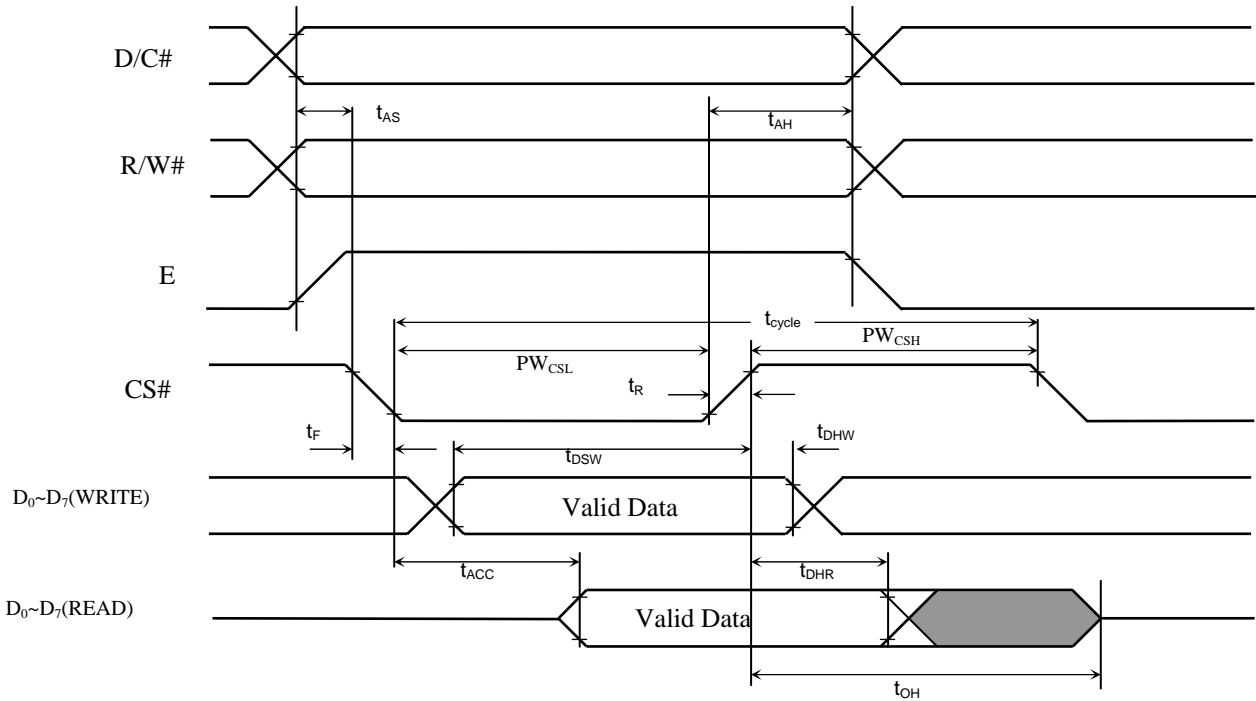
$V_{DD} - V_{SS} = 2.4 \text{ to } 3.5V$

$T_A = 25^\circ C$

Table 25 : 6800-Series MPU Parallel Interface Timing Characteristics

Symbol	Parameter	Min	Typ	Max	Unit
t_{cycle}	Clock Cycle Time	300	-	-	ns
t_{AS}	Address Setup Time	0	-	-	ns
t_{AH}	Address Hold Time	0	-	-	ns
t_{DSW}	Write Data Setup Time	40	-	-	ns
t_{DHW}	Write Data Hold Time	15	-	-	ns
t_{DHR}	Read Data Hold Time	20	-	-	ns
t_{OH}	Output Disable Time	-	-	70	ns
t_{ACC}	Access Time	-	-	140	ns
PW_{CSL}	Chip Select Low Pulse Width (read)	120	-	-	ns
	Chip Select Low Pulse Width (write)	60	-	-	ns
PW_{CSH}	Chip Select High Pulse Width (read)	60	-	-	ns
	Chip Select High Pulse Width (write)	60	-	-	ns
t_R	Rise Time	-	-	15	ns
t_F	Fall Time	-	-	15	ns

Figure 36 : 6800-series MPU Parallel Interface Characteristics



Conditions:

$V_{DD} - V_{SS} = 2.4$ to $3.5V$

$T_A = 25^{\circ}C$

Table 26 : 8080-Series MPU Parallel Interface Timing Characteristics

Symbol	Parameter	Min	Typ	Max	Unit
t_{cycle}	Clock Cycle Time	300	-	-	ns
t_{AS}	Address Setup Time	10	-	-	ns
t_{AH}	Address Hold Time	0	-	-	ns
t_{DSW}	Write Data Setup Time	40	-	-	ns
t_{DHW}	Write Data Hold Time	15	-	-	ns
t_{DHR}	Read Data Hold Time	20	-	-	ns
t_{OH}	Output Disable Time	-	-	70	ns
t_{ACC}	Access Time	-	-	140	ns
t_{PWLR}	Read Low Time	120	-	-	ns
t_{PWLW}	Write Low Time	60	-	-	ns
t_{PWHR}	Read High Time	60	-	-	ns
t_{PWHW}	Write High Time	60	-	-	ns
t_R	Rise Time	-	-	15	ns
t_F	Fall Time	-	-	15	ns
t_{CS}	Chip select setup time	0	-	-	ns
t_{CSH}	Chip select hold time to read signal	0	-	-	ns
t_{CSF}	Chip select hold time	20	-	-	ns

Figure 37 : 8080-series parallel interface characteristics (Form 1)

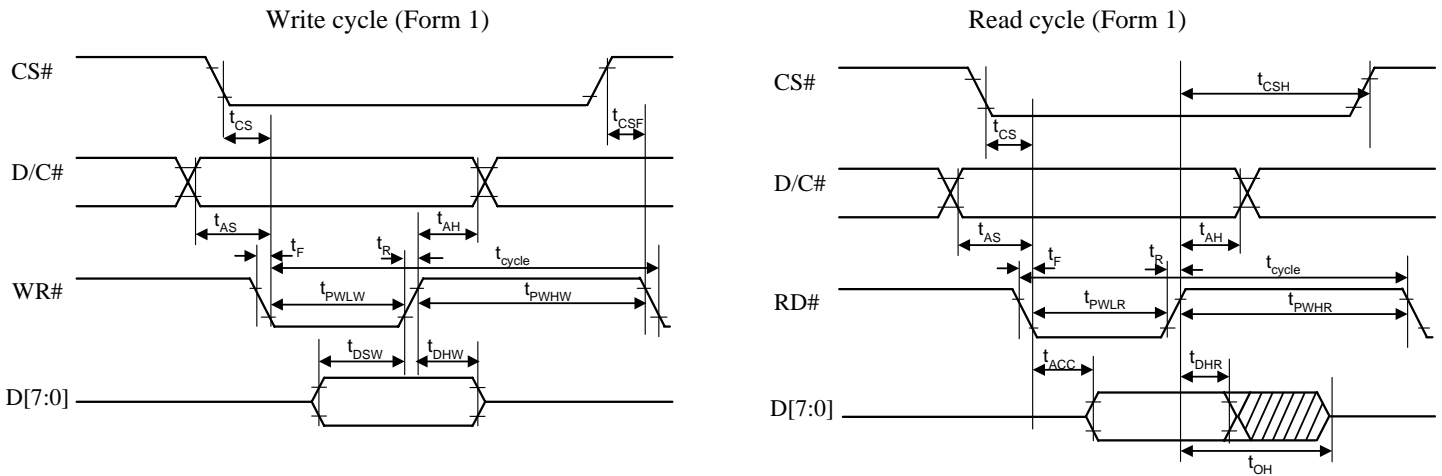
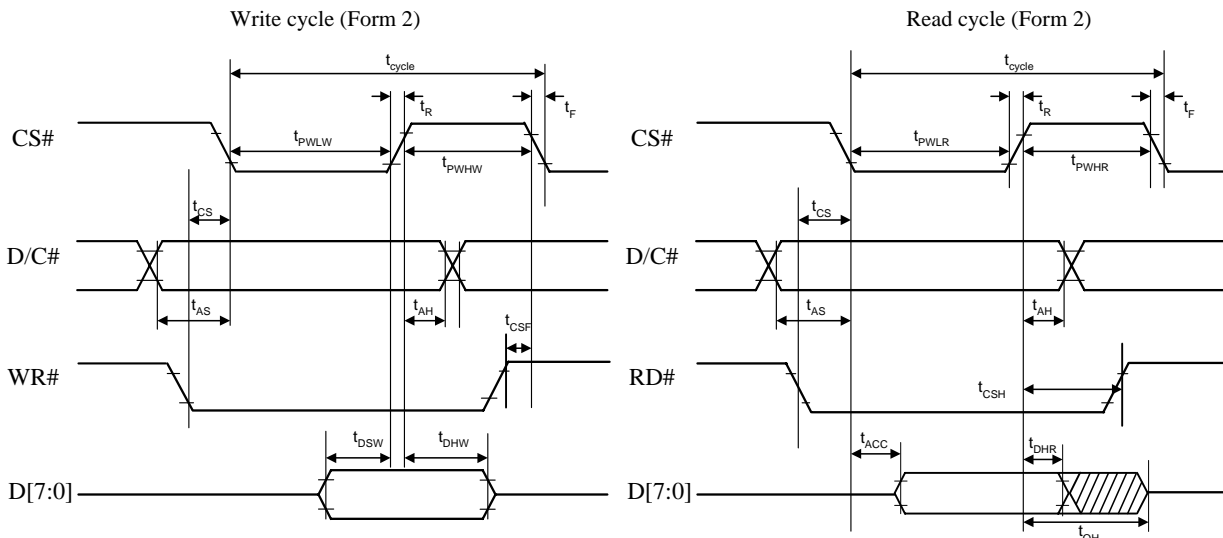


Figure 38 : 8080-series parallel interface characteristics (Form 2)



Conditions:

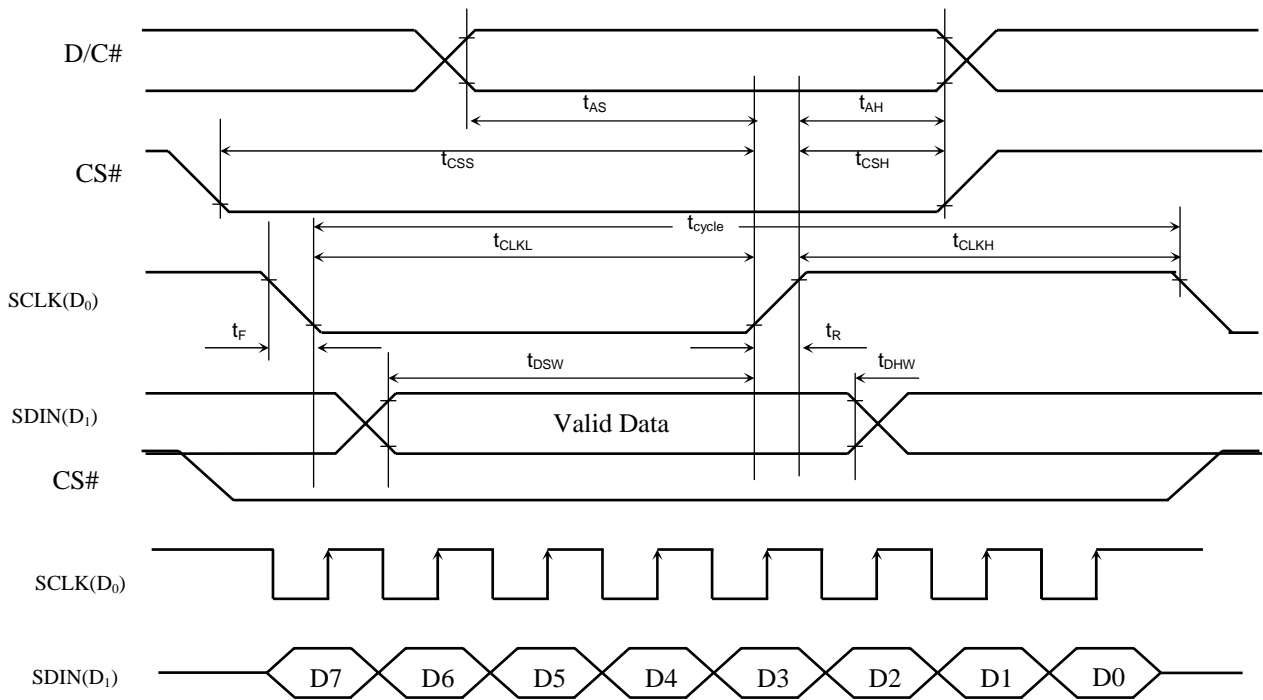
$V_{DD} - V_{SS} = 2.4 \text{ to } 3.5\text{V}$

$T_A = 25^\circ\text{C}$

Table 27 : Serial Interface Timing Characteristics

Symbol	Parameter	Min	Typ	Max	Unit
t_{cyc}	Clock Cycle Time	250	-	-	ns
t_{AS}	Address Setup Time	150	-	-	ns
t_{AH}	Address Hold Time	150	-	-	ns
t_{CSS}	Chip Select Setup Time	120	-	-	ns
t_{CSH}	Chip Select Hold Time	60	-	-	ns
t_{DSW}	Write Data Setup Time	100	-	-	ns
t_{DHW}	Write Data Hold Time	100	-	-	ns
t_{CLKL}	Clock Low Time	100	-	-	ns
t_{CLKH}	Clock High Time	100	-	-	ns
t_R	Rise Time	-	-	15	ns
t_F	Fall Time	-	-	15	ns

Figure 39 : Serial Interface Characteristics



14 APPLICATION EXAMPLES

Figure 40 : Application Example for SSD1325Z SPI serial interface mode

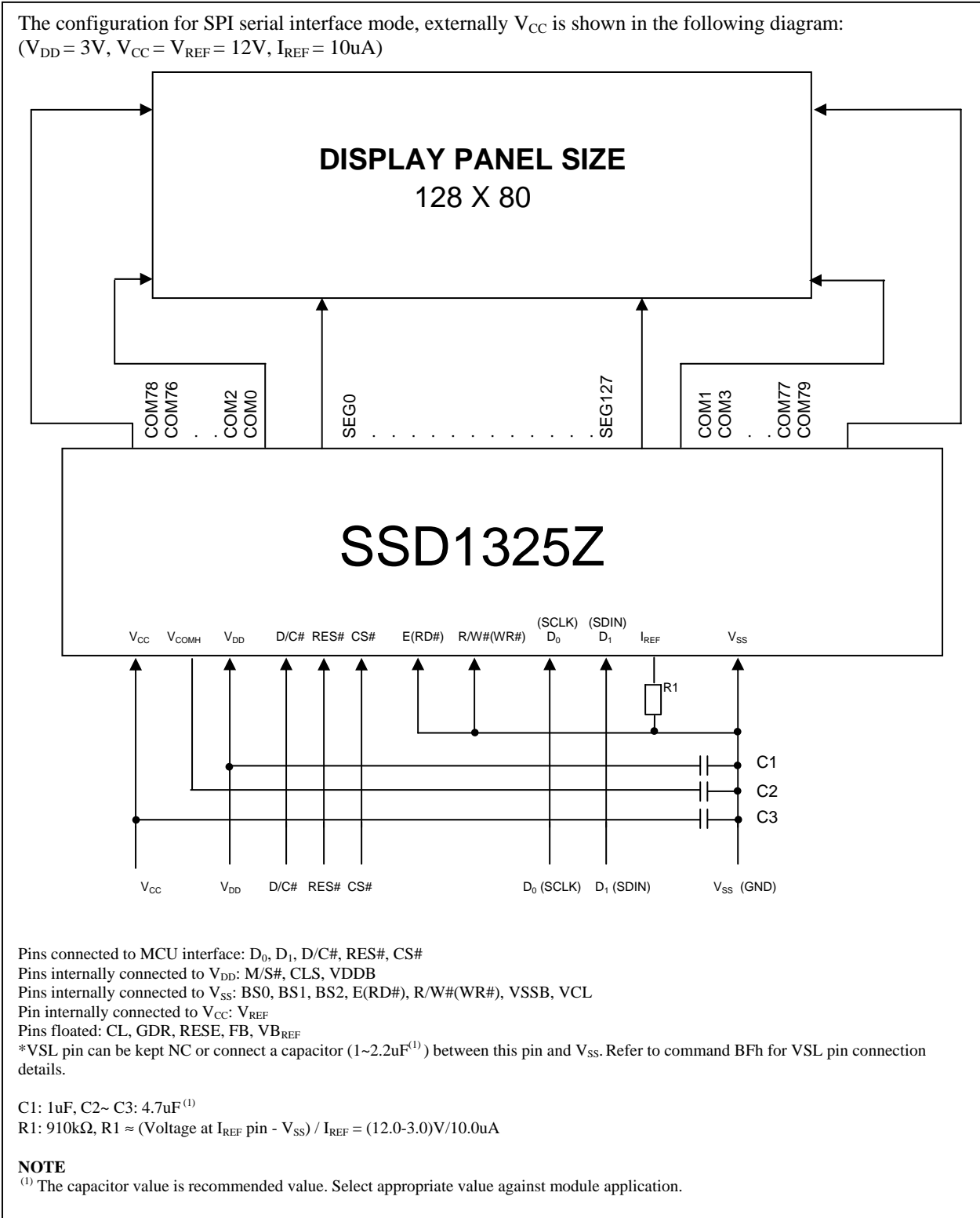
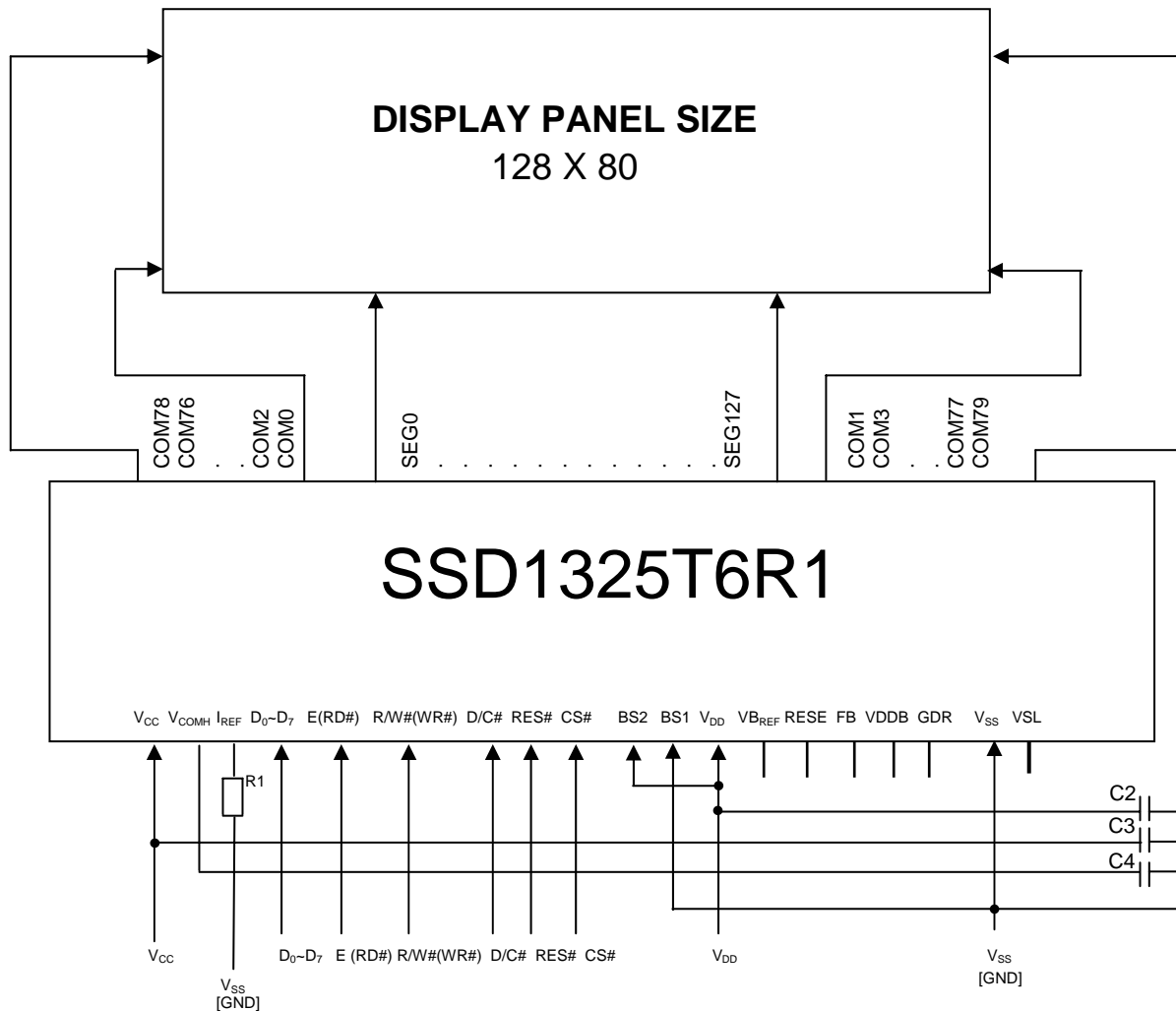


Figure 41: Application Example for SSD1325T6R1

The configuration for 6800-parallel interface mode, externally V_{CC} is shown in the following diagram:
 ($V_{DD} = 3V$, $V_{CC} = V_{REF} = 12V$, $I_{REF} = 10\mu A$)



Pins connected to MCU interface: $D_0 \sim D_7$, $E(RD\#)$, $R/W\#(WR\#)$, $D/C\#$, $CS\#$, $RES\#$

Pins internally connected to V_{DD} : $M/S\#$, CLS

Pins internally connected to V_{SS} : $BS0$, $VSSB$

Pin internally connected to V_{CC} : V_{REF}

Pins floated: GDR , $RESE$, FB , VB_{REF} , $VDDB$

* VSL pin can be kept NC or connect a capacitor ($1 \sim 2.2\mu F^{(1)}$) between this pin and V_{SS} . Refer to command BFh for VSL pin connection details.

$C2 \sim C4$: $4.7\mu F^{(1)}$

$R1$: $910k\Omega$, $R1 \approx (Voltage\ at\ I_{REF}\ pin - V_{SS}) / I_{REF} = (12.0 - 3.0)V / 10.0\mu A$

Note

⁽¹⁾ The capacitor value is recommended value. Select appropriate value against module application.

15 PACKAGE INFORMATION

15.1 SSD1325Z Die Tray Information

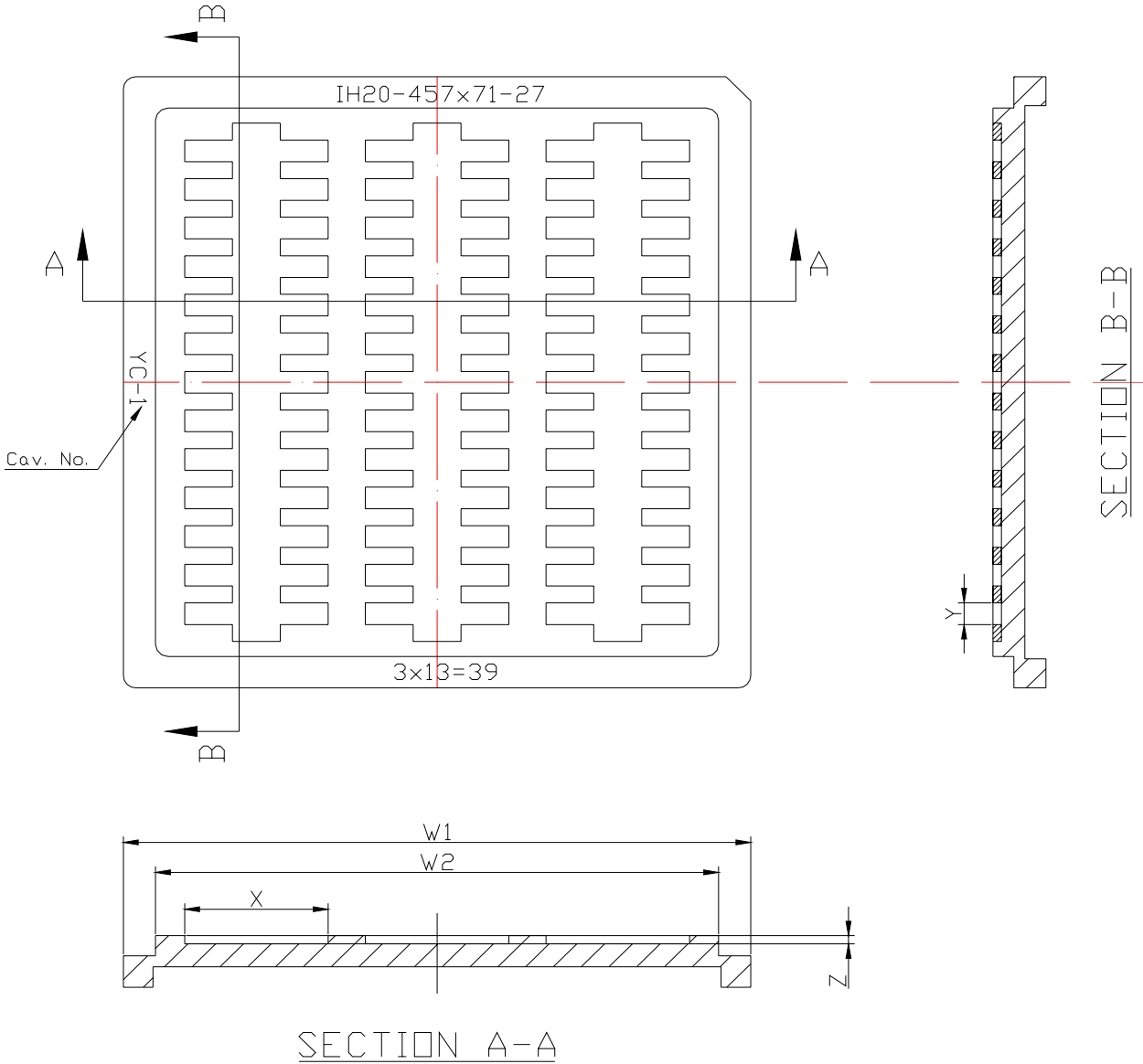


Figure 42 : SSD1325Z Die Tray Drawing

Table 28 : SSD1325Z Die Tray Dimensions

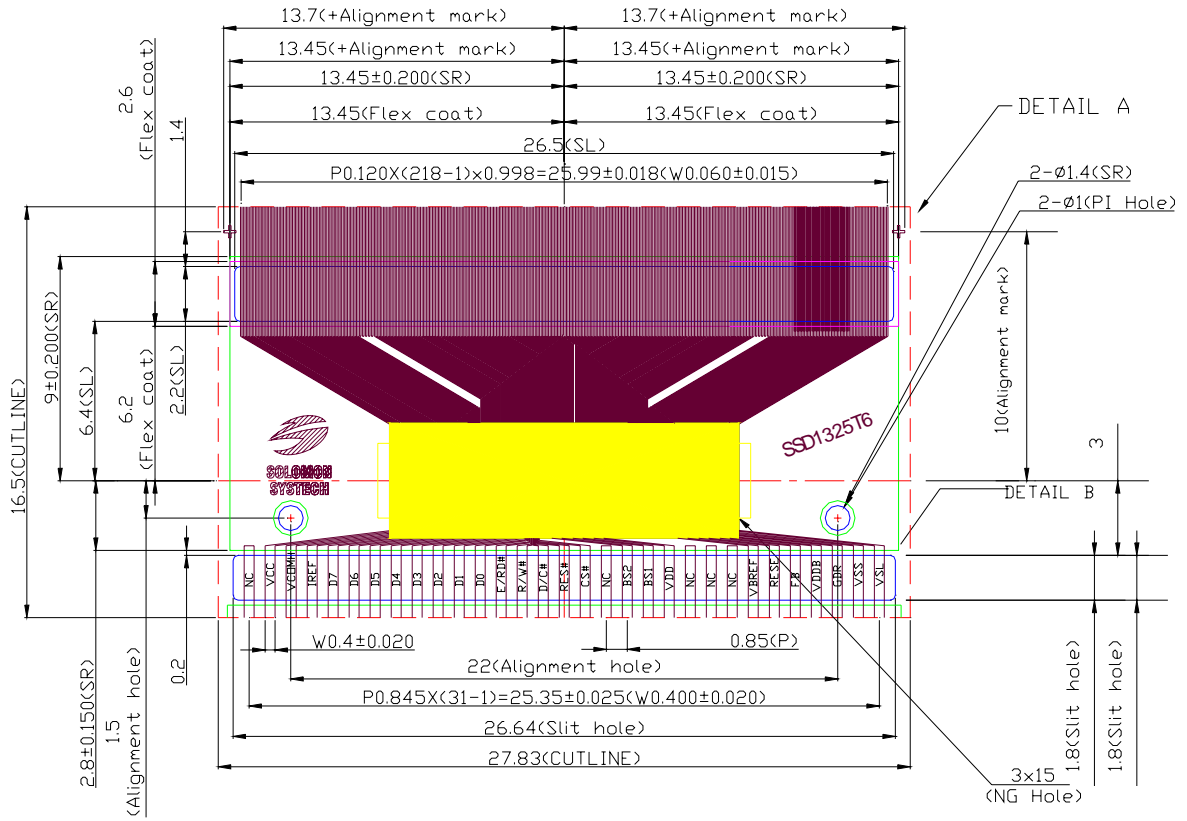
Parameter	Dimensions
W1	50.70±0.2 mm
W2	45.50±0.2 mm
X	11.60±0.1 mm
Y	1.80±0.1 mm
Z	0.71±0.05 mm
N (number of die)	39

Remark

1. Depth of text: Max. 0.1mm
2. Tray material: ABS
3. Tray color code: Black
4. Surface resistance $10^9 \sim 10^{11} \Omega$
5. Tray warpage: Max 0.10mm
6. Unspecifier dim's tolerance: $\pm 0.15\text{mm}$
7. Pocket size: 13.56 x 1.65 x 0.61mm

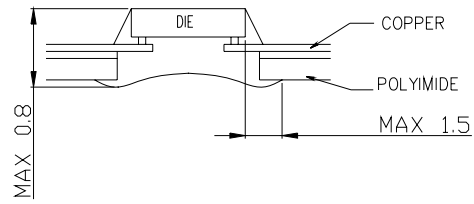
15.2 SSD1325T6R1 Detail Dimension

Figure 43 : SSD1325T6R1 Detail Dimension

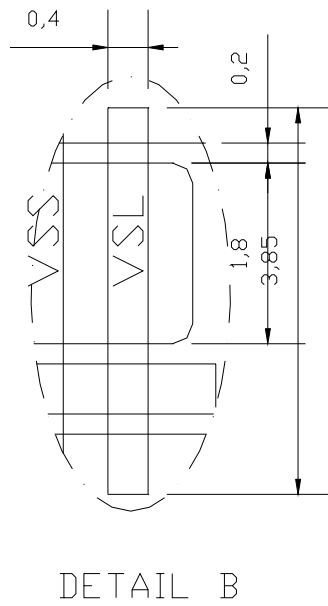
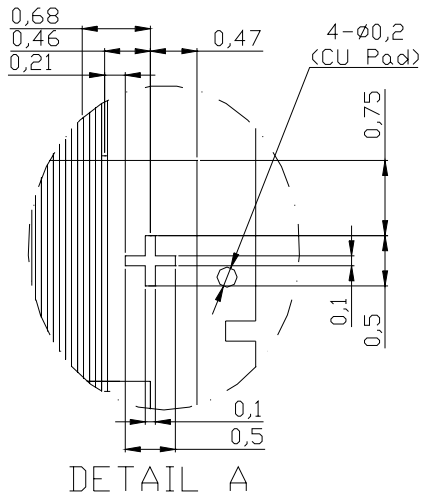


NOTE:


1. GENERAL TOLERANCE: $\pm 0.05\text{mm}$
2. CUTLINE TOLERANCE: $\pm 0.15\text{mm}$
3. MATERIAL
 - PI: $75\pm 6\mu\text{m}$
 - CU: $18\pm 5\mu\text{m}$
 - SR: $26\pm 14\mu\text{m}$
 - ADHESIVE: $12\pm 2\mu\text{m}$
4. FLEX COATING: $\text{Min}10\mu\text{m}$
5. SN PLATING: $0.20\pm 0.05\mu\text{m}$
6. TAP SITE: 4 SPH, 19.00mm



MIRROR DESIGN



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